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## SOME SYMMETRIC PROPERTIES OF KENMOTSU MANIFOLDS ADMITTING SEMI-SYMMETRIC METRIC CONNECTION

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Abstract. The objective of the present paper is to study some symmetric properties of the Kenmotsu manifold endowed with a semi-symmetric metric connection. Here we consider pseudo-symmetric, Ricci pseudo-symmetric, projective pseudo-symmetric and  $\phi$ -projective semi-symmetric Kenmotsu manifolds with respect to the semi-symmetric metric connection. Finally, we provide an example of the 3-dimensional Kenmotsu manifold admitting a semi-symmetric metric connection which verifies our result. **Keywords:** Kenmotsu manifold; projective curvature tensor; semi-symmetric metric connection;  $\eta$ -Einstein manifold.

### 1. Introduction

In 1932, Hayden [12] introduced the idea of metric connection with a torsion on a Riemannian manifold. By considering the torsion tensor of a linear connection, Friedmann and Schouten [11] gave a new connection called semi-symmetric connection. The torsion tensor with respect to the semi-symmetric connection  $\bar{\nabla}$  is given by

(1.1) 
$$\overline{T}(X,Y) = \overline{\nabla}_X Y - \overline{\nabla}_Y X - [X,Y].$$

The connection  $\overline{\nabla}$  is called a semi-symmetric metric connection [12] if  $\overline{\nabla}g = 0$ , otherwise, non-metric connection. A relation between the semi-symmetric metric connection  $\overline{\nabla}$  and the Levi-Civita connection  $\nabla$  on (M, g) established by Yano [18] is given by

(1.2) 
$$\overline{\nabla}_X Y = \nabla_X Y + \eta(Y) X - g(X, Y) \xi.$$

Semi-symmetric manifolds form a subclass of the class of pseudo-symmetric manifolds. The concept of pseudo-symmetric manifold was introduced by Chaki and

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Chaki [8] and Deszcz [10] in two different ways. Here we study the properties of pseudo-symmetric manifolds with a semi-symmetric metric connection in the Deszcz sense. An *n*-dimensional Riemannian manifold M is called pseudo-symmetric in the sense of Deszcz [10] if the Riemannian curvature tensor R satisfies the following relation

(1.3) 
$$(R(X,Y) \cdot R)(U,V)W = L_R((X \wedge_q Y) \cdot R)(U,V)W,$$

for all the vector fields  $X, Y, Z, U, V, W \in TM$ . Where  $L_R$  is a smooth function on M and  $X \wedge_q Y$  is an endomorphism defined by

(1.4) 
$$(X \wedge_g Y)Z = g(Y, Z)X - g(X, Z)Y.$$

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The notion of semi-symmetric metric connection has been weakened by many geometers such as [2, 3, 5, 9, 15, 17] etc., with different structures of manifolds and submanifolds. In particular, De [1] and Bagewadi et. al. [4] studied semisymmetric metric connection on Kenmotsu manifolds with a projective curvature tensor. Also in [16], Singh et. al. studied the semi-symmetric metric connection in an  $\epsilon$ -Kenmotsu manifold.

The projective curvature tensor  $\overline{P}$  with respect to the semi-symmetric metric connection on a Kenmotsu manifold is defined by [1]

(1.5) 
$$\bar{P}(X,Y)Z = \bar{R}(X,Y)Z - \frac{1}{n-1}[\bar{S}(Y,Z)X - \bar{S}(X,Y)Z],$$

for  $X, Y, Z \in \chi(M)$ . Here  $\overline{S}$  is the Ricci tensor with respect to the semi-symmetric metric connection.

Further, a relation between the curvature tensor  $\overline{R}$  of the semi-symmetric metric connection  $\overline{\nabla}$  and the curvature tensor R of the Levi-Civita connection  $\nabla$  is given by [18]

(1.6) 
$$\overline{R}(X,Y)Z = R(X,Y)Z - \alpha(Y,Z)X + \alpha(X,Z)Y - g(Y,Z)LX + g(X,Z)LY,$$

where  $\alpha$  is a tensor field of type (0,2) and L is a tensor field of type (1,1) which is given by

(1.7) 
$$\alpha(Y,Z) = g(LY,Z) = (\nabla_Y \eta)(Z) - \eta(Y)\eta(Z) + \frac{1}{2}\eta(\xi)g(Y,Z),$$

for any vector fields  $X, Y, Z \in \chi(M)$ . From (1.6), it follows that

(1.8) 
$$\bar{S}(Y,Z) = S(Y,Z) - (n-2)\alpha(Y,Z) - ag(Y,Z),$$

where  $\bar{S}$  denotes the Ricci tensor with respect to  $\bar{\nabla}$  and a=trace of  $\alpha$ .

Motivated by these studies, we investigate the semi-symmetric metric connection due to Yano [18] on Kenmotsu manifolds. The paper is organized as follows. After giving preliminaries and basic results of the Kenmotsu manifold in Section 2, in Section 3 we study pseudo-symmetric Kenmotsu manifolds with respect to the semi-symmetric metric connection, proving that either  $L_{\bar{R}} = -2$  or the manifold is  $\eta$ -Einstein. In the next section we prove that in a Ricci pseudo-symmetric Kenmotsu manifold with respect to the semi-symmetric metric connection, either  $L_{\bar{S}}=-2$  or the manifold is  $\eta\text{-Einstein}.$  Sections 5 and 6 are devoted to the study of projective pseudo-symmetric and  $\phi$ -projective semi-symmetric Kenmotsu manifolds with respect to the semi-symmetric metric connection. Finally, we construct an example of a 3-dimensional Kenmotsu manifold admitting the semi-symmetric metric connection and verify the results.

#### Preliminaries 2.

Let M be an n-dimensional almost contact Riemannian manifold equipped with the almost contact metric structure  $(\phi, \xi, \eta, g)$ , where  $\phi$  is a (1,1) tensor field,  $\xi$  is a characteristic vector field,  $\eta$  is a 1-form and g is the Riemannian metric satisfying the following conditions [7];

(2.1) 
$$\phi^2(X) = -X + \eta(X)\xi, \quad \eta(\xi) = 1, \quad \eta \circ \phi = 0, \quad \phi\xi = 0, \quad g(X,\xi) = \eta(X),$$
  
(2.2)  $g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y),$ 

for all vector fields X, Y on M. If an almost contact metric manifold satisfies

(2.3) 
$$(\nabla_X \phi)(Y) = g(\phi X, Y)\xi - \eta(Y)\phi X,$$

then M is called a Kenmotsu manifold [14]. Here  $\nabla$  denotes the operator of covariant differentiation with respect to g. From (2.3), it follows that

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(2.4) 
$$\nabla_X \xi = X - \eta(X)\xi,$$

(2.5) 
$$(\nabla_X \eta)(Y) = g(X, Y) - \eta(X)\eta(Y).$$

In a Kenmotsu manifold M, the following relations hold:

$$\begin{array}{ll} (2.6) & \eta(R(X,Y)Z) = [g(X,Z)\eta(Y) - g(Y,Z)\eta(X)], \\ (2.7) & (a) \; R(\xi,X)Y = [\eta(Y)X - g(X,Y)\xi], & (b) \; R(X,Y)\xi = [\eta(X)Y - \eta(Y)X], \\ (2.8) & (a) \; S(X,Y) = -(n-1)g(X,Y), & (b) \; QX = -(n-1)X, \\ (2.9) & (a) \; S(X,\xi) = -(n-1)\eta(X), & (b) \; S(\xi,\xi) = -(n-1), & (c) \; Q\xi = -(n-1)\xi, \\ (2.10) \; (\nabla_W R)(X,Y)\xi = g(W,X)Y - g(W,Y)X - R(X,Y)W, \\ (2.11) \; S(\phi X, \phi Y) = S(X,Y) + (n-1)\eta(X)\eta(Y). \end{array}$$

Now by using (1.7), (2.1) and (2.5) in (1.6), we have the following relation

$$\bar{R}(X,Y)Z = R(X,Y)Z - 3[g(Y,Z)X - g(X,Z)Y] + 2[\eta(Y)X) - \eta(X)Y]\eta(Z) + 2[g(Y,Z)\eta(X) - g(X,Z)\eta(Y)]\xi.$$
(2.12)

Contracting X in (2.12), we get

(2.2)

(2.13) 
$$\bar{S}(Y,Z) = S(Y,Z) - (3n-5)g(Y,Z) + 2(n-2)\eta(Y)\eta(Z).$$

Again contracting Y and Z in (2.13), we get

(2.14) 
$$\bar{r} = r - (n-1)(3n-4),$$

where  $\bar{r}$  and r are the scalar curvatures with respect to the semi-symmetric metric connection and the Levi-Civita connection respectively.

# 3. Pseudo-symmetric Kenmotsu manifold with respect to the semi-symmetric metric connection

Definition: An *n*-dimensional Kenmotsu manifold M is said to be pseudosymmetric with respect to semi-symmetric metric connection if the curvature tensor  $\overline{R}$  of  $\overline{\nabla}$  satisfies the condition

(3.1) 
$$(\bar{R}(X,Y)\cdot\bar{R})(U,V)W = L_{\bar{R}}((X\wedge_g Y)\cdot\bar{R})(U,V)W,$$

where  $L_{\bar{R}}$  is a function on M. From (3.1), we have

$$\begin{split} \bar{R}(X,Y)(\bar{R}(U,V)W) &- \bar{R}(\bar{R}(X,Y)U,V)W - \bar{R}(U,\bar{R}(X,Y)V)W \\ &- \bar{R}(U,V)(\bar{R}(X,Y)W) = L_{\bar{R}}[(X \wedge_g Y)(\bar{R}(U,V)W) - \bar{R}((X \wedge_g Y)U,V)W \\ (3.2) &- \bar{R}(U,(X \wedge_g Y)V)W - \bar{R}(U,V)(X \wedge_g Y)W]. \end{split}$$

Replacing X by  $\xi$  in (3.2), we get

$$\begin{aligned} \bar{R}(\xi,Y)(\bar{R}(U,V)W) &- \bar{R}(\bar{R}(\xi,Y)U,V)W - \bar{R}(U,\bar{R}(\xi,Y)V)W \\ &- \bar{R}(U,V)(\bar{R}(\xi,Y)W) = L_{\bar{R}}[(\xi \wedge_g Y)(\bar{R}(U,V)W) - \bar{R}((\xi \wedge_g Y)U,V)W \\ (3.3) &- \bar{R}(U,(\xi \wedge_g Y)V)W - \bar{R}(U,V)(\xi \wedge_g Y)W]. \end{aligned}$$

Using (1.4) and (2.12) in (3.3) and then taking the inner product with  $\xi$ , we obtain

$$\begin{aligned} (L_{\bar{R}}+2)[-\bar{R}(U,V,W,Y) + \eta(\bar{R}(U,V)W)\eta(Y) + 2g(Y,U)\eta(V)\eta(W) \\ -2g(Y,U)g(V,W) - \eta(\bar{R}(Y,V)W)\eta(U) - 2g(Y,V)\eta(U)\eta(W) \\ +2g(Y,V)g(U,W) - \eta(\bar{R}(U,Y)W)\eta(V) - \eta(\bar{R}(U,V)Y)\eta(W)] &= 0. \end{aligned}$$

On plugging  $U = Y = e_i$  in (3.4) and taking summation over *i*, we get

(3.5) 
$$(L_{\bar{R}}+2)[S(V,W)-(n-5)g(V,W)+2(n-1)\eta(V)\eta(W)]=0.$$

This implies that either  $L_{\bar{R}} = -2$  or

(3.6) 
$$S(V,W) = (n-5)g(V,W) + 2(1-n)\eta(V)\eta(W).$$

On contracting (3.6), we get

(3.7) 
$$r = n(n-7) + 2.$$

Hence we can state the following:

**Theorem 3.1.** Let M be an n-dimensional pseudo-symmetric Kenmotsu manifold with respect to semi-symmetric metric connection. Then either  $L_{\bar{R}} = -2$  or the manifold is  $\eta$ -Einstein with constant scalar curvature r = n(n-7) + 2 with respect to Levi-Civita connection.

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# 4. Ricci pseudo-symmetric Kenmotsu manifold with respect to the semi-symmetric metric connection

Definition: An n-dimensional Kenmotsu manifold M is said to be Ricci pseudo-symmetric with respect to semi-symmetric metric connection, if

(4.1) 
$$(\overline{R}(X,Y)\cdot\overline{S})(Z,U) = L_{\overline{S}}Q(g,\overline{S})(Z,U;X,Y),$$

holds true on M, where  $L_{\bar{S}}$  is some function and Q(g,S) is the Tachibana tensor on M. From (4.1), it follows that

(4.2) 
$$\overline{S}(\overline{R}(X,Y)Z,U) + \overline{S}(Z,\overline{R}(X,Y)U) \\ = L_{\overline{S}}[\overline{S}((X \wedge_{q} Y)Z,U) + \overline{S}(Z,(X \wedge_{q} Y)U)].$$

Putting  $Y = U = \xi$  in (4.2), we have

$$(4.3) \ \bar{S}(\bar{R}(X,\xi)Z,\xi) + \bar{S}(Z,\bar{R}(X,\xi)\xi) = L_{\bar{S}}[\bar{S}((X \wedge \xi)Z,\xi) + \bar{S}(Z,(X \wedge \xi)\xi)].$$

Using (1.4), (2.12), (2.13) and (2.7) in (4.3), we can get

(4.4) 
$$(L_{\bar{S}}+2)[S(X,Z)-(n-3)g(X,Z)+2(n-2)\eta(X)\eta(Z)]=0.$$

This implies that either  $L_{\bar{S}} = -2$  or

(4.5) 
$$S(X,Z) = (n-3)g(X,Z) + 2(2-n)\eta(X)\eta(Z).$$

On contracting (4.5) over X and Z, we get

(4.6) 
$$r = (n-1)(n-4).$$

Thus we can state the following theorem:

Theorem 4.1. If a Kenmotsu manifold M is Ricci pseudo-symmetric with respect to semi-symmetric metric connection, then either  $L_{\bar{S}} = -2$  or the manifold is  $\eta$ -Einstein with constant scalar curvature r = (n-1)(n-4) with respect to Levi-Civita connection.

## 5. Projective pseudo-symmetric Kenmotsu manifold with respect to the semi-symmetric metric connection

Definition: An *n*-dimensional Kenmotsu manifold M is said to be projective pseudo-symmetric with respect to semi-symmetric metric connection if

(5.1) 
$$(\bar{R}(X,Y)\cdot\bar{P})(U,V)W = L_{\bar{P}}((X\wedge_{q}Y)\cdot\bar{P})(U,V)W,$$

holds on M. Putting  $Y = W = \xi$  in (5.1), we get

(5.2) 
$$(\bar{R}(X,\xi) \cdot \bar{P})(U,V)\xi = L_{\bar{P}}((X \wedge_g \xi) \cdot \bar{P})(U,V)\xi.$$

Now right hand side of (5.2) can be written as

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$$L_{\bar{P}}((X \wedge_g \xi) \cdot \bar{P})(U, V)\xi = L_{\bar{P}}[((X \wedge_g \xi)\bar{P})(U, V)\xi - \bar{P}((X \wedge_g \xi)U, V)\xi - \bar{P}(U, (X \wedge_g \xi)V)\xi - \bar{P}(U, V)(X \wedge_g \xi)\xi].$$
(5.3)

By virtue of (1.4), (1.5), (2.12), (2.13) and (2.7) in (5.3), we obtain

(5.4) 
$$L_{\bar{P}}((X \wedge_g \xi) \cdot \bar{P})(U, V)\xi = -L_{\bar{P}} \cdot \bar{P}(U, V)X.$$

Next by considering left hand side of (5.2), we have

$$(\bar{R}(X,\xi) \cdot \bar{P})(U,V)\xi = \bar{R}(X,\xi)\bar{P}(U,V)\xi - \bar{P}(\bar{R}(X,\xi)U,V)\xi$$
  
(5.5) 
$$- \bar{P}(U,\bar{R}(X,\xi)V)\xi - \bar{P}(U,V)\bar{R}(X,\xi)\xi.$$

Again using (1.5), (2.12), (2.13) and (2.7) in (5.5), we get

(5.6) 
$$(\bar{R}(X,\xi)\cdot\bar{P})(U,V)\xi = 2\bar{P}(U,V)X.$$

Substituting (5.4) and (5.6) in (5.2), we obtain

(5.7) 
$$(L_{\bar{P}}+2)\bar{P}(U,V)X=0.$$

This leads us to the following:

**Theorem 5.1.** If an *n*-dimensional Kenmotsu manifold is projective pseudo-symmetric with respect to the semi-symmetric metric connection, then either  $L_{\bar{P}} = -2$  or the manifold is projectively flat.

Also, in a Kenmotsu manifold, Bagewadi, Prakasha and Venkatesha [4] proved the following:

Lemma 5.1.[4] If the projective curvature tensor of a Kenmotsu manifold M admitting the semi-symmetric metric connection vanishes, then M reduces to an Einstein manifold with the constant scalar curvature -n(n-1).

Hence from Theorem 5.1. and Lemma 5.1., we conclude that:

Corollary 5.1. A projective pseudo-symmetric Kenmotsu manifold admitting the semi-symmetric metric connection is an Einstein manifold with the constant scalar curvature with respect to the Levi-Civita connection provided  $L_{\bar{P}} \neq -2$ .

# 6. $\phi$ -projective semi-symmetric Kenmotsu manifold with respect to the semi-symmetric metric connection

**Definition:** An *n*-dimensional Kenmotsu manifold M is said to be  $\phi$ -projectively semi-symmetric with respect to the semi-symmetric metric connection if  $\overline{P}(X,Y) \cdot \phi = 0$ .

Let us consider an n-dimensional Kenmotsu manifold M which is  $\phi\text{-projective}$  semi-symmetric. Then we have

(6.1) 
$$\bar{P}(X,Y)\phi Z - \phi \bar{P}(X,Y)Z = 0,$$

for any vector fields X, Y and Z on M. By virtue of (1.5) in (6.1) gives

(6.2) 
$$\bar{R}(X,Y)\phi Z - \phi \bar{R}(X,Y)Z + \frac{1}{n-1}[\bar{S}(Y,\phi Z)X - \bar{S}(X,\phi Z)Y + \bar{S}(Y,Z)\phi X - \bar{S}(X,Z)\phi Y] = 0.$$

On plugging  $Y = \xi$  in (6.2) and then using (2.12), (2.13) and (2.7), we obtain

(6.3) 
$$2g(X,\phi Z)\xi - \frac{1}{n-1}\bar{S}(X,\phi Z)\xi = 0.$$

Now taking the inner product of the above equation with  $\xi$ , we get

(6.4) 
$$2g(X,\phi Z) - \frac{1}{n-1}\bar{S}(X,\phi Z) = 0.$$

Replacing Z by  $\phi Z$  in (6.4) and then by virtue of (2.1) and (2.13), we obtain

(6.5) 
$$S(X,Z) = Ag(X,Z) + B\eta(X)\eta(Z),$$

where A = 5n - 7 and B = -2(3n - 5). Hence we can state the following:

**Theorem 6.1.** An *n*-dimensional  $\phi$ -projective semi-symmetric Kenmotsu manifold with respect to the semi-symmetric metric connection is  $\eta$ -Einstein with respect to the Levi-Civita connection.

#### 7. Example

Consider a 3-dimensional manifold  $M = \{(x, y, z) \in \mathbb{R}^3 : z \neq 0\}$ , where (x, y, z) are the standard coordinates in  $\mathbb{R}^3$ . We choose the vector fields

$$E_1 = -e^{-z}\frac{\partial}{\partial x}, \qquad E_2 = e^{-z}\frac{\partial}{\partial y}, \qquad E_3 = \frac{\partial}{\partial z},$$

which are linearly independent at each point of M. Let g be the Riemannian metric defined by

(7.1) 
$$g = e^{2z} (dx \otimes dx + dy \otimes dy) + \eta \otimes \eta,$$

where  $\eta$  is the 1-form defined by  $\eta(X) = g(X, E_3)$ , for any vector field X on M. Then  $\{E_1, E_2, E_3\}$  is an orthonormal basis of M. We define a (1, 1) tensor field  $\phi$  as

(7.2) 
$$\phi\left(X\frac{\partial}{\partial x} + Y\frac{\partial}{\partial y}\right) + Z\frac{\partial}{\partial z} = \left(Y\frac{\partial}{\partial x} - X\frac{\partial}{\partial y}\right).$$

Thus, we have

(7.3) 
$$\phi(E_1) = E_2, \ \phi(E_2) = -E_1 \text{ and } \phi(E_3) = 0.$$

The linearity property of  $\phi$  and g yields that

$$\eta (E_3) = 1, \qquad \phi^2 X = -X + \eta (X) E_3, (\phi X, \phi Y) = g (X, Y) - \eta (X) \eta (Y),$$

for any vector fields X, Y on M.

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Moreover, we get

$$[E_i, \xi] = E_i, \quad [E_i, E_j] = 0, \quad i, j = 1, 2$$

Using Koszul's formula, we obtain

$$\nabla_{E_i} E_i = -\xi, \quad \nabla_{E_i} \xi = E_i, \quad i = 1, 2.$$

and others are zero. Thus for  $E_3 = \xi$ ,  $M(\phi, \xi, \eta, g)$  is a Kenmotsu manifold. Now, the non-zero terms of the semi-symmetric metric connection on M become

(7.4) 
$$\bar{\nabla}_{E_i} E_i = -2\xi, \quad \bar{\nabla}_{E_i} \xi = 2E_i \quad i = 1, 2.$$

With the help of the above results it can be easily verified that

$$\begin{split} R(E_1,E_2)E_3 &= 0, & R(E_2,E_3)E_3 = -E_2, & R(E_1,E_3)E_3 = -E_1, \\ R(E_1,E_2)E_2 &= -E_1, & R(E_2,E_3)E_2 = E_3, & R(E_1,E_3)E_2 = 0, \\ R(E_1,E_2)E_1 &= E_2, & R(E_2,E_3)E_1 = 0, & R(E_1,E_3)E_1 = E_3. \\ and & \\ \bar{R}(E_1,E_2)E_3 &= 0, & \bar{R}(E_2,E_3)E_3 = -2E_2, & \bar{R}(E_1,E_3)E_3 = -2E_1, \\ \bar{R}(E_1,E_2)E_2 &= -4E_1, & \bar{R}(E_2,E_3)E_2 = 2E_3, & \bar{R}(E_1,E_3)E_2 = 0, \\ (7.5) & \bar{R}(E_1,E_2)E_1 = 4E_2, & \bar{R}(E_2,E_3)E_1 = 0, & \bar{R}(E_1,E_3)E_1 = 2E_3. \end{split}$$

In view of (1.1), one can obtain the torsion tensor  $\bar{T}$  with respect to the semi-symmetric metric connection as

$$\overline{T}(E_i, E_i) = 0$$
 for  $i = 1, 2, 3;$   
 $\overline{T}(E_1, E_2) = 0, \ \overline{T}(E_1, E_3) = E_1, \ \overline{T}(E_2, E_3) = E_2.$ 

Since  $E_1, E_2, E_3$  forms a basis, the vector fields  $X, Y, Z \in \chi(M)$  can be written as

(7.6) 
$$\begin{pmatrix} X \\ Y \\ Z \end{pmatrix} = \begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix} \begin{pmatrix} E_1 \\ E_2 \\ E_3 \end{pmatrix},$$

where  $a_i, b_i, c_i \in \mathbb{R}^+$  (the set of all positive real numbers), i = 1, 2, 3. Using the expressions of the curvature tensors, we find values of the Riemannian curvature and Ricci curvature with respect to the semi-symmetric metric connection as;

$$\bar{R}(X,Y)Z = [-4\{a_1b_2 - b_1a_2\}b_3 + 2\{c_1a_2 - a_1c_2\}c_3]E_1 + [-4\{b_1a_2 - a_1b_2\}a_3 + 2\{c_1b_2 - b_1c_2\}c_3]E_2$$

$$(7.7) \qquad + \quad \left[-2\{c_1a_2 - a_1c_2\}a_3 - 2\{c_1b_2 - b_1c_2\}b_3\right]E_3,$$

(7.8) 
$$\bar{S}(E_1, E_1) = \bar{S}(E_2, E_2) = -6, \ \bar{S}(E_3, E_3) = -4.$$

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In view of the expression of the endomorphism  $(E_i \wedge_g E_j)E_w = g(E_j, E_w)E_i - g(E_i, E_w)E_j$  for  $1 \le i, j, w \le 3$  and equations (7.5) and (7.8), one can easily verify that

$$\bar{S}(\bar{R}(E_i, E_3)E_j, E_3) + \bar{S}(E_j, \bar{R}(E_i, E_3)E_3) = -2[\bar{S}((E_i \wedge_g E_3)E_j, E_3) + \bar{S}(E_j, (E_i \wedge_g E_3)E_3)],$$
(7.9)

in view of the above equation Theorem 4.1. is verified.

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