

COMMON FIXED POINT THEOREMS INVOLVING C -CLASS FUNCTIONS IN G -METRIC SPACES

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Abstract. The purpose of this paper is to prove some common fixed point theorems using the concept of C class function in G -metric spaces. Moreover, some examples are presented to illustrate the validity of our results.

Key words: fixed-point theorems, C -class functions, G -metric space.

1. Introduction and Preliminaries

In [13], Mustafa and Sims introduced a new class of generalized metric space, called G -metric, as generalization of a metric space (X, d) . In fact, various researchers studied several and many fixed point theorems for self mappings in this structure (G -metric), for example we refer readers to References ([2, 3, 4, 6, 7, 8, 9, 10, 12, 14, 15, 16, 17, 18, 19, 20, 21, 22]).

In this paper, we will obtain common fixed point results for three mappings satisfying certain contractive conditions on G -metric space. The obtained results extend many recent results in the literature.

The following definitions and results will be needed:

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Definition 1.1. [13] Let X be a nonempty set. Suppose that the mapping $G : X \times X \times X \rightarrow \mathbb{R}^+$ satisfies:

- (a) $G(x, y, z) = 0$ if $x = y = z$;
- (b) $0 < G(x, x, y)$ for all $x, y \in X$. with $x \neq y$;
- (c) $G(x, y, y) \leq G(x, y, z)$ for all $x, y, z \in X$ with $y \neq z$;
- (d) $G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots$ (symmetry in all three variables); and
- (e) $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$ for all $x, y, z, a \in X$.

Then G is called a G -metric on X and (X, G) is called a G -metric space.

Note that if $G(x, y, z) = 0$ then $x = y = z$.

Definition 1.2. [13] A sequence $\{x_n\}$ in a G -metric space X is:

- (i) a G -Cauchy sequence if, for every $\varepsilon > 0$, there is a natural number n_0 such that for all $n, m, l \geq n_0$, $G(x_n, x_m, x_l) < \varepsilon$
- (ii) a G -Convergent sequence if, for any $\varepsilon > 0$, there is an $x \in X$ and an $n_0 \in \mathbb{N}$ such that for all $n, m \geq n_0$, $G(x_n, x_m, x) < \varepsilon$.

A G -metric space on X is said to be G -complete if every G -Cauchy sequence in X is G -convergent in X . It is known that $\{x_n\}$ G -converges to $x \in X$ if and only if $G(x_m, x_n, x) \rightarrow 0$ as $n, m \rightarrow +\infty$.

Proposition 1.1. [13] Let X be a G -metric space. Then the following are equivalent:

- (1) The sequence $\{x_n\}$ is G -convergent to x .
- (2) $G(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow +\infty$.
- (3) $G(x_n, x, x) \rightarrow 0$ as $n \rightarrow +\infty$.
- (4) $G(x_n, x_m, x) \rightarrow 0$ as $n, m \rightarrow +\infty$.

Proposition 1.2. [13] Let X be a G -metric space. Then the following are equivalent:

- (1) The sequence $\{x_n\}$ is G -Cauchy.
- (2) For every for every $\varepsilon > 0$ there exists $n_0 \in \mathbb{N}$ such that for all $n, m \geq n_0$, $G(x_n, x_m, x_m) < \varepsilon$; that is, if $G(x_n, x_m, x_m) \rightarrow 0$ as $n, m \rightarrow +\infty$.

Definition 1.3. [13] A G -metric space (X, G) is called symmetric G -metric space if $G(x, y, y) = G(y, x, x)$ for all $x, y \in X$, and called nonsymmetric if it is not symmetric.

Definition 1.4. [13] A G -metric space X is said to be complete if every G -Cauchy sequence in X is G -convergent in X .

Proposition 1.3. [13] Let (X, G) be a G -metric space, then the function $G(x, y, z)$ is jointly continuous in all three variables.

Recently, Arslan Hojat Ansari in [5] introduced the concept of a C -class functions which covers a large class of contractive conditions.

Definition 1.5. [5] A continuous function $F : [0, +\infty)^2 \rightarrow \mathbb{R}$ is called C -class function if for any $s, t \in [0, +\infty)$; the following conditions hold

- c1 $F(s, t) \leq s$;
- c2 $F(s, t) = s$ implies that either $s = 0$ or $t = 0$.

An extra condition on F that $F(0, 0) = 0$ could be imposed in some cases if required. The letter C will denote the class of all C - functions.

Example 1.1. The following examples shows that the class C is nonempty:

- 1. $F(s, t) = s - t$;
- 2. $F(s, t) = ms$; for some $m \in (0, 1)$.
- 3. $F(s, t) = \frac{s}{(1+t)^r}$ for some $r \in (0, 1)$.
- 4. $F(s, t) = \frac{\log(t+a^s)}{(1+t)}$, for some $a > 1$.

Let Φ_u denote the class of the functions $\varphi : [0, +\infty) \rightarrow [0, +\infty), \varphi(0) \geq 0$ Therefore, the condition $\varphi(0) \geq 0$ is meaningless. It may be $\varphi(0) = 0$.

In 1984, Khan et al. [11] introduced altering distance function as follows:

Definition 1.6. [11] A function $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is called an altering distance function if the following properties are satisfied:

- i) ψ is non-decreasing and continuous,
- ii) $\psi(t) = 0$ if and only if $t = 0$.

Let us suppose that Ψ denote the class of the altering distance functions.

Definition 1.7. A tripled (ψ, φ, F) where $\psi \in \Psi$; $\varphi \in \Phi_u$ and $F \in C$ is said to be a monotone if for any $x, y \in [0, 1)$,

$$x \leq y \text{ implies } F(\psi(x), \varphi(x)) \leq F(\psi(y), \varphi(y)).$$

Example 1.2. Let $F(s, t) = s - t, \varphi(x) = \sqrt{x}$

$$\psi(x) = \begin{cases} \sqrt{x} & \text{if } 0 \leq x \leq 1 \\ x^2 & \text{if } x > 1 \end{cases},$$

then (ψ, φ, F) is monotone.

2. Main results

Now, we are ready to state our main theorem

Theorem 2.1. *Let (X, G) be a complete G -metric space and suppose mappings f , g and $h : X \rightarrow X$ satisfy*

$$(2.1) \quad \psi(G(fx, gy, hz)) \leq F(\psi(M(x, y, z)), \varphi(M(x, y, z))),$$

for all $x, y, z \in X$, where $F : [0, +\infty)^2 \rightarrow \mathbb{R}$ is C -class function, $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is an altering distance function, $\varphi : [0, +\infty) \rightarrow [0, +\infty)$ is an ultra altering distance function and

$$M(x, y, z) = \max\{G(x, y, z), G(x, x, fx), G(y, y, gy), G(z, z, hz), \\ G(x, fx, gy), G(y, gy, hz), G(z, hz, fx)\}.$$

Then f, g and h have a unique common fixed point in X . Moreover, any fixed point of f is a fixed point of g and h and conversely.

Proof. Suppose that x_0 is an arbitrary point in X . Define a sequence $\{x_n\}$ by $x_{3n+1} = fx_{3n}$, $x_{3n+2} = gx_{3n+1}$, $x_{3n+3} = hx_{3n+2}$.

Firstly, taking $G(x_{3n}, x_{3n+1}, x_{3n+2}) = 0$, for some n . Using (2.1), we obtain

$$\psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3})) \leq F(\psi(M(x_{3n}, x_{3n+1}, x_{3n+2})), \varphi(M(x_{3n}, x_{3n+1}, x_{3n+2}))),$$

where

$$M(x_{3n}, x_{3n+1}, x_{3n+2}) = \max\{G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n}, x_{3n}, fx_{3n}), \\ G(x_{3n+1}, x_{3n+1}, gx_{3n+1}), G(x_{3n+2}, x_{3n+2}, hx_{3n+2}), \\ G(x_{3n}, fx_{3n}, gx_{3n+1}), G(x_{3n+1}, gx_{3n+1}, hx_{3n+2}), \\ G(x_{3n+2}, hx_{3n+2}, fx_{3n})\} \\ = \max\{G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n}, x_{3n}, x_{3n+1}), \\ G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n}, x_{3n}, x_{3n+1}), \\ G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n+1}, x_{3n+2}, x_{3n+3}), \\ G(x_{3n+2}, x_{3n+3}, x_{3n+1})\}.$$

So

$$\psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3})) \leq F(\psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3})), \varphi(G(x_{3n+1}, x_{3n+2}, x_{3n+3}))) \\ \leq \psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3}))$$

implies that $\psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3})) = 0$ and

$$(2.2) \quad x_{3n+1} = x_{3n+2} = x_{3n+3}.$$

The same arguments, we obtain $x_{3n+2} = x_{3n+3} = x_{3n+4}$ and hence x_{3n} becomes a common fixed point of f, g and h .

Now, by taking $G(x_{3n}, x_{3n+1}, x_{3n+2}) > 0$ for every n and using (2.1), we obtain

$$\psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3})) \leq F(\psi(M(x_{3n}, x_{3n+1}, x_{3n+2})), \varphi(M(x_{3n}, x_{3n+1}, x_{3n+2}))),$$

where

$$\begin{aligned} M(x_{3n}, x_{3n+1}, x_{3n+2}) &= \max\{G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n}, x_{3n}, fx_{3n}), \\ &\quad G(x_{3n+1}, x_{3n+1}, gx_{3n+1}), G(x_{3n+2}, x_{3n+2}, hx_{3n+2}), \\ &\quad G(x_{3n}, fx_{3n}, gx_{3n+1}), G(x_{3n+1}, gx_{3n+1}, hx_{3n+2}), \\ &\quad G(x_{3n+2}, hx_{3n+2}, fx_{3n})\} \\ &= \max\{G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n}, x_{3n}, x_{3n+1}), \\ &\quad G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n}, x_{3n}, x_{3n+1}), \\ &\quad G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n+1}, x_{3n+2}, x_{3n+3}), \\ &\quad G(x_{3n+2}, x_{3n+3}, x_{3n+1})\}. \end{aligned}$$

Hence

$$\begin{aligned} &\psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3})) \\ &\leq F\left(\psi(\max\{G(x_{3n+1}, x_{3n+2}, x_{3n+3}), G(x_{3n}, x_{3n+1}, x_{3n+2})\}), \right. \\ &\quad \left. \varphi(\max\{G(x_{3n}, x_{3n+1}, x_{3n+2}), G(x_{3n+1}, x_{3n+2}, x_{3n+3})\})\right). \end{aligned}$$

Suppose $\max\{G(x_{3n+1}, x_{3n+2}, x_{3n+3}), G(x_{3n}, x_{3n+1}, x_{3n+2})\} = G(x_{3n+1}, x_{3n+2}, x_{3n+3})$, so, we find the same result of (2.2), we obtain $G(x_{3n}, x_{3n+1}, x_{3n+2}) = 0$, This contradicts the assumption. Thus,

$$\begin{aligned} &\psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3})) \\ &\leq F(\psi(G(x_{3n}, x_{3n+1}, x_{3n+2})), \varphi(G(x_{3n}, x_{3n+1}, x_{3n+2}))) \\ &\leq \psi(G(x_{3n}, x_{3n+1}, x_{3n+2})). \end{aligned}$$

Then

$$\psi(G(x_{3n+1}, x_{3n+2}, x_{3n+3})) \leq \psi(G(x_{3n}, x_{3n+1}, x_{3n+2})).$$

By the nondecreasing of ψ , it follows that

$$G(x_{3n+1}, x_{3n+2}, x_{3n+3}) \leq G(x_{3n}, x_{3n+1}, x_{3n+2}).$$

Similarly, we find

$$\begin{aligned} G(x_{3n+3}, x_{3n+4}, x_{3n+5}) &\leq G(x_{3n+2}, x_{3n+3}, x_{3n+4}) \\ &\leq G(x_{3n+1}, x_{3n+2}, x_{3n+3}) \leq G(x_{3n}, x_{3n+1}, x_{3n+2}), \end{aligned}$$

Consequently, it can be shown that for all n ,

$$G(x_{n+1}, x_{n+2}, x_{n+3}) \leq G(x_n, x_{n+1}, x_{n+2}).$$

Therefore, $\{G(x_{3n+1}, x_{3n+2}, x_{3n+3})\}$ is a non increasing sequence, then there exists $L \geq 0$, such that

$$\psi \left(\lim_{n \rightarrow +\infty} G(x_{3n+1}, x_{3n+2}, x_{3n+3}) \right) \leq F \left(\begin{array}{l} \psi \left(\lim_{n \rightarrow +\infty} G(x_{3n}, x_{3n+1}, x_{3n+2}) \right), \\ \varphi \left(\lim_{n \rightarrow +\infty} \inf G(x_{3n}, x_{3n+1}, x_{3n+2}) \right). \end{array} \right)$$

Then, we have

$$\psi(L) \leq F(\psi(L), \varphi(L)) \leq \psi(L)$$

Thus $\psi(L) = 0$ and we conclude that

$$(2.3) \quad \lim_{n \rightarrow +\infty} G(x_{3n+1}, x_{3n+2}, x_{3n+3}) = 0.$$

Now, we shall show that $\{x_n\}$ is a G -Cauchy sequence. It is sufficient to show that $\{x_{3n}\}$ is G -Cauchy in X . If it is not, there is $\varepsilon > 0$ and integers $3n_k, 3m_k$ with $3m_k > 3n_k > k$ such that

$$(2.4) \quad G(x_{3n_k}, x_{3m_k}, x_{3m_k}) \geq \varepsilon \quad \text{and} \quad G(x_{3n_k}, x_{3m_k-3}, x_{3m_k-3}) < \varepsilon$$

Now, (2.3) and (2.4) give

$$\begin{aligned} \varepsilon &\leq G(x_{3n_k}, x_{3m_k}, x_{3m_k}) \\ &\leq G(x_{3n_k}, x_{3m_k-3}, x_{3m_k-3}) + G(x_{3m_k-3}, x_{3m_k}, x_{3m_k}) \\ &\leq G(x_{3n_k}, x_{3m_k-3}, x_{3m_k-3}) + G(x_{3m_k-3}, x_{3m_k-1}, x_{3m_k-1}) \\ &\quad + G(x_{3m_k-1}, x_{3m_k}, x_{3m_k}) \\ &\leq G(x_{3n_k}, x_{3m_k-3}, x_{3m_k-3}) + G(x_{3m_k-1}, x_{3m_k-2}, x_{3m_k-3}) \\ &\quad + G(x_{3m_k-1}, x_{3m_k}, x_{3m_k+1}), \end{aligned}$$

which implies that

$$(2.5) \quad \lim_{k \rightarrow +\infty} G(x_{3n_k}, x_{3m_k}, x_{3m_k}) = \varepsilon.$$

Also, in the same manner, we obtain

$$(2.6) \quad \lim_{k \rightarrow +\infty} G(x_{3n_k+1}, x_{3m_k+2}, x_{3m_k+3}) = \varepsilon.$$

However, by using (2.3) and (2.6), we obtain

$$(2.7) \quad \lim_{k \rightarrow +\infty} G(x_{3n_k}, x_{3m_k+1}, x_{3m_k+2}) = \varepsilon.$$

Also, using (2.3) and (2.7) we have

$$(2.8) \quad \lim_{k \rightarrow +\infty} G(x_{3n_k}, x_{3n_k+1}, x_{3m_k+2}) = \varepsilon.$$

Now, from the definition of $M(x, y, z)$ and from (2.3), (2.6), (2.7), (2.8) we get

$$\begin{aligned} & M(x_{3n_k}, x_{3m_k+1}, x_{3m_k+2}) \\ = & \max\{G(x_{3n_k}, x_{3m_k+1}, x_{3m_k+2}), G(x_{3n_k}, x_{3n_k}, x_{3n_k+1}), \\ & G(x_{3m_k+1}, x_{3m_k+1}, x_{3m_k+2}), G(x_{3m_k+2}, x_{3m_k+2}, x_{3m_k+3}), \\ & G(x_{3n_k}, x_{3n_k+1}, x_{3m_k+2}), G(x_{3m_k+1}, x_{3m_k+2}, x_{3m_k+3}), \\ & G(x_{3m_k+2}, x_{3m_k+3}, x_{3n_k+1})\} \end{aligned}$$

Hence

$$\lim_{k \rightarrow +\infty} M(x_{3n_k}, x_{3m_k+1}, x_{3m_k+2}) = \max\{\varepsilon, 0, 0, 0, \varepsilon, \varepsilon, \varepsilon\} = \varepsilon.$$

From (2.1), we obtain

$$\begin{aligned} \psi(G(x_{3n_k+1}, x_{3m_k+2}, x_{3m_k+3})) &= \psi(G(fx_{3n_k}, gx_{3m_k+1}, hx_{3m_k+2})) \\ &\leq F\left(\begin{matrix} \psi(M(x_{3n_k}, x_{3m_k+1}, x_{3m_k+2})), \\ \varphi(M(x_{3n_k}, x_{3m_k+1}, x_{3m_k+2})) \end{matrix}\right), \end{aligned}$$

So, as $k \rightarrow +\infty$, we have

$$\psi(\varepsilon) \leq F(\psi(\varepsilon), \varphi(\varepsilon)) \leq \psi(\varepsilon)$$

which leads to a contradiction because $\varepsilon > 0$.

It follows that $\{x_{3n}\}$ is a G -Cauchy sequence and by the G -completeness of X , there exists $u \in X$ such that $\{x_n\}$ converges to u as $n \rightarrow +\infty$. We claim that $fu = u$. For this, consider

$$\psi(G(fu, x_{3n+2}, x_{3n+3})) \leq F(\psi(M(u, x_{3n+1}, x_{3n+2})), \varphi(M(u, x_{3n+1}, x_{3n+2}))),$$

where

$$\begin{aligned} & M(u, x_{3n+1}, x_{3n+2}) \\ = & \max\{G(u, x_{3n+1}, x_{3n+2}), G(u, u, fu), G(x_{3n+1}, x_{3n+1}, gx_{3n+1}), \\ & G(x_{3n+2}, x_{3n+2}, hx_{3n+2}), G(u, fu, gx_{3n+1}), \\ & G(x_{3n+1}, gx_{3n+1}, hx_{3n+2}), G(x_{3n+2}, hx_{3n+2}, fu)\} \\ = & \max\{G(u, x_{3n+1}, x_{3n+2}), G(u, u, fu), G(x_{3n+1}, x_{3n+1}, x_{3n+2}), \\ & G(x_{3n+2}, x_{3n+2}, x_{3n+3}), G(u, fu, x_{3n+2}), \\ & G(x_{3n+1}, x_{3n+2}, x_{3n+3}), G(x_{3n+2}, x_{3n+3}, fu)\}. \end{aligned}$$

Letting $n \rightarrow +\infty$, we obtain that

$$\psi(G(fu, u, u)) \leq F(\psi(G(fu, u, u)), \varphi(G(fu, u, u))) \leq \psi(G(fu, u, u))$$

Hence $fu = u$. Similarly it can be shown that $gu = u$ and $hu = u$.

Finally, to show the uniqueness of common fixed point. Suppose that v is another common fixed point of f , g and h . Then

$$\psi(G(u, v, v)) = \psi(G(fu, gv, hv)) \leq F(\psi M(u, v, v), \varphi(M(u, v, v))),$$

where

$$\begin{aligned} M(u, v, v) &= \max\{G(u, v, v), G(u, u, fu), G(v, v, gv), \\ &\quad G(v, v, hv), G(u, fu, v), G(v, gv, hv), G(v, hv, fu)\} \\ &= \max\{G(u, v, v), G(u, u, u), G(v, v, v), \\ &\quad G(v, v, v), G(u, u, v), G(v, v, v), G(v, v, u)\} \\ &= \max\{G(u, v, v), G(u, u, v)\} \end{aligned}$$

If $M(u, v, v) = G(u, v, v)$, then

$$\psi(G(u, v, v)) \leq F(\psi(G(u, v, v)), \varphi(G(u, v, v))) \leq \psi(G(u, v, v))$$

which implies that $G(u, v, v) = 0$, a contradiction.

If

$$M(u, v, v) = G(u, u, v),$$

we can find

$$\psi(G(u, v, v)) \leq F(\psi(G(u, u, v)), \varphi(G(u, u, v))) \leq \psi(G(u, u, v))$$

so, by nondecreasing of ψ , it follows that

$$(2.9) \quad G(u, v, v) \leq G(u, u, v)$$

Again applying (2.1), we have

$$\psi(G(u, u, v)) \leq F(\psi(G(u, v, v)), \varphi(G(u, v, v))) \leq \psi(G(u, v, v)).$$

This implies that

$$(2.10) \quad G(u, u, v) \leq G(u, v, v)$$

by (2.9) and (2.10), we get $G(u, u, v) = G(u, v, v)$, a contradiction. Hence u is a unique common fixed point of f, g and h .

Now, we prove that every fixed point of f is a fixed point of g and h . suppose that for some p in X , we have $f(p) = p$. We claim that $p = g(p) = h(p)$.

If not then in the case when $p \neq g(p)$ or $p \neq h(p)$ we obtain

$$\psi(G(p, gp, hp)) = \psi(G(fp, gp, hp)) \leq F(\psi M((p, p, p)), \varphi(M((p, p, p))),$$

where

$$\begin{aligned} M(p, p, p) &= \max\{G(p, p, p), G(p, p, fp), G(p, p, gp), G(p, p, hp), \\ &\quad G(p, fp, gp), G(p, gp, hp), G(p, hp, fp)\} \\ &= \max\{0, G(p, p, gp), G(p, p, hp), G(p, gp, hp)\} \\ &= G(p, gp, hp) \end{aligned}$$

Thus

$$\psi(G(p, gp, hp)) \leq F(\psi(G(p, gp, hp)), \varphi(G(p, gp, hp))) \leq \psi(G(p, gp, hp))$$

a contradiction. Therefore in all cases, we conclude that, $f(p) = g(p) = h(p) = p$. Hence, every fixed point of f is a fixed point of g and h , and conversely. \square

Now, we give an example to support Theorem 2.1.

Example 2.1. Let $X = [0, 1]$ and $G(x, y, z) = \max\{|x - y|, |y - z|, |z - x|\}$ be a G - metric on X . Define $f, g, h : X \rightarrow X$ by

$$f(x) = \begin{cases} \frac{x}{15}, & x \in [0, \frac{1}{2}) \\ \frac{x}{11}, & x \in [\frac{1}{2}, 1] \end{cases}$$

$$g(x) = \begin{cases} \frac{x}{9}, & x \in [0, \frac{1}{2}) \\ \frac{x}{7}, & x \in [\frac{1}{2}, 1] \end{cases}$$

and

$$h(x) = \begin{cases} \frac{x}{7}, & x \in [0, \frac{1}{2}) \\ \frac{x}{4}, & x \in [\frac{1}{2}, 1] \end{cases}$$

We take $\psi(t) = t$ and $F(t, s) = \frac{9}{10}t$ for $t \in [0, +\infty)$, so that

$$F(\psi(M(x, y, z)), \varphi(M(x, y, z))) = \frac{9}{10}\psi(M(x, y, z)) = \frac{9}{10}M(x, y, z)$$

where

$$M(x, y, z) = \max \left\{ \begin{array}{l} G(x, y, z), G(x, x, fx), G(y, y, gy), G(z, z, hz), \\ G(x, fx, gy), G(y, gy, hz), G(z, hz, fx) \end{array} \right\}$$

a) If $x, y, z \in [0, \frac{1}{2})$

$G(x, y, z) = \max\{ x - y , y - z , z - x \}$
$G(x, x, fx) = \frac{14}{15}x$
$G(y, y, gy) = \frac{8}{9}y$
$G(z, z, hz) = \frac{6}{7}z$

Then, $M(x, y, z) = \max\{\max\{|x - y|, |y - z|, |z - x|\}, \frac{14}{15}x, \frac{8}{9}y, \frac{6}{7}z\}$.

So,

$$\begin{aligned} \psi(G(fx, gy, hz)) &= G(fx, gy, hz) = \max\{|fx - gy|, |gy - hz|, |hz - fx|\} \\ &= \max\{|\frac{x}{15} - \frac{y}{9}|, |\frac{y}{9} - \frac{z}{7}|, |\frac{z}{7} - \frac{x}{15}|\} \\ &\leq \frac{9}{10} \max\left\{\max\{|x - y|, |y - z|, |z - x|\}, \frac{14}{15}x, \frac{8}{9}y, \frac{6}{7}z\right\} \\ &= \frac{9}{10}M(x, y, z) \end{aligned}$$

b) If $x, y, z \in [\frac{1}{2}, 1]$

$G(x, y, z) = \max\{ x - y , y - z , z - x \}$
$G(x, x, fx) = \frac{10}{11}x$
$G(y, y, gy) = \frac{6}{7}y$
$G(z, z, hz) = \frac{3}{4}z$

Then, $M(x, y, z) = \max\{\max\{|x - y|, |y - z|, |z - x|\}, \frac{10}{11}x, \frac{6}{7}y, \frac{3}{4}z\}$.

We have,

$$\begin{aligned}
 \psi(G(fx, gy, hz)) &= G(fx, gy, hz) = \max\{|fx - gy|, |gy - hz|, |hz - fx|\} \\
 &= \max\{|\frac{x}{11} - \frac{y}{7}|, |\frac{y}{7} - \frac{z}{4}|, |\frac{z}{4} - \frac{x}{11}|\} \\
 &\leq \frac{9}{10} \max\left\{\max\{|x - y|, |y - z|, |z - x|\}, \frac{10}{11}x, \frac{6}{7}y, \frac{3}{4}z\right\} \\
 &= \frac{9}{10}M(x, y, z)
 \end{aligned}$$

c) If $x \in [0, \frac{1}{2})$ and $y, z \in [\frac{1}{2}, 1)$

$G(x, y, z) = \max\{ x - y , y - z , z - x \}$
$G(x, x, fx) = \frac{14}{15}x$
$G(y, y, gy) = \frac{6}{7}y$
$G(z, z, hz) = \frac{3}{4}z$

Then, $M(x, y, z) = \max\{\max\{|x - y|, |y - z|, |z - x|\}, \frac{14}{15}x, \frac{6}{7}y, \frac{3}{4}z\}$

We get,

$$\begin{aligned}
 \psi(G(fx, gy, hz)) &= G(fx, gy, hz) = \max\{|fx - gy|, |gy - hz|, |hz - fx|\} \\
 &= \max\{|\frac{x}{11} - \frac{y}{7}|, |\frac{y}{7} - \frac{z}{4}|, |\frac{z}{4} - \frac{x}{11}|\} \\
 &\leq \frac{9}{10} \max\left\{\max\{|x - y|, |y - z|, |z - x|\}, \frac{14}{15}x, \frac{6}{7}y, \frac{3}{4}z\right\} \\
 &= \frac{9}{10}M(x, y, z)
 \end{aligned}$$

d) As above results, we can find that the other cases are the same.

Therefore, all the conditions of Theorem 2.1 are satisfied. Then 0 is the unique common fixed point of f , g and h . Moreover, each fixed point of f is a fixed point of g and h , and conversely.

Corollary 2.1. *Let f , g and h be self maps on a complete G -metric space X satisfying the inequality*

$$(2.11) \quad \psi(G(fx, gy, hz)) \leq F(\psi(G(x, y, z)), \varphi(G(x, y, z))),$$

for all $x, y, z \in X$, where $F : [0, +\infty)^2 \rightarrow \mathbb{R}$ is C -class function, $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is an altering distance function, $\varphi : [0, +\infty) \rightarrow [0, +\infty)$ is an ultra altering distance function. Then f, g and h have a unique common fixed point in X . Moreover, any fixed point of f is a fixed point of g and h and conversely.

Corollary 2.2. [1] *Let f, g and h be self maps on a complete G -metric space X satisfying the inequality*

$$\psi(G(fx, gy, hz)) \leq \psi(M(x, y, z)) - \varphi(M(x, y, z))$$

where $\varphi \in \Psi$, $\psi \in \Psi$ and

$$M(x, y, z) = \max\{G(x, y, z), G(x, x, fx), G(y, y, gy), G(z, z, hz), \\ G(x, fx, gy), G(y, gy, hz), G(z, hz, fx)\}$$

for all $x, y, z \in X$. Then f, g and h have a unique common fixed point in X . Moreover, any fixed point of f is a fixed point of g and h and conversely.

Proof. Set $F(s, t) = s - t$ in Theorem 2.1. \square

Remark 2.1. Put $\psi(t) = t$, $F(s, t) = ks$ with $k \in (0, 1)$, we can find corollary 2.3 of [14]

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