# TRANSLATION-FAVORABLE FLAT SURFACES IN 3-SPACES 

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#### Abstract

In the paper, we obtain the complete classification of Translation-Factorable (TF-) surfaces with vanishing Gaussian curvature in Euclidean and Minkowski 3-spaces. Keywords: flat surfaces, Gaussian curvatures, 3-spaces


## 1. Introduction

In the study of the differential geometries of surfaces in 3-spaces, it is the most popular to examine curvature properties or the relationships between the corresponding curvatures of them. Let $M$ be a surface in 3 -spaces and $(x, y, z)$ rectangular coordinates. It is well known that $M$ is called as translation or factorable (homothetical) surface if it is locally described as the graph of $z=f(x)+g(y)$ or $z=f(x) g(y)$, respectively. Translation surfaces having constant mean curvature (CMC) or constant Gaussian curvature (CGC) in 3 -spaces have been studied in $[1,4,15,16,22,23]$. Furthermore, translation surfaces in 3 -spaces satisfying Weingarten condition have been studied by Dillen et. all in [10], by Sipus in [22] and also by Sipus and Dijvak in [23]. On the other hand, factorable (homothetical) surfaces whose curvatures satisfy certain conditions have been investigated in $[2,3,17]$. As an exception, surfaces with vanishing curvature have been also very much focused. It is well known that $M$ is called as flat or minimal surface if the Gaussian curvature or the mean curvature vanishes, respectively. The study of flat or minimal surfaces have found many applications in differential geometry

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and also physics, (see in $[5,11,24,25]$ ). Very recently, as a generalization of these surfaces, Difi, Ali and Zoubir described a new type surfaces called with translationfactorable (TF) surfaces in Euclidean 3-space in [9]. Moreover, author investigated these surfaces in Galilean 3-spaces, in [14]. In that paper, authors studied on the position vector of this new type surface in the 3-dimensional Euclidean space and Lorentzian-Minkowski space satisfying the special condition $\Delta r_{i}=\lambda_{i} r_{i}$, where $\Delta$ denotes the Laplace operator.

The main interest of this paper is to obtain the complete classification of Transla-tion-Factorable (TF-) surfaces with vanishing Gaussian curvatures in 3 -spaces, starting from this new type of surface, called as Translation-Factorable (TF-) surfaces, defined in [9]. In Sect. 2, we introduce the notations that we are going to use and give a brief summary of basic definitions in theory of surfaces in Euclidean and Minkowski 3 -spaces. In Sect. 3 and 4, we give the complete classification of TF-flat surfaces in the Euclidean 3-space and Minkowski 3-space, respectively.

## 2. Preliminiaries

Let Euclidean and Minkowski 3-spaces denote with $\mathbb{E}^{3}$ and $\mathbb{E}_{1}^{3}$, respectively. One may introduce an euclidean and Lorentzian inner products between $u=\left(u_{1}, u_{2}, u_{3}\right)$ and $v=\left(v_{1}, v_{2}, v_{3}\right)$ as

$$
\langle u, v\rangle=\left(d \xi_{0}\right)^{2}+\left(d \xi_{1}\right)^{2}+\left(d \xi_{2}\right)^{2} \quad \text { and } \quad\langle u, v\rangle_{L}=\left(d \xi_{0}\right)^{2}+\left(d \xi_{1}\right)^{2}-\left(d \xi_{2}\right)^{2} .
$$

Here $\left(\xi_{0}, \xi_{1}, \xi_{2}\right)$ is rectangular coordinate system of 3 -spaces. These inner products induce in $\mathbb{E}^{3}$ and $\mathbb{E}_{1}^{3}$ a norm in a natural way:

$$
\|u\|=\sqrt{|\langle u, u\rangle|} \quad \text { and } \quad\|u\|_{L}=\sqrt{|\langle u, u\rangle|_{L}}
$$

respectively. In addition, the corresponding cross products in $\mathbb{E}^{3}$ and $\mathbb{E}_{1}^{3}$ shall be showed here by $\wedge$ and $\wedge_{L}$, respectively: notice that $\wedge_{L}$ should be computed as

$$
u \wedge_{L} v=e_{1}\left|\begin{array}{cc}
u_{2} & u_{3} \\
v_{2} & v_{3}
\end{array}\right|-e_{2}\left|\begin{array}{cc}
u_{1} & u_{3} \\
v_{1} & v_{3}
\end{array}\right|-e_{3}\left|\begin{array}{cc}
u_{1} & u_{2} \\
v_{1} & v_{2}
\end{array}\right|
$$

Let $M^{2}$ be a surface in $\mathbb{E}^{3}$ or $\mathbb{E}_{1}^{3}$. If $M^{2}$ is parameterized by an immersion

$$
x\left(u^{1}, u^{2}\right)=\left(x^{1}\left(u^{1}, u^{2}\right), x^{2}\left(u^{1}, u^{2}\right), x^{3}\left(u^{1}, u^{2}\right)\right)
$$

then $M^{2}$ is a regular surface if and only if the corresponding cross products of $x_{1}$ and $x_{2}$ don't vanish anywhere. Here, $x_{k}=\partial x / \partial u^{k}, k=1,2$. So, the normal vector field $\mathbf{N}$ of a regular surface $M^{2}$ in $\mathbb{E}^{3}$ or $\mathbb{E}_{1}^{3}$ is given by

$$
\begin{equation*}
\mathbf{N}=\frac{x_{1} \wedge x_{2}}{\left\|x_{1} \wedge x_{2}\right\|} \quad \text { or } \quad \mathbf{N}_{L}=\frac{x_{1} \wedge_{L} x_{2}}{\left\|x_{1} \wedge_{L} x_{2}\right\|_{L}} \tag{2.1}
\end{equation*}
$$

The first fundamental form of $x: U \longrightarrow M^{2} \subset \mathbb{E}^{3}$ (or $\mathbb{E}_{1}^{3}$ ) is defined as:

$$
\begin{equation*}
I=g_{i j} d u^{i} d u^{j}, \quad g_{i j}=\left\langle x_{i}, x_{j}\right\rangle \quad \text { or } \quad g_{i j}=\left\langle x_{i}, x_{j}\right\rangle_{L} . \tag{2.2}
\end{equation*}
$$

The second fundamental form $I I$ in simply and pseudo-isotropic spaces is with differentiable coefficients

$$
\begin{equation*}
I I=h_{i j} d u^{i} d u^{j}, \quad h_{i j}=\left\langle\mathbf{N}, x_{i j}\right\rangle \quad \text { or } \quad h_{i j}=\left\langle\mathbf{N}, x_{i j}\right\rangle_{L} . \tag{2.3}
\end{equation*}
$$

Therefore, the Gaussian curvature $K$ and the mean curvature $H$ of surface $\Sigma$ are defined by, respectively,

$$
\begin{align*}
K & =\frac{h_{11} h_{22}-h_{12}^{2}}{W^{2}}  \tag{2.4}\\
H & =\frac{g_{11} h_{22}-2 g_{12} h_{12}+g_{22} h_{11}}{2 W^{2}} \tag{2.5}
\end{align*}
$$

where $W=\sqrt{\left|g_{11} g_{22}-g_{12}^{2}\right|}$. Note that if $g_{11} g_{22}-g_{12}{ }^{2}<0$ or $g_{11} g_{22}-g_{12}{ }^{2}>0$, then the surface $M^{2}$ in $\mathbb{E}_{1}^{3}$ is called as time-like or space-like surface, respectively.

Now, first we would like to give the definition of the translation-factorable (TF-) surfaces in $\mathbb{E}^{3}$ defined in [9]. And then we would like to complete the definition of translation-factorable (TF-) surfaces in $\mathbb{E}_{1}^{3}$ given in same paper as follows:

Definition 2.1. Let $M^{2}$ be a surface in Euclidean 3-space. Then $M$ is called a translation-factorable (TF-) surface if it can be locally written as following:

$$
\begin{equation*}
x(s, t)=(s, t, B(f(s) g(t))+A(f(s)+g(t))) \tag{2.6}
\end{equation*}
$$

where $f$ and $g$ are some real functions and $A, B$ are non-zero constants.

Definition 2.2. Let $M^{2}$ be a surface in Minkowski 3 -space, $\mathbb{E}_{1}^{3}$. Then $M$ is called a translation-factorable (TF-) surface if it can be locally written as one of the followings:

$$
\begin{equation*}
x(s, t)=(s, t, B(f(s) g(t))+A(f(s)+g(t))), \tag{2.7}
\end{equation*}
$$

or

$$
\begin{equation*}
x(s, t)=(A(f(s)+g(t))+B(f(s) g(t)), s, t)) \tag{2.8}
\end{equation*}
$$

which are called as first and second type and where $f$ and $g$ are some real functions and $A, B$ are non-zero constants.

Remark 2.1. From Definition 2.2, one can be directly seen when taking $A=0$ and $B \neq 0$, then surface becomes a factorable surface studied in [17]. On the other hand, if one can take $B=0$ and $A \neq 0$, then surface is a translation surface studied in [15].

## 3. Classification of Translation-Factorable surfaces with vanishing Gaussian curvature in $\mathbb{E}^{3}$

As mentioned in the previous section, the TF-surfaces can be parametrized as in (2.6) in Euclidean 3-spaces. In this section, we calculate the Gaussian curvature for the TF-surfaces in $\mathbb{E}^{3}$. And then, we examine when it vanishes. Finally, we give the complete classification of of the TF-surfaces with vanishing Gaussian curvatures.

Let $M^{2}$ be a TF-surface in Euclidean 3 -space, $\mathbb{E}^{3}$. Hence it can be parametrized as

$$
\begin{equation*}
x(s, t)=(s, t, B(f(s) g(t))+A(f(s)+g(t))) . \tag{3.1}
\end{equation*}
$$

Thus, the partial derivatives and $\mathbf{N}$, the unit normal vector field defined by (2.1) of this type surface are obtained by

$$
\begin{align*}
x_{s} & =\left(1,0,(B g(t)+A) f^{\prime}(s)\right)  \tag{3.2}\\
x_{t} & =\left(0,1, g^{\prime}(t)(B f(s)+A)\right)  \tag{3.3}\\
\mathbf{N} & =\frac{1}{W}\left(-f^{\prime}(s)(B g(t)+A),-g^{\prime}(t)(B f(s)+A), 1\right) \tag{3.4}
\end{align*}
$$

Here $W=\sqrt{1+g^{\prime}(t)^{2}(B f(s)+A)^{2}+f^{\prime}(s)^{2}(B g(t)+A)^{2}}$ and by I, we have denoted derivatives with respect to corresponding parameters. For readability, here and in the rest of the paper, we will lower the parameters of the $f(s)$ and $g(t)$ functions. Now, by considering the above into the second equalities in (2.2) and (2.3), respectively, we get

$$
\begin{align*}
& g_{11}=1+{f^{\prime}}^{2}(B g+A)^{2} \\
& g_{12}=g^{\prime} f^{\prime}(B f+A)(B g+A)  \tag{3.5}\\
& g_{22}=1+{g^{\prime}}^{2}(B f+A)^{2}
\end{align*}
$$

and

$$
\begin{equation*}
h_{11}=\frac{f^{\prime \prime}(B g+A)}{W}, \quad h_{12}=\frac{B f^{\prime} g^{\prime}}{W}, \quad h_{22}=\frac{g^{\prime \prime}(B f+A)}{W} \tag{3.6}
\end{equation*}
$$

where $W^{2}=1+{g^{\prime}}^{2}(B f+A)^{2}+{f^{\prime}}^{2}(B g+A)^{2}$. Hence, by substituting of the last two statements into (2.4) gives

$$
\begin{equation*}
K=\frac{f^{\prime \prime} g^{\prime \prime}(B f+A)(B g+A)-B^{2}\left(f^{\prime}\right)^{2}\left(g^{\prime}\right)^{2}}{1+{g^{\prime}}^{2}(B f+A)^{2}+{f^{\prime 2}}^{2}(B g+A)^{2}} \tag{3.7}
\end{equation*}
$$

where $f$ and $g$ are some real functions and $A, B$ are non-zero constants.
Now, we would like to investigate the vanishing Gaussian curvature problem for TF-surfaces in $\mathbb{E}^{3}$. As well known, the surfaces with vanishing Gaussian curvature are called flat. Now, we examine TF- flat surface in Euclidean 3-space, whose Gaussian curvature is identically zero. Then the following classification theorem is valid.

Theorem 3.1. Let $M^{2}$ be a TF-surface defined by (3.1) in the Euclidean 3-space. Then, $M^{2}$ is a flat surface if and only if it can be parametrized as one of the followings:

1. $M^{2}$ is a part of a plane,
2. $M^{2}$ is a regular surface in $\mathbb{E}^{3}$ parametrized by

$$
\begin{equation*}
x(s, t)=(s, t, g(t)(B c+A)+A c) \tag{3.8}
\end{equation*}
$$

where $f=c$ is a constant function or

$$
\begin{equation*}
x(s, t)=(s, t, f(s)(B c+A)+A c) \tag{3.9}
\end{equation*}
$$

where $g=c$ is a constant function.
3. $f$ and $g$ are given by

$$
\begin{equation*}
f(s)=-\frac{1}{B} e^{B\left(c_{1} s+c_{2}\right)}+\frac{A}{B}, \quad g(t)=-\frac{1}{B} e^{B\left(c_{1} t+c_{2}\right)}+\frac{A}{B} . \tag{3.10}
\end{equation*}
$$

4. $f$ and $g$ are given by

$$
\begin{align*}
& f(s)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} s+c_{2}\right)\right)^{\frac{1}{1-C}},  \tag{3.11}\\
& g(t)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} t+c_{2}\right)\right)^{\frac{1}{1-C}} .
\end{align*}
$$

Proof. Let $M^{2}$ be the TF- flat surface. Thus, from (3.7), it is clear that is sufficient that

$$
\begin{equation*}
f^{\prime \prime} g^{\prime \prime}(B f+A)(B g+A)-B^{2}\left(f^{\prime}\right)^{2}\left(g^{\prime}\right)^{2}=0 \tag{3.12}
\end{equation*}
$$

Let us consider on the following possibilities:
Case (1): $f^{\prime}=0$ and $g^{\prime}=0$. Then, the equation (3.12) is trivially satisfied. By considering these assumptions in (3.1), respectively, we obtain $M^{2}$ is an open part of plane. Thus, we have Case (1) of Theorem 3.1.

Case (2): $f^{\prime}=0$ or $g^{\prime}=0$. First, assume that $f^{\prime}=0$, i.e., $f$ be constant. In case, the equation (3.12) is trivially satisfied. But, in case $g$ is a arbitrary smooth function. Thus, we get (3.8). Similarly, by considering the assumption of $g$ as $g^{\prime}=0$, we can get (3.9) in Theorem 3.1.

Case (3): Let $f^{\prime \prime}=0$ or $g^{\prime \prime}=0$, but not both. First, assume that $f^{\prime \prime}=0$, i.e., $f$ be a linear function. In this case, one get $g^{\prime}=0$ to provide the equation (3.12). Second, let $g^{\prime \prime}=0$. Then by the similar way, $f^{\prime}=0$ must be. Note that one can easily see that these cases are covered by Case (2).

Case (4): Let $f^{\prime}, g^{\prime}, f^{\prime \prime}$ and $g^{\prime \prime}$ be non-zero. Then, the equation (3.12) can be rewritten as

$$
\begin{equation*}
\frac{f^{\prime \prime}(A+B f)}{B\left(f^{\prime}\right)^{2}}=\frac{B\left(g^{\prime}\right)^{2}}{g^{\prime \prime}(A+B g)}=C \tag{3.13}
\end{equation*}
$$

for non-zero constant $C$. We are going to consider the following cases seperately: Case (4a): $C=1$. In this case (3.13) implies that

$$
\begin{equation*}
f^{\prime \prime}(A+B f)=B\left(f^{\prime}\right)^{2} \quad \text { and } \quad B\left(g^{\prime}\right)^{2}=g^{\prime \prime}(A+B g) \tag{3.14}
\end{equation*}
$$

from which, we get (3.10) in Case (3) in Theorem 3.1.
Case (4b): $C \neq 1$. In this case we solve (3.13) to obtain (3.11).
Conversely, a direct computation yields that the Gaussian curvature of each of surfaces given in Theorem 3.1 vanishes identically.

## 4. Classification of Translation-Factorable surfaces with vanishing Gaussian curvature in $\mathbb{E}_{1}^{3}$

In this section, we study two types of TF-surfaces in the 3-dimensional Minkowski space. Let $M^{2}$ be a TF-surface parametrized in (2.7) or (2.8) in Minkowski 3-spaces. Namely, $M^{2}$ can be parametrized as

$$
\begin{equation*}
x(s, t)=(s, t, A(f(s)+g(t))+B f(s) g(t)) \tag{4.1}
\end{equation*}
$$

or

$$
\begin{equation*}
x(s, t)=(A(f(s)+g(t))+B f(s) g(t), s, t)), \tag{4.2}
\end{equation*}
$$

which are called as first and second type TF-surfaces .
First, we would like to consider on the type I TF-surface parametrized as in (4.1). Thus, we have,

$$
\begin{align*}
x_{s} & =\left(1,0, f^{\prime}(A+B g)\right)  \tag{4.3}\\
x_{t} & =\left(0,1, g^{\prime}(A+B f)\right) \tag{4.4}
\end{align*}
$$

Also, $\mathbf{N}_{L}$ the unit normal vector field of $M^{2}$ defined by (2.1) is given by

$$
\begin{equation*}
\mathbf{N}_{L}=\frac{1}{W}\left(f^{\prime}(A+B g),-g^{\prime}(A+B f), 1\right) \tag{4.5}
\end{equation*}
$$

Here with I, we have denoted derivatives with respect to corresponding parameters and

$$
\begin{equation*}
W=\sqrt{\left|1-g^{\prime 2}(A+B f)^{2}-f^{\prime 2}(A+B g)^{2}\right|} \tag{4.6}
\end{equation*}
$$

By considering (4.3), (4.4) and (4.5) into the third equalities in (2.2) and (2.3), respectively, we obtain
$g_{11}=1-{f^{\prime}}^{2}(A+B g)^{2}, \quad g_{12}=-f^{\prime} g^{\prime}(A+B f)(A+B g), \quad g_{22}=1-{g^{\prime}}^{2}(A+B f)^{2}$, and

$$
\begin{equation*}
h_{11}=\frac{f^{\prime \prime}(B g+A)}{W}, \quad h_{12}=\frac{B f^{\prime} g^{\prime}}{W}, \quad h_{22}=\frac{g^{\prime \prime}(B f+A)}{W} . \tag{4.8}
\end{equation*}
$$

Thus, by substituting of these above statements into (2.4) gives

$$
\begin{equation*}
K_{L}=\frac{f^{\prime \prime} g^{\prime \prime}(B f+A)(B g+A)-B^{2}\left(f^{\prime}\right)^{2}\left(g^{\prime}\right)^{2}}{W^{4}} \tag{4.9}
\end{equation*}
$$

where $f$ and $g$ are some real functions, $A, B$ are non-zero constants and $W$ is given as in (4.6).

Now, we would like to give the following theorem being the classification of type I TF-surfaces with vanishing Gaussian curvature in $\mathbb{E}_{1}^{3}$.

Theorem 4.1. Let $M^{2}$ be a type I TF-surface defined by (4.1) in the Minkowski 3-space. Then,

1. $M^{2}$ is a type I space-like flat surface if and only if it can be parametrized as one of the followings:
(a) $M^{2}$ is a part of a plane,
(b) $M^{2}$ is a space-like surface in $\mathbb{E}_{1}^{3}$ parametrized by

$$
\begin{equation*}
x(s, t)=(s, t, g(t)(A+B c)+A c) \tag{4.10}
\end{equation*}
$$

where $f=c$ is a constant function and $\frac{-1}{A+B c}<g^{\prime}<\frac{1}{A+B c}$ or

$$
\begin{equation*}
x(s, t)=(s, t, f(s)(A+B c)+A c) \tag{4.11}
\end{equation*}
$$

where $g=c$ is a constant function and $\frac{-1}{A+B c}<f^{\prime}<\frac{1}{A+B c}$.
(c) $f$ and $g$ are given by

$$
\begin{equation*}
f(s)=-\frac{1}{B} e^{B\left(c_{1} s+c_{2}\right)}+\frac{A}{B}, \quad g(t)=-\frac{1}{B} e^{B\left(c_{1} t+c_{2}\right)}+\frac{A}{B} \tag{4.12}
\end{equation*}
$$

such that satisfy the condition (4.18).
(d) $f$ and $g$ are given by

$$
\begin{align*}
& f(s)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} s+c_{2}\right)\right)^{\frac{1}{1-C}}  \tag{4.13}\\
& g(t)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} t+c_{2}\right)\right)^{\frac{1}{1-C}}
\end{align*}
$$

such that satisfy the condition (4.18).
2. $M^{2}$ is a type I time-like flat surface if and only if it can be parametrized as one of the followings:
(a) $M^{2}$ is a time-like surface in $\mathbb{E}_{1}^{3}$ parametrized by

$$
\begin{equation*}
x(s, t)=(s, t, g(t)(B c+A)+A c) \tag{4.14}
\end{equation*}
$$

where $f=c$ is a constant function or

$$
\begin{equation*}
x(s, t)=(s, t, f(s)(B c+A)+A c) \tag{4.15}
\end{equation*}
$$

where $g=c$ is a constant function.
(b) $f$ and $g$ are given by

$$
\begin{equation*}
f(s)=-\frac{1}{B} e^{B\left(c_{1} s+c_{2}\right)}+\frac{A}{B}, \quad g(t)=-\frac{1}{B} e^{B\left(c_{1} t+c_{2}\right)}+\frac{A}{B} \tag{4.16}
\end{equation*}
$$

(c) $f$ and $g$ are given by

$$
\begin{align*}
& f(s)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} s+c_{2}\right)\right)^{\frac{1}{1-C}}  \tag{4.17}\\
& g(t)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} t+c_{2}\right)\right)^{\frac{1}{1-C}}
\end{align*}
$$

Proof. Let $M^{2}$ be a type I TF- flat surface. First, let $M^{2}$ be a type I space-like surface. Then from (4.6), we have

$$
\begin{equation*}
{g^{\prime}}^{2}(A+B f)^{2}+{f^{\prime 2}}^{2}(A+B g)^{2}<1 \tag{4.18}
\end{equation*}
$$

Since $M^{2}$ is a flat surface, then from (4.9), it is clear that is sufficient that

$$
\begin{equation*}
f^{\prime \prime} g^{\prime \prime}(A+B f)(A+B g)-B^{2}\left(f^{\prime}\right)^{2}\left(g^{\prime}\right)^{2}=0 \tag{4.19}
\end{equation*}
$$

Let us consider on the following possibilities:
Case (1): $f^{\prime}=0$ and $g^{\prime}=0$. Then, the equation (4.18) and (4.19) are trivially satisfied. By considering these assumptions in (4.1), respectively, we obtain $M^{2}$ is an open part of plane. Thus, we have Case (1a) of Theorem 4.1.

Case (2): $f^{\prime}=0$ or $g^{\prime}=0$. First, assume that $f^{\prime}=0$, i.e., $f$ be a constant. In case, the equation (4.19) is trivially satisfied and also from (4.18) yields $g$ is satisfied $\frac{-1}{A+B c}<g^{\prime}<\frac{1}{A+B c}$. Thus, we get (4.10). Similarly, by considering the assumption of $g$ as $g^{\prime}=0$, we can get (4.11) in Theorem 4.1.

Case (3): Let $f^{\prime \prime}=0$ or $g^{\prime \prime}=0$, but not both. First, assume that $f^{\prime \prime}=0$, i.e., $f^{\prime}=c_{1}$ and $f=c_{1} s+c_{2}$ be a linear function. In this case, one get $g^{\prime}=0$, namely $g=C_{1}$, to provide the equation (4.19). Thus, from (4.18), we get the condition $1<c_{1}^{2} C_{1}^{2}$. Second, let $g^{\prime \prime}=0$. Then by the similar way, $f^{\prime}=0$ must be. Note that one can easily see that these cases are covered by Case (1b).

Case (4): Let $f^{\prime}, g^{\prime}, f^{\prime \prime}$ and $g^{\prime \prime}$ be non-zero. Then, the equation (4.19) can be rewritten as

$$
\begin{equation*}
\frac{f^{\prime \prime}(A+B f)}{B\left(f^{\prime}\right)^{2}}=\frac{B\left(g^{\prime}\right)^{2}}{g^{\prime \prime}(A+B g)}=C, \tag{4.20}
\end{equation*}
$$

for non-zero constant $C$. We are going to consider the following cases seperately:
Case (4a): $C=1$. In this case (4.20) implies that

$$
\begin{equation*}
f^{\prime \prime}(A+B f)=B\left(f^{\prime}\right)^{2} \quad \text { and } \quad B\left(g^{\prime}\right)^{2}=g^{\prime \prime}(A+B g) \tag{4.21}
\end{equation*}
$$

from which, we get (4.12) in Case (1c) in Theorem 4.1.

Case (4b): $C \neq 1$. In this case we solve (4.20) to obtain (4.13).
Secondly, let $M^{2}$ be a type I time-like surface in $\mathbb{E}_{1}^{3}$. Then from (4.6), we have

$$
\begin{equation*}
{g^{\prime}}^{2}(A+B f)^{2}+{f^{\prime 2}}^{2}(A+B g)^{2}>1 \tag{4.22}
\end{equation*}
$$

In view of this condition, the proof of the second case can be made similar to the previous case.

Conversely, a direct computation yields that the Gaussian curvature of each of surfaces given in Theorem 4.1 vanishes identically.

Now, secondly let $M^{2}$ be a type II TF-surfaces given as in (4.2). Thus, we have,

$$
\begin{align*}
x_{s} & =\left(f^{\prime}(A+B g), 1,0\right),  \tag{4.23}\\
x_{t} & =\left(g^{\prime}(A+B f), 0,1\right) . \tag{4.24}
\end{align*}
$$

Also, $\mathbf{N}_{L}$ the unit normal vector field of $M^{2}$ defined by (2.1) is given by

$$
\begin{equation*}
\mathbf{N}_{L}=\frac{1}{W}\left(1,-f^{\prime}(A+B g), g^{\prime}(A+B f)\right) \tag{4.25}
\end{equation*}
$$

Here with I, we have denoted derivatives with respect to corresponding parameters and

$$
\begin{equation*}
W=\sqrt{\left|1+f^{\prime 2}(A+B g)^{2}-g^{\prime 2}(A+B f)^{2}\right|} \tag{4.26}
\end{equation*}
$$

By considering (4.23), (4.24) and (4.25) into the third equalities in (2.2) and (2.3), respectively, we obtain
$g_{11}=1+{f^{\prime}}^{2}(A+B g)^{2}, \quad g_{12}=f^{\prime} g^{\prime}(A+B f)(A+B g), \quad g_{22}=g^{\prime 2}(A+B f)^{2}-1$,
and

$$
\begin{equation*}
h_{11}=\frac{f^{\prime \prime}(B g+A)}{W}, \quad h_{12}=\frac{B f^{\prime} g^{\prime}}{W}, \quad h_{22}=\frac{g^{\prime \prime}(B f+A)}{W} . \tag{4.28}
\end{equation*}
$$

Thus, by substituting of these above statements into (2.4) gives

$$
\begin{equation*}
K_{L}=\frac{f^{\prime \prime} g^{\prime \prime}(B f+A)(B g+A)-B^{2}\left(f^{\prime}\right)^{2}\left(g^{\prime}\right)^{2}}{W^{4}} \tag{4.29}
\end{equation*}
$$

where $f$ and $g$ are some real functions, $A, B$ are non-zero constants and $W$ is given as in (4.26). As well knowing that if $M^{2}$ is a space-like surface then, from (4.26) yields

$$
\begin{equation*}
g^{\prime 2}(A+B f)^{2}-{f^{\prime}}^{2}(A+B g)^{2}<1 \tag{4.30}
\end{equation*}
$$

On the other hand, if $M^{2}$ is a time-like surface then, from (4.26) yields

$$
\begin{equation*}
g^{\prime 2}(A+B f)^{2}-f^{\prime 2}(A+B g)^{2}>1 \tag{4.31}
\end{equation*}
$$

Now we would like to give the following theorem being the classification of type II TF-flat surfaces in $\mathbb{E}_{1}^{3}$.

Theorem 4.2. Let $M^{2}$ be a type II TF-surface defined by (4.2) in the Minkowski 3-space. Then,

1. $M^{2}$ is a type II space-like flat surface if and only if it can be parametrized as one of the followings:
(a) $M^{2}$ is a part of a plane,
(b) $M^{2}$ is a space-like surface in $\mathbb{E}_{1}^{3}$ parametrized by

$$
\begin{equation*}
x(s, t)=(s, t, g(t)(A+B c)+A c) \tag{4.32}
\end{equation*}
$$

where $f=c$ is a constant function and $\frac{-1}{A+B c}<g^{\prime}<\frac{1}{A+B c}$ or

$$
\begin{equation*}
x(s, t)=(s, t, f(s)(A+B c)+A c) \tag{4.33}
\end{equation*}
$$

where $g=c$ is a constant function and $0<f^{\prime 2}(A+B c)^{2}+1$.
(c) $f$ and $g$ are given by

$$
\begin{equation*}
f(s)=-\frac{1}{B} e^{B\left(c_{1} s+c_{2}\right)}+\frac{A}{B}, \quad g(t)=-\frac{1}{B} e^{B\left(c_{1} t+c_{2}\right)}+\frac{A}{B} \tag{4.34}
\end{equation*}
$$

such that satisfy the condition (4.30).
(d) $f$ and $g$ are given by

$$
\begin{align*}
& f(s)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} s+c_{2}\right)\right)^{\frac{1}{1-C}}  \tag{4.35}\\
& g(t)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} t+c_{2}\right)\right)^{\frac{1}{1-C}}
\end{align*}
$$

such that satisfy the condition (4.30).
2. $M^{2}$ is a type I time-like flat surface if and only if it can be parametrized as one of the followings:
(a) $M^{2}$ is a time-like surface in $\mathbb{E}_{1}^{3}$ parametrized by

$$
\begin{equation*}
x(s, t)=(s, t, g(t)(B c+A)+A c) \tag{4.36}
\end{equation*}
$$

where $f=c$ is a constant function or

$$
\begin{equation*}
x(s, t)=(s, t, f(s)(B c+A)+A c) \tag{4.37}
\end{equation*}
$$

where $g=c$ is a constant function.
(b) $f$ and $g$ are given by

$$
\begin{equation*}
f(s)=-\frac{1}{B} e^{B\left(c_{1} s+c_{2}\right)}+\frac{A}{B}, \quad g(t)=-\frac{1}{B} e^{B\left(c_{1} t+c_{2}\right)}+\frac{A}{B} \tag{4.38}
\end{equation*}
$$

such that satisfy the condition (4.31).
(c) $f$ and $g$ are given by

$$
\begin{align*}
& f(s)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} s+c_{2}\right)\right)^{\frac{1}{1-C}},  \tag{4.39}\\
& g(t)=-\frac{A}{B}+B^{\frac{C}{C-1}}\left((C-1)\left(c_{1} t+c_{2}\right)\right)^{\frac{1}{1-C}}
\end{align*}
$$

such that satisfy the condition (4.31).
Proof. In view of the condition (4.6), the proof of this theorem can be made similar to the previous Theorem 4.1.

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