

HYPERBOLIC KENMOTSU MANIFOLD ADMITTING A NEW TYPE OF SEMI-SYMMETRIC NON-METRIC CONNECTION

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Abstract. In this work, we study a new type of semi-symmetric non-metric connection on hyperbolic Kenmotsu manifold. Some Riemannian curvature's characteristics on hyperbolic Kenmotsu manifold are investigated. The properties of semi-symmetric, locally φ -symmetric and Ricci semi-symmetric hyperbolic Kenmotsu manifold endowed with a new type of semi-symmetric non-metric connection are evaluated. A semi-symmetric and Ricci semi-symmetric hyperbolic Kenmotsu manifold with a semi-symmetric non-metric connection is also demonstrated, the Ricci soliton of data $(\mathfrak{g}_1, \xi^b, \lambda)$ is shrinking. Finally, we demonstrate our results with a 3-dimensional example.

Keywords: Semi-symmetric non-metric, hyperbolic Kenmotsu manifold, Ricci soliton, Einstein manifold, Ricci semi-symmetric.

1. Introduction

A. Friedmann and A. Schouten [16] first established the concept of a semi-symmetric linear connection on differentiable manifold in 1924. E. Bartolotti [6] gave a geometrical meaning to such a connection. Further, H. A. Hayden [17] introduced the concept of metric connection with non zero torsion tensor on a Riemannian manifold.

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nian manifold. Agashe and Chafle [2] define a semi-symmetric non-metric connection in Riemannian manifold. This was further studied by Agashe and Chafle [3], S. K. Chaubey and A. C. Pandey [11] and many other geometers like [8, 14, 18]. Sengupta, De and Binh [21], De and Sengupta [13] define new type of semi-symmetric non-metric connection on Riemannian manifold. In line with this S. K. Chaubey and A. Yildiz [9] define another new type of semi-symmetric non-metric connection and studied different geometrical properties. On Riemannian manifold $(\Omega_{2n+1}, \mathfrak{g}_1)$, a linear connection $\tilde{\nabla}$ is semi-symmetric if $\tilde{\mathcal{T}}(\mathfrak{J}_1, \mathfrak{J}_2) = \bar{\eta}(\mathfrak{J}_2)\mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1)\mathfrak{J}_2, \forall \mathfrak{J}_1, \mathfrak{J}_2 \in \Gamma\Omega_{2n+1}$, where $\bar{\eta}$ is 1-form. Particularly, if $\mathfrak{J}_1 = \varphi\mathfrak{J}_1$ and $\mathfrak{J}_2 = \varphi\mathfrak{J}_2$, then the semi-symmetric connection reduces to the quarter-symmetric connection [15]. A semi-symmetric connection $\tilde{\nabla}$ is metric if $\tilde{\nabla}_{\mathfrak{g}_1} = 0$ & if $\tilde{\nabla}_{\mathfrak{g}_1} \neq 0$, then it is non-metric. Since then, the properties of the semi-symmetric non-metric connection on different structures have been studied by many geometers [22, 12].

On the other hand, the almost hyperbolic (f, ξ, η, g) -structure was defined and studied by Upadhyay and Dube [23]. Dube and Bhatt [7] studied CR-submanifold of trans-hyperbolic Sasakian manifold. Pankaj, S. K. Chaubey and Gillhanayar [20] studied Yamabe and gradient Yamabe soliton on 3-dimensional hyperbolic Kenmotsu manifolds. Mobin Ahmad and Kashif Ali [1] also studied CR-submanifold of a nearly hyperbolic Kenmotsu manifold admitting a quarter-symmetric non-metric connection. In the present article, it is initiated as follows: In section 2; contains some basic results of hyperbolic Kenmotsu manifolds. In section 3; we find some required results of the semi-symmetric non-metric connection. In section 4; we establish the relation between curvature tensor and semi-symmetric non-metric connection. The properties of semi-symmetric studied in section 5. Some results of locally φ -symmetric studied in section 6 and Ricci semi-symmetric hyperbolic Kenmotsu manifold equipped with semi-symmetric non-metric connection are investigated in section 7. We provided an example in section 8 and we also verified our results.

2. Hyperbolic Kenmotsu Manifold

Let $(\Omega_{2n+1}, \mathfrak{g}_1)$ be a contact manifold equipped with structure $(\varphi, \xi^b, \bar{\eta}, \mathfrak{g}_1)$, where φ is a $(1,1)$ -tensor field, ξ^b is a vector field, $\bar{\eta}$ is 1-form and \mathfrak{g}_1 is a Riemannian metric [20] such that-

$$(2.1) \quad \varphi^2\mathfrak{J}_1 = \mathfrak{J}_1 + \bar{\eta}(\mathfrak{J}_1)\xi^b, \quad \bar{\eta}(\xi^b) = -1, \quad \varphi\xi^b = 0, \quad \bar{\eta}(\varphi\mathfrak{J}_1) = 0,$$

$$(2.2) \quad \mathfrak{g}_1(\varphi\mathfrak{J}_1, \varphi\mathfrak{J}_2) = -\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) - \bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_2),$$

$$(2.3) \quad \mathfrak{g}_1(\varphi\mathfrak{J}_1, \mathfrak{J}_2) = -\mathfrak{g}_1(\mathfrak{J}_1, \varphi\mathfrak{J}_2), \quad \mathfrak{g}_1(\mathfrak{J}_1, \xi^b) = \bar{\eta}(\mathfrak{J}_1),$$

for all $\mathfrak{J}_1, \mathfrak{J}_2 \in \Gamma\Omega_{2n+1}$. A contact manifold Ω_{2n+1} is hyperbolic Kenmotsu manifold iff

$$(2.4) \quad (\nabla_{\mathfrak{J}_1}\varphi)\mathfrak{J}_2 = \mathfrak{g}_1(\varphi\mathfrak{J}_1, \mathfrak{J}_2)\xi^b - \bar{\eta}(\mathfrak{J}_2)\varphi\mathfrak{J}_1,$$

where ∇ is Levi-Civita connection on Ω_{2n+1} . From (2.1), (2.2), (2.3) and (2.4), we find

$$(2.5) \quad d\bar{\eta} = 0, \quad \nabla_{\mathfrak{J}_1} \xi^b = -\mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1) \xi^b,$$

$$(2.6) \quad (\nabla_{\mathfrak{J}_1} \bar{\eta}) \mathfrak{J}_2 = \mathfrak{g}_1(\varphi \mathfrak{J}_1, \varphi \mathfrak{J}_2) = -\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) - \bar{\eta}(\mathfrak{J}_1) \bar{\eta}(\mathfrak{J}_2).$$

Also the hyperbolic Kenmotsu manifold hold the following relations:

$$(2.7) \quad \bar{\eta}(\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3) = \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_1) - \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_2),$$

$$(2.8) \quad \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \xi^b = \bar{\eta}(\mathfrak{J}_2) \mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1) \mathfrak{J}_2,$$

$$(2.9) \quad \mathcal{R}(\xi^b, \mathfrak{J}_1) \mathfrak{J}_2 = \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) \xi^b - \bar{\eta}(\mathfrak{J}_2) \mathfrak{J}_1,$$

$$(2.10) \quad \mathcal{R}(\xi^b, \mathfrak{J}_1) \xi^b = -\mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1) \xi^b,$$

$$(2.11) \quad \mathcal{S}^b(\mathfrak{J}_1, \xi^b) = 2n\bar{\eta}(\mathfrak{J}_1),$$

$$(2.12) \quad \mathcal{S}^b(\xi^b, \xi^b) = -2n,$$

$$(2.13) \quad \mathcal{Q}^b(\xi^b) = -2n\xi^b,$$

\mathcal{S}^b and \mathcal{Q}^b are related by

$$(2.14) \quad \mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_2) = \mathfrak{g}_1(\mathcal{Q}^b \mathfrak{J}_1, \mathfrak{J}_2).$$

Definition 2.1. An almost contact manifold Ω_{2n+1} is an η -Einstein manifold (η -EM) if Ricci-tensor \mathcal{S}^b is of the form

$$(2.15) \quad \mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_2) = a_1 \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) + a_2 \bar{\eta}(\mathfrak{J}_1) \bar{\eta}(\mathfrak{J}_2),$$

where a_1 and a_2 are smooth functions on Ω_{2n+1} . If $a_2 = 0$, then manifold Ω_{2n+1} is an Einstein manifold (EM).

3. A new type of semi-symmetric non-metric connection

Let Ω_{2n+1} be hyperbolic Kenmotsu manifold. A linear connection $\tilde{\nabla}$ on Ω_{2n+1} is given as

$$(3.1) \quad \tilde{\nabla}_{\mathfrak{J}_1} \mathfrak{J}_2 = \nabla_{\mathfrak{J}_1} \mathfrak{J}_2 + \frac{1}{2} [\bar{\eta}(\mathfrak{J}_2) \mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1) \mathfrak{J}_2]$$

is known as a semi-symmetric non-metric connection $\tilde{\nabla}$ if it satisfies

$$(3.2) \quad \tilde{\mathcal{T}}(\mathfrak{J}_1, \mathfrak{J}_2) = \bar{\eta}(\mathfrak{J}_2) \mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1) \mathfrak{J}_2$$

and

$$(3.3) \quad (\tilde{\nabla}_{\mathfrak{J}_1} \mathfrak{g}_1)(\mathfrak{J}_2, \mathfrak{J}_3) = \frac{1}{2} [2\bar{\eta}(\mathfrak{J}_1) \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) - \bar{\eta}(\mathfrak{J}_2) \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) - \bar{\eta}(\mathfrak{J}_3) \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2)].$$

Now,

$$(3.4) \quad (\tilde{\nabla}_{\mathfrak{J}_1} \varphi)(\mathfrak{J}_2) = \frac{1}{2} [2(\nabla_{\mathfrak{J}_1} \varphi) \mathfrak{J}_2 - \bar{\eta}(\mathfrak{J}_2) (\varphi \mathfrak{J}_1)],$$

$$(3.5) \quad (\tilde{\nabla}_{\mathfrak{J}_1} \bar{\eta})(\mathfrak{J}_2) = (\nabla_{\mathfrak{J}_1} \bar{\eta})(\mathfrak{J}_2),$$

$$(3.6) \quad (\tilde{\nabla}_{\mathfrak{J}_1} \mathfrak{g}_1)(\varphi \mathfrak{J}_2, \mathfrak{J}_3) = \frac{1}{2} [2\bar{\eta}(\mathfrak{J}_1) \mathfrak{g}_1(\varphi \mathfrak{J}_2, \mathfrak{J}_3) - \bar{\eta}(\mathfrak{J}_3) \mathfrak{g}_1(\mathfrak{J}_1, \varphi \mathfrak{J}_2)].$$

Changing \mathfrak{J}_2 by ξ^b in (3.1), we have

$$(3.7) \quad \tilde{\nabla}_{\mathfrak{J}_1} \xi^b = \nabla_{\mathfrak{J}_1} \xi^b - \frac{1}{2} \varphi^2 \mathfrak{J}_1.$$

Replacing \mathfrak{J}_1 by ξ^b in (3.3), we get

$$(3.8) \quad (\tilde{\nabla}_{\xi^b} \mathfrak{g}_1)(\mathfrak{J}_2, \mathfrak{J}_3) = \mathfrak{g}_1(\varphi \mathfrak{J}_2, \varphi \mathfrak{J}_3) = -\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) - \bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3).$$

4. Curvature tensor of a hyperbolic Kenmotsu manifold endowed with semi-symmetric non-metric connection

The curvature tensor $\tilde{\mathcal{R}}$ with $\tilde{\nabla}$ defined as follows:

$$(4.1) \quad \tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 = \tilde{\nabla}_{\mathfrak{J}_1} \tilde{\nabla}_{\mathfrak{J}_2} \mathfrak{J}_3 - \tilde{\nabla}_{\mathfrak{J}_2} \tilde{\nabla}_{\mathfrak{J}_1} \mathfrak{J}_3 - \tilde{\nabla}_{[\mathfrak{J}_1, \mathfrak{J}_2]} \mathfrak{J}_3,$$

Using (3.1) in (4.1), we obtain

$$(4.2) \quad \begin{aligned} \tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 &= \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 + \frac{1}{2} [(\nabla_{\mathfrak{J}_1} \bar{\eta})(\mathfrak{J}_3) \mathfrak{J}_2 - (\nabla_{\mathfrak{J}_1} \bar{\eta})(\mathfrak{J}_2) \mathfrak{J}_3 \\ &\quad - (\nabla_{\mathfrak{J}_2} \bar{\eta})(\mathfrak{J}_3) \mathfrak{J}_1 + (\nabla_{\mathfrak{J}_2} \bar{\eta})(\mathfrak{J}_1) \mathfrak{J}_3] \\ &\quad + \frac{1}{4} [\bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3) \mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1) \bar{\eta}(\mathfrak{J}_3) \mathfrak{J}_2], \end{aligned}$$

where,

$$(4.3) \quad \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 = \nabla_{\mathfrak{J}_1} \nabla_{\mathfrak{J}_2} \mathfrak{J}_3 - \nabla_{\mathfrak{J}_2} \nabla_{\mathfrak{J}_1} \mathfrak{J}_3 - \nabla_{[\mathfrak{J}_1, \mathfrak{J}_2]} \mathfrak{J}_3.$$

Now, using (2.6) in (4.2), we find

$$(4.4) \quad \begin{aligned} \tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 &= \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 + \frac{1}{2} [\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \mathfrak{J}_1 - \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) \mathfrak{J}_2] \\ &\quad + \frac{3}{4} [\bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3) \mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1) \bar{\eta}(\mathfrak{J}_3) \mathfrak{J}_2]. \end{aligned}$$

Contracting equation (4.4) along \mathfrak{J}_1 , we get

$$(4.5) \quad \tilde{\mathcal{S}}^b(\mathfrak{J}_2, \mathfrak{J}_3) = \mathcal{S}^b(\mathfrak{J}_2, \mathfrak{J}_3) + n\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) + \frac{3n}{2}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3).$$

By virtue of (2.14) and (4.5) gives

$$(4.6) \quad \tilde{\mathcal{Q}}^b(\mathfrak{J}_2) = \mathcal{Q}^b(\mathfrak{J}_2) + n(\mathfrak{J}_2) + \frac{3n}{2}\bar{\eta}(\mathfrak{J}_2)\xi^b.$$

Again, contracting (4.5), we get

$$(4.7) \quad \tilde{\tau} = \tau + n(2n - \frac{1}{2}).$$

Where $\tilde{\mathcal{R}}; \mathcal{R}, \tilde{\mathcal{S}}^b; \mathcal{S}^b, \tilde{\mathcal{Q}}^b; \mathcal{Q}^b$ and $\tilde{\tau}; \tau$ are curvature tensor, Ricci tensor, Ricci operators and scalar curvature respectively equipped with $\tilde{\nabla}$ and Levi-Civita connection ∇ .

Replacing $\mathfrak{J}_1 = \xi^b$ in (4.4) and using (2.1), (2.3), we get

$$(4.8) \quad \begin{aligned} \tilde{\mathcal{R}}(\xi^b, \mathfrak{J}_2)\mathfrak{J}_3 &= \mathcal{R}(\xi^b, \mathfrak{J}_2)\mathfrak{J}_3 + \frac{1}{2}[\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\xi^b - \bar{\eta}(\mathfrak{J}_3)\mathfrak{J}_2] \\ &+ \frac{3}{4}[\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\xi^b + \bar{\eta}(\mathfrak{J}_3)\mathfrak{J}_2]. \end{aligned}$$

Using (2.9) in above equation (4.8), we get

$$(4.9) \quad \tilde{\mathcal{R}}(\xi^b, \mathfrak{J}_2)\mathfrak{J}_3 = \frac{3}{2}\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\xi^b + \frac{3}{4}[\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\xi^b - \bar{\eta}(\mathfrak{J}_3)\mathfrak{J}_2].$$

Fix $\mathfrak{J}_3 = \xi^b$ in (4.4) and using (2.1), (2.3), (2.8), we get

$$(4.10) \quad \begin{aligned} \tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2)\xi^b &= \frac{3}{4}\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2)\xi^b \\ &= \frac{3}{4}(\bar{\eta}(\mathfrak{J}_2)\mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1)\mathfrak{J}_2). \end{aligned}$$

Remark 4.1. Equation (4.10) shows that the manifold endowed with $\tilde{\nabla}$ is regular.

In view of (2.3), (2.8), (4.4) and $\mathfrak{g}_1(\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2, \mathfrak{J}_3), \mathfrak{J}_4) = -\mathfrak{g}_1(\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2, \mathfrak{J}_4), \mathfrak{J}_3)$, we have

$$(4.11) \quad \bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3) = \frac{3}{2}[\bar{\eta}(\mathfrak{J}_1)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) - \bar{\eta}(\mathfrak{J}_2)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)].$$

Contracting (4.10) with \mathfrak{J}_1 , we find

$$(4.12) \quad \tilde{\mathcal{S}}^b(\mathfrak{J}_2, \xi^b) = \frac{3n}{2}\bar{\eta}(\mathfrak{J}_2).$$

Taking $\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 = 0$ in equation (4.4), we get

$$(4.13) \quad \begin{aligned} \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 &= \frac{1}{2} [\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)\mathfrak{J}_2 - \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\mathfrak{J}_1] \\ &+ \frac{3}{4} [\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_3)\mathfrak{J}_2 - \bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\mathfrak{J}_1]. \end{aligned}$$

In view of $\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2, \mathfrak{J}_3, \mathfrak{J}_4) = \mathfrak{g}_1(\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3, \mathfrak{J}_4)$ and (4.13), we yields

$$(4.14) \quad \begin{aligned} \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2, \mathfrak{J}_3, \mathfrak{J}_4) &= \frac{1}{2} [\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4) - \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_4)] \\ &+ \frac{3}{4} [\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4) - \bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_4)]. \end{aligned}$$

Contracting above equation along \mathfrak{J}_1 and \mathfrak{J}_4 , we get

$$(4.15) \quad \mathcal{S}^b(\mathfrak{J}_2, \mathfrak{J}_3) = -n\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) - \frac{3n}{2}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3).$$

Theorem 4.1. *A hyperbolic Kenmotsu manifold Ω_{2n+1} is an η -EM, if Riemannian curvature tensor endowed with $\tilde{\nabla}$ is vanished.*

5. Semi-symmetric hyperbolic Kenmotsu manifold equipped with connection $\tilde{\nabla}$

A contact manifold Ω_{2n+1} with connection $\tilde{\nabla}$ is semi-symmetric if

$$(\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \cdot \tilde{\mathcal{R}})(\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5 = 0.$$

Then, we have

$$(5.1) \quad \begin{aligned} &\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2)\tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5 - \tilde{\mathcal{R}}(\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5 \\ &- \tilde{\mathcal{R}}(\mathfrak{J}_3, \tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_4)\mathfrak{J}_5 - \tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_5 = 0. \end{aligned}$$

On changing $\mathfrak{J}_1 = \xi^b$ in (5.1), we get

$$(5.2) \quad \begin{aligned} &\tilde{\mathcal{R}}(\xi^b, \mathfrak{J}_2)\tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5 - \tilde{\mathcal{R}}(\tilde{\mathcal{R}}(\xi^b, \mathfrak{J}_2)\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5 \\ &- \tilde{\mathcal{R}}(\mathfrak{J}_3, \tilde{\mathcal{R}}(\xi^b, \mathfrak{J}_2)\mathfrak{J}_4)\mathfrak{J}_5 - \tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\tilde{\mathcal{R}}(\xi^b, \mathfrak{J}_2)\mathfrak{J}_5 = 0. \end{aligned}$$

In view of (4.9), we obtain

$$\begin{aligned} 2\mathfrak{g}_1(\mathfrak{J}_2, \tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5) &= -\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5) - \bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5) \\ &- 2\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\bar{\eta}(\tilde{\mathcal{R}}(\xi^b, \mathfrak{J}_4)\mathfrak{J}_5) - \bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\bar{\eta}(\tilde{\mathcal{R}}(\xi^b, \mathfrak{J}_4)\mathfrak{J}_5) \\ &+ \bar{\eta}(\mathfrak{J}_3)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_2, \mathfrak{J}_4)\mathfrak{J}_5) - 2\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_3, \xi^b)\mathfrak{J}_5) \\ &- \bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_4)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_3, \xi^b)\mathfrak{J}_5) + \bar{\eta}(\mathfrak{J}_4)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_2)\mathfrak{J}_5) \\ &- 2\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_5)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\xi^b) - \bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_5)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\xi^b) \end{aligned}$$

$$(5.3) \quad +\bar{\eta}(\mathfrak{J}_5)\bar{\eta}(\tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_2).$$

Using (2.1), (2.3), (4.9), (4.10) and (4.11) in (5.3), we get

$$(5.4) \quad \begin{aligned} \tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4, \mathfrak{J}_5, \mathfrak{J}_2) &= \frac{3}{2}[\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_5) - \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4)\mathfrak{g}_1(\mathfrak{J}_3, \mathfrak{J}_5)] \\ &+ \frac{3}{4}[\bar{\eta}(\mathfrak{J}_4)\bar{\eta}(\mathfrak{J}_5)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) - \bar{\eta}(\mathfrak{J}_3)\bar{\eta}(\mathfrak{J}_5)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4)]. \end{aligned}$$

Hence, we have

$$(5.5) \quad \begin{aligned} \tilde{\mathcal{R}}(\mathfrak{J}_3, \mathfrak{J}_4)\mathfrak{J}_5 &= \frac{3}{2}[\mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_5)\mathfrak{J}_3 - \mathfrak{g}_1(\mathfrak{J}_3, \mathfrak{J}_5)\mathfrak{J}_4] \\ &+ \frac{3}{4}[\bar{\eta}(\mathfrak{J}_4)\bar{\eta}(\mathfrak{J}_5)\mathfrak{J}_3 - \bar{\eta}(\mathfrak{J}_3)\bar{\eta}(\mathfrak{J}_5)\mathfrak{J}_4]. \end{aligned}$$

Contracting (5.5) with \mathfrak{J}_3 , we get

$$(5.6) \quad \tilde{\mathcal{S}}^b(\mathfrak{J}_4, \mathfrak{J}_5) = 3n\mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_5) + \frac{3n}{2}\bar{\eta}(\mathfrak{J}_4)\bar{\eta}(\mathfrak{J}_5)$$

and

$$(5.7) \quad \tilde{\mathcal{Q}}^b(\mathfrak{J}_4) = 3n\mathfrak{J}_4 + \frac{3n}{2}\bar{\eta}(\mathfrak{J}_4)\xi^b.$$

Again contracting (5.6), we have

$$(5.8) \quad \tilde{\tau} = \frac{3n}{2}[4n+1].$$

By virtue (2.15) and equation (5.6), we state:

Theorem 5.1. *A semi-symmetric hyperbolic Kenmotsu manifold Ω_{2n+1} equipped with $\tilde{\nabla}$, then Ω_{2n+1} is an η -EM.*

Now, using (4.5), (4.6), (4.7) in (5.6), (5.7) and (5.8), we obtain

$$(5.9) \quad \mathcal{S}^b(\mathfrak{J}_4, \mathfrak{J}_5) = 2n\mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_5),$$

$$(5.10) \quad \mathcal{Q}^b\mathfrak{J}_4 = 2n(\mathfrak{J}_4)$$

and

$$(5.11) \quad \tau = 2n(2n+1).$$

Corollary 5.1. *A semi-symmetric hyperbolic Kenmotsu manifold Ω_{2n+1} endowed with $\tilde{\nabla}$ is an EM with semi-symmetric non-metric connection $\tilde{\nabla}$.*

The conformal curvature tensor $\tilde{\mathcal{L}}^\dagger$ endowed with $\tilde{\nabla}$ is defined as

$$\begin{aligned}
 \tilde{\mathcal{L}}^\dagger(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 &= \tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 - \frac{1}{2n-1}[\tilde{\mathcal{S}}^b(\mathfrak{J}_2, \mathfrak{J}_3)\mathfrak{J}_1 - \tilde{\mathcal{S}}^b(\mathfrak{J}_1, \mathfrak{J}_3)\mathfrak{J}_2 \\
 &\quad + \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\tilde{\mathcal{Q}}^b\mathfrak{J}_1 - \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)\tilde{\mathcal{Q}}^b\mathfrak{J}_2] \\
 (5.12) \quad &\quad + \frac{\tilde{\tau}}{2n(2n-1)}[\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\mathfrak{J}_1 - \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)\mathfrak{J}_2].
 \end{aligned}$$

Using (5.5), (5.6), (5.7) and (5.8) in (5.12), we find

$$\begin{aligned}
 \tilde{\mathcal{L}}^\dagger(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 &= \frac{3}{4(2n-1)}[\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)\mathfrak{J}_2 - \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\mathfrak{J}_1 \\
 &\quad + \bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_3)\mathfrak{J}_2 - \bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\mathfrak{J}_1] \\
 (5.13) \quad &\quad - \frac{3}{2(2n-1)}[\bar{\eta}(\mathfrak{J}_1)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\xi^b - \bar{\eta}(\mathfrak{J}_2)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)\xi^b].
 \end{aligned}$$

Taking $\mathfrak{J}_3 = \xi^b$ in (5.13), we obtain

$$(5.14) \quad \tilde{\mathcal{L}}^\dagger(\mathfrak{J}_1, \mathfrak{J}_2)\xi^b = 0.$$

Then, we have following result

Theorem 5.2. *A semi-symmetric hyperbolic Kenmotsu manifold Ω_{2n+1} admitting connection $\tilde{\nabla}$ is ξ^b -conformally flat with $\tilde{\nabla}$.*

6. Locally φ -symmetric hyperbolic Kenmotsu manifold admitting a connection $\tilde{\nabla}$

Definition 6.1. A manifold Ω_{2n+1} endowed with $\tilde{\nabla}$ is locally φ -symmetric [4] if

$$\varphi^2((\tilde{\nabla}_{\mathfrak{J}_4}\tilde{\mathcal{R}})(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3) = 0.$$

All vector fields $\mathfrak{J}_1, \mathfrak{J}_2, \mathfrak{J}_3, \mathfrak{J}_4$ orthogonal to ξ^b .

We know that

$$\begin{aligned}
 (\tilde{\nabla}_{\mathfrak{J}_4}\mathcal{R})(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 &= \tilde{\nabla}_{\mathfrak{J}_4}\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 - \mathcal{R}(\tilde{\nabla}_{\mathfrak{J}_4}\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 \\
 (6.1) \quad &\quad - \mathcal{R}(\mathfrak{J}_1, \tilde{\nabla}_{\mathfrak{J}_4}\mathfrak{J}_2)\mathfrak{J}_3 - \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2)(\tilde{\nabla}_{\mathfrak{J}_4}\mathfrak{J}_3).
 \end{aligned}$$

Using (3.1) and (2.7) in (6.1), we get

$$\begin{aligned}
 (\tilde{\nabla}_{\mathfrak{J}_4}\mathcal{R})(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 &= (\nabla_{\mathfrak{J}_4}\mathcal{R})(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 + \frac{1}{2}[2\bar{\eta}(\mathfrak{J}_4)\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_3 \\
 &\quad - \bar{\eta}(\mathfrak{J}_1)\mathcal{R}(\mathfrak{J}_4, \mathfrak{J}_2)\mathfrak{J}_3 - \bar{\eta}(\mathfrak{J}_2)\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_4)\mathfrak{J}_3 \\
 &\quad - \bar{\eta}(\mathfrak{J}_3)\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2)\mathfrak{J}_4 + \bar{\eta}(\mathfrak{J}_1)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\mathfrak{J}_4
 \end{aligned}$$

$$(6.2) \quad -\bar{\eta}(\mathfrak{J}_2) \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) \mathfrak{J}_4].$$

Covariant differentiation of (4.4) with respect to $\tilde{\nabla}$ along \mathfrak{J}_4 and using (2.6), (3.5), (6.2), we obtain

$$(6.3) \quad \begin{aligned} (\tilde{\nabla}_{\mathfrak{J}_4} \tilde{\mathcal{R}})(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 &= (\nabla_{\mathfrak{J}_4} \mathcal{R})(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 + \frac{1}{2} [2\bar{\eta}(\mathfrak{J}_4) \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 \\ &\quad - \bar{\eta}(\mathfrak{J}_1) \mathcal{R}(\mathfrak{J}_4, \mathfrak{J}_2) \mathfrak{J}_3 - \bar{\eta}(\mathfrak{J}_2) \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_4) \mathfrak{J}_3 \\ &\quad - \bar{\eta}(\mathfrak{J}_3) \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_4 + \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_1) \mathfrak{J}_4 \\ &\quad - \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_2) \mathfrak{J}_4 + \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_4) \mathfrak{J}_1 \\ &\quad - \bar{\eta}(\mathfrak{J}_4) \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) \mathfrak{J}_2 + 2\bar{\eta}(\mathfrak{J}_1) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_3) \mathfrak{J}_2 \\ &\quad - 2\bar{\eta}(\mathfrak{J}_2) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_3) \mathfrak{J}_1 + 2\bar{\eta}(\mathfrak{J}_3) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_1) \mathfrak{J}_2 \\ &\quad - 2\bar{\eta}(\mathfrak{J}_3) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_2) \mathfrak{J}_1 - 3\bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_4) \mathfrak{J}_1 \\ &\quad + 3\bar{\eta}(\mathfrak{J}_1) \bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_4) \mathfrak{J}_2]. \end{aligned}$$

Applying φ^2 on both side of equation (6.3) and using (2.1), (2.2), (2.3), we obtain

$$(6.4) \quad \begin{aligned} \varphi^2((\tilde{\nabla}_{\mathfrak{J}_4} \tilde{\mathcal{R}})(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3) &= \varphi^2((\nabla_{\mathfrak{J}_4} \mathcal{R})(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3) + \frac{1}{2} [2\bar{\eta}(\mathfrak{J}_4) \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3 \\ &\quad + 2\bar{\eta}(\mathfrak{J}_4) \bar{\eta}(\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3) \xi^b - \bar{\eta}(\mathfrak{J}_1) \mathcal{R}(\mathfrak{J}_4, \mathfrak{J}_2) \mathfrak{J}_3 \\ &\quad - \bar{\eta}(\mathfrak{J}_1) \bar{\eta}(\mathcal{R}(\mathfrak{J}_4, \mathfrak{J}_2) \mathfrak{J}_3) \xi^b - \bar{\eta}(\mathfrak{J}_2) \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_4) \mathfrak{J}_3 \\ &\quad - \bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_4) \mathfrak{J}_3) \xi^b - \bar{\eta}(\mathfrak{J}_3) \mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_4 \\ &\quad - \bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_4) \xi^b + \bar{\eta}(\mathfrak{J}_1) \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \mathfrak{J}_4 \\ &\quad + 2\bar{\eta}(\mathfrak{J}_1) \bar{\eta}(\mathfrak{J}_4) \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \xi^b - \bar{\eta}(\mathfrak{J}_2) \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) \mathfrak{J}_4 \\ &\quad - 2\bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_4) \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) \xi^b + \bar{\eta}(\mathfrak{J}_4) \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \mathfrak{J}_1 \\ &\quad - \bar{\eta}(\mathfrak{J}_4) \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) \mathfrak{J}_2 - 2\bar{\eta}(\mathfrak{J}_2) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_3) \mathfrak{J}_1 \\ &\quad - 2\bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_1) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_2) \xi^b - 2\bar{\eta}(\mathfrak{J}_3) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_2) \mathfrak{J}_1 \\ &\quad + 2\bar{\eta}(\mathfrak{J}_1) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_3) \mathfrak{J}_2 + 2\bar{\eta}(\mathfrak{J}_3) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_1) \mathfrak{J}_2 \\ &\quad + 2\bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_2) \mathfrak{g}_1(\mathfrak{J}_4, \mathfrak{J}_1) \xi^b + 3\bar{\eta}(\mathfrak{J}_1) \bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_4) \mathfrak{J}_2 \\ &\quad - 3\bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_4) \mathfrak{J}_1]. \end{aligned}$$

Taking $\mathfrak{J}_1, \mathfrak{J}_2, \mathfrak{J}_3$ and \mathfrak{J}_4 orthogonal to ξ^b , then (6.4) yields

$$(6.5) \quad \varphi^2((\tilde{\nabla}_{\mathfrak{J}_4} \tilde{\mathcal{R}})(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3) = \varphi^2((\nabla_{\mathfrak{J}_4} \mathcal{R})(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3).$$

Hence, the following theorem

Theorem 6.1. *The necessary and sufficient condition for manifold Ω_{2n+1} to be locally φ -symmetric equipped with ∇ is that it is also locally φ -symmetric endowed with $\tilde{\nabla}$.*

7. Ricci semi-symmetric hyperbolic Kenmotsu manifold admitting a connection $\tilde{\nabla}$

A contact metric manifold Ω_{2n+1} endowed with $\tilde{\nabla}$ is Ricci semi-symmetric if $(\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \cdot \tilde{\mathcal{S}}^b)(\mathfrak{J}_3, \mathfrak{J}_4) = 0$, then we have

$$(7.1) \quad \tilde{\mathcal{S}}^b(\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3, \mathfrak{J}_4) + \tilde{\mathcal{S}}^b(\mathfrak{J}_3, \tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_4) = 0.$$

Replacing \mathfrak{J}_1 by ξ^b and using (4.9), we have

$$(7.2) \quad \begin{aligned} & \frac{3}{2} \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \tilde{\mathcal{S}}^b(\xi^b, \mathfrak{J}_4) + \frac{3}{4} \bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3) \tilde{\mathcal{S}}^b(\xi^b, \mathfrak{J}_4) - \frac{3}{4} \bar{\eta}(\mathfrak{J}_3) \tilde{\mathcal{S}}^b(\mathfrak{J}_2, \mathfrak{J}_4) \\ & + \frac{3}{2} \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4) \tilde{\mathcal{S}}^b(\mathfrak{J}_3, \xi^b) + \frac{3}{4} \bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_4) \tilde{\mathcal{S}}^b(\mathfrak{J}_3, \xi^b) \\ & - \frac{3}{4} \bar{\eta}(\mathfrak{J}_4) \tilde{\mathcal{S}}^b(\mathfrak{J}_3, \mathfrak{J}_2) = 0. \end{aligned}$$

Equations (4.12) and (7.2) reduce to

$$(7.3) \quad \begin{aligned} & \frac{9n}{4} \bar{\eta}(\mathfrak{J}_4) \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) + \frac{9n}{8} \bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_4) - \frac{3}{4} \bar{\eta}(\mathfrak{J}_3) \tilde{\mathcal{S}}^b(\mathfrak{J}_2, \mathfrak{J}_4) \\ & + \frac{9n}{4} \bar{\eta}(\mathfrak{J}_3) \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4) + \frac{9n}{8} \bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3) \bar{\eta}(\mathfrak{J}_4) \\ & - \frac{3}{4} \bar{\eta}(\mathfrak{J}_4) \tilde{\mathcal{S}}^b(\mathfrak{J}_3, \mathfrak{J}_2) = 0. \end{aligned}$$

Taking $\mathfrak{J}_4 = \xi^b$ and using (4.12), we have

$$(7.4) \quad \tilde{\mathcal{S}}^b(\mathfrak{J}_2, \mathfrak{J}_3) = 3n \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) + \frac{3n}{2} \bar{\eta}(\mathfrak{J}_2) \bar{\eta}(\mathfrak{J}_3).$$

Using (4.5) in (7.4), we have

$$(7.5) \quad \mathcal{S}^b(\mathfrak{J}_2, \mathfrak{J}_3) = 2n \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3).$$

Hence, we have the following theorem

Theorem 7.1. *A Ricci semi-symmetric hyperbolic Kenmotsu manifold Ω_{2n+1} equipped with $\tilde{\nabla}$ is an η -EM.*

Now, we have

$$(7.6) \quad \begin{aligned} & (\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \cdot \tilde{\mathcal{S}}^b)(\mathfrak{J}_3, \mathfrak{J}_4) = -\tilde{\mathcal{S}}^b(\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_3, \mathfrak{J}_4) \\ & - \tilde{\mathcal{S}}^b(\mathfrak{J}_3, \tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \mathfrak{J}_4). \end{aligned}$$

Using (4.4), (4.5) in (7.6), we have

$$(\tilde{\mathcal{R}}(\mathfrak{J}_1, \mathfrak{J}_2) \cdot \tilde{\mathcal{S}}^b)(\mathfrak{J}_3, \mathfrak{J}_4) = (\mathcal{R}(\mathfrak{J}_1, \mathfrak{J}_2) \cdot \mathcal{S}^b)(\mathfrak{J}_3, \mathfrak{J}_4) - \frac{1}{2} \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_4)$$

$$\begin{aligned}
& +\frac{1}{2}\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)\mathcal{S}^b(\mathfrak{J}_2, \mathfrak{J}_4) - \frac{3}{4}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_4) \\
& +\frac{3}{4}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_3)\mathcal{S}^b(\mathfrak{J}_2, \mathfrak{J}_4) - \frac{1}{2}\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_1) \\
& +\frac{1}{2}\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_4)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_2) - \frac{3}{4}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_4)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_1) \\
& +\frac{3}{4}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_4)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_2) + \frac{3n}{2}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_4) \\
& +\frac{3n}{2}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4) - \frac{3n}{2}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_4)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \\
& -\frac{3n}{2}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_4)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3),
\end{aligned}
\tag{7.7}$$

We suppose that $\tilde{\mathcal{R}}.\tilde{\mathcal{S}}^b = \mathcal{R}.\mathcal{S}^b$, then (7.7) can be expressed as

$$\begin{aligned}
& -\frac{1}{2}\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3)\mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_4) + \frac{1}{2}\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3)\mathcal{S}^b(\mathfrak{J}_2, \mathfrak{J}_4) - \frac{3}{4}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_4) \\
& +\frac{3}{4}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_3)\mathcal{S}^b(\mathfrak{J}_2, \mathfrak{J}_4) - \frac{1}{2}\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_1) + \frac{1}{2}\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_4)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_2) \\
& -\frac{3}{4}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_4)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_1) + \frac{3}{4}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_4)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_2) + \frac{3n}{2}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_4) \\
& +\frac{3n}{2}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_3)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_4) - \frac{3n}{2}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_4)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) \\
& -\frac{3n}{2}\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_4)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) = 0.
\end{aligned}
\tag{7.8}$$

Replacing \mathfrak{J}_4 by ξ^b in the (7.8) and using (2.1), (2.2), (2.3) and (2.11), we obtain

$$\begin{aligned}
& \frac{n}{2}\bar{\eta}(\mathfrak{J}_1)\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) + \frac{5n}{2}\bar{\eta}(\mathfrak{J}_2)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_3) + \frac{1}{4}\bar{\eta}(\mathfrak{J}_2)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_1) \\
& -\frac{1}{4}\bar{\eta}(\mathfrak{J}_1)\mathcal{S}^b(\mathfrak{J}_3, \mathfrak{J}_2) + \frac{3n}{2}\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3) = 0.
\end{aligned}
\tag{7.9}$$

Putting $\mathfrak{J}_1 = \xi^b$ in (7.9), we find

$$\mathcal{S}^b(\mathfrak{J}_2, \mathfrak{J}_3) = 2n\mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) - 6n\bar{\eta}(\mathfrak{J}_2)\bar{\eta}(\mathfrak{J}_3) \Rightarrow r = 4n(n+2).
\tag{7.10}$$

Hence, we conclude the following theorem

Theorem 7.2. *A hyperbolic Kenmotsu manifold Ω_{2n+1} equipped with $\tilde{\nabla}$ satisfies $\tilde{\mathcal{R}}.\tilde{\mathcal{S}}^b - \mathcal{R}.\mathcal{S}^b = 0$, then manifold Ω_{2n+1} is an η -EM.*

Definition 7.1. A Ricci soliton $(\mathfrak{g}_1, V_b, \lambda)$ on a Riemannian manifold is defined as

$$(\mathcal{L}_{V_b}\mathfrak{g}_1)(\mathfrak{J}_1, \mathfrak{J}_2) + 2\mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_2) + 2\lambda\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) = 0,
\tag{7.11}$$

where \mathcal{L}_{V_b} is a Lie-derivative along V_b and λ is a constant. A triplet $(\mathfrak{g}_1, V_b, \lambda)$ is shrinking, steady and expanding according to $\lambda < 0$, $\lambda = 0$, $\lambda > 0$ respectively [5].

We have two situations regarding the vector field $V_b : V_b \in \text{Span}\xi^b$ and $V_b \perp \xi^b$. We investigate only the case $V_b = \xi^b$. The Ricci soliton of data $(\mathfrak{g}_1, \xi^b, \lambda)$ on manifold Ω_{2n+1} equipped with $\tilde{\nabla}$ can be defined by

$$(7.12) \quad (\tilde{\mathcal{L}}_{\xi^b} \mathfrak{g}_1)(\mathfrak{J}_1, \mathfrak{J}_2) + 2\tilde{\mathcal{S}}^b(\mathfrak{J}_1, \mathfrak{J}_2) + 2\lambda \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) = 0,$$

A straightforward calculation gives

$$(7.13) \quad (\tilde{\mathcal{L}}_{\xi^b} \mathfrak{g}_1)(\mathfrak{J}_1, \mathfrak{J}_2) = (\tilde{\nabla}_{\xi^b} \mathfrak{g}_1)(\mathfrak{J}_1, \mathfrak{J}_2) - \mathfrak{g}_1(\tilde{\nabla}_{\mathfrak{J}_1} \xi^b, \mathfrak{J}_2) - \mathfrak{g}_1(\mathfrak{J}_1, \tilde{\nabla}_{\mathfrak{J}_2} \xi^b).$$

Now using (2.1), (2.5), (3.7) and (3.8) in (7.13), we have

$$(7.14) \quad (\tilde{\mathcal{L}}_{\xi^b} \mathfrak{g}_1)(\mathfrak{J}_1, \mathfrak{J}_2) = 2[\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) + \bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_2)].$$

From (4.5), (5.9), (7.5) and (7.12), we yields

$$(7.15) \quad (1 + 3n + \lambda)\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) + (1 + \frac{3n}{2})\bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_2) = 0.$$

Taking $\mathfrak{J}_1 = \mathfrak{J}_2 = \xi^b$ in (7.15), we get

$$\lambda = -\frac{3n}{2} < 0.$$

Thus, we state the following theorem

Theorem 7.3. *A triplet $(\mathfrak{g}_1, \xi^b, \lambda)$ on manifold Ω_{2n+1} endowed with $\tilde{\nabla}$ is always shrinking.*

8. Example of hyperbolic Kenmotsu Manifold

Example 8.1. Let $\Omega_3 = (x, y, z) \in R^3 : z \neq 0$ be a 3-dimensional manifold with the standard coordinates (x, y, z) of R^3 [20]. Let $\varsigma_1 = e^z \frac{\partial}{\partial x}$, $\varsigma_2 = e^z \frac{\partial}{\partial y}$, $\varsigma_3 = \frac{\partial}{\partial z} = \xi^b$ be linear independent vector fields.

Suppose \mathfrak{g}_1 be the Ω_3 Riemannian metric specified by

$$(8.1) \quad \begin{aligned} \mathfrak{g}_1(\varsigma_1, \varsigma_2) &= \mathfrak{g}_1(\varsigma_2, \varsigma_3) = \mathfrak{g}_1(\varsigma_3, \varsigma_1) = 0, \\ \mathfrak{g}_1(\varsigma_1, \varsigma_1) &= 1, \quad \mathfrak{g}_1(\varsigma_2, \varsigma_2) = \mathfrak{g}_1(\varsigma_3, \varsigma_3) = -1, \end{aligned}$$

where

$$\mathfrak{g}_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

and φ is $(1, 1)$ -tensor field defined by

$$(8.2) \quad \varphi(\varsigma_1) = \varsigma_2, \varphi(\varsigma_2) = \varsigma_1, \varphi(\varsigma_3) = 0.$$

By using linearity of φ and \mathfrak{g}_1 , we have

$$(8.3) \quad \begin{aligned} \bar{\eta}(\zeta_3) &= -1, \quad \varphi^2 \mathfrak{J}_1 = \mathfrak{J}_1 + \bar{\eta}(\mathfrak{J}_1)\zeta_3, \\ \mathfrak{g}_1(\varphi \mathfrak{J}_1, \varphi \mathfrak{J}_2) &= -\mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) - \bar{\eta}(\mathfrak{J}_1)\bar{\eta}(\mathfrak{J}_2) \end{aligned}$$

Here $\bar{\eta}(\mathfrak{J}_1) = \mathfrak{g}_1(\mathfrak{J}_1, \zeta_3)$ defines a 1-form on Ω_3 . Hence for $\xi^b = \zeta_3$, the structure $(\varphi, \xi^b, \bar{\eta}, \mathfrak{g}_1)$ defined on Ω_3 . By applying definition $[\mathfrak{J}_1, \mathfrak{J}_2] = \mathfrak{J}_1(\mathfrak{J}_2 f) - \mathfrak{J}_2(\mathfrak{J}_1 f)$, the Lie bracket can be computed

$$(8.4) \quad \begin{aligned} [\zeta_1, \zeta_1] &= 0, \quad [\zeta_1, \zeta_2] = 0, \quad [\zeta_1, \zeta_3] = -\zeta_1, \\ [\zeta_2, \zeta_1] &= 0, \quad [\zeta_2, \zeta_2] = 0, \quad [\zeta_2, \zeta_3] = -\zeta_2, \\ [\zeta_3, \zeta_1] &= \zeta_1, \quad [\zeta_3, \zeta_2] = \zeta_2, \quad [\zeta_3, \zeta_3] = 0. \end{aligned}$$

Koszul's formula is given as

$$(8.5) \quad \begin{aligned} 2\mathfrak{g}_1(\nabla_{\mathfrak{J}_1} \mathfrak{J}_2, \mathfrak{J}_3) &= \mathfrak{J}_1 \mathfrak{g}_1(\mathfrak{J}_2, \mathfrak{J}_3) + \mathfrak{J}_2 \mathfrak{g}_1(\mathfrak{J}_3, \mathfrak{J}_1) - \mathfrak{J}_3 \mathfrak{g}_1(\mathfrak{J}_1, \mathfrak{J}_2) \\ &+ \mathfrak{g}_1([\mathfrak{J}_1, \mathfrak{J}_2], \mathfrak{J}_3) - \mathfrak{g}_1([\mathfrak{J}_2, \mathfrak{J}_3], \mathfrak{J}_1) + \mathfrak{g}_1([\mathfrak{J}_3, \mathfrak{J}_1], \mathfrak{J}_2). \end{aligned}$$

Now utilizing the above equation, we can compute

$$(8.6) \quad \begin{aligned} \nabla_{\zeta_1} \zeta_1 &= -\zeta_3, \quad \nabla_{\zeta_1} \zeta_2 = 0, \quad \nabla_{\zeta_1} \zeta_3 = -\zeta_1, \\ \nabla_{\zeta_2} \zeta_1 &= 0, \quad \nabla_{\zeta_2} \zeta_2 = \zeta_3, \quad \nabla_{\zeta_2} \zeta_3 = -\zeta_2, \\ \nabla_{\zeta_3} \zeta_1 &= 0, \quad \nabla_{\zeta_3} \zeta_2 = 0, \quad \nabla_{\zeta_3} \zeta_3 = 0. \end{aligned}$$

Also $\mathfrak{J}_1 = \mathfrak{J}_1^1 \zeta_1 + \mathfrak{J}_1^2 \zeta_2 + \mathfrak{J}_1^3 \zeta_3$ and $\xi^b = \zeta_3$, then we have

$$(8.7) \quad \begin{aligned} \nabla_{\mathfrak{J}_1} \xi^b &= \nabla_{\mathfrak{J}_1^1 \zeta_1 + \mathfrak{J}_1^2 \zeta_2 + \mathfrak{J}_1^3 \zeta_3} \zeta_3 \\ &= \mathfrak{J}_1^1 \nabla_{\zeta_1} \zeta_3 + \mathfrak{J}_1^2 \nabla_{\zeta_2} \zeta_3 + \mathfrak{J}_1^3 \nabla_{\zeta_3} \zeta_3 \\ &= -\mathfrak{J}_1^1 \zeta_1 - \mathfrak{J}_1^2 \zeta_2 \end{aligned}$$

and

$$(8.8) \quad \begin{aligned} -\mathfrak{J}_1 - \bar{\eta}(\mathfrak{J}_1)\xi^b &= -(\mathfrak{J}_1^1 \zeta_1 + \mathfrak{J}_1^2 \zeta_2 + \mathfrak{J}_1^3 \zeta_3) - \mathfrak{g}_1(\mathfrak{J}_1^1 \zeta_1 + \mathfrak{J}_1^2 \zeta_2 + \mathfrak{J}_1^3 \zeta_3, \zeta_3) \zeta_3 \\ &= -\mathfrak{J}_1^1 \zeta_1 - \mathfrak{J}_1^2 \zeta_2 - \mathfrak{J}_1^3 \zeta_3 + \mathfrak{J}_1^3 \zeta_3 \\ &= -\mathfrak{J}_1^1 \zeta_1 - \mathfrak{J}_1^2 \zeta_2, \end{aligned}$$

where $\mathfrak{J}_1^1, \mathfrak{J}_1^2, \mathfrak{J}_1^3$ are scalars. From (8.7) and (8.8), the structure $(\varphi, \xi^b, \bar{\eta}, \mathfrak{g}_1)$ is hyperbolic Kenmotsu structure. Therefore $\Omega_3(\varphi, \xi^b, \bar{\eta}, \mathfrak{g}_1)$ is hyperbolic Kenmotsu

manifold. In reference of (2.1), (2.3), (3.1) and (8.6), we get

$$\begin{aligned}
 \tilde{\nabla}_{\varsigma_1} \varsigma_1 &= -\varsigma_3, & \tilde{\nabla}_{\varsigma_1} \varsigma_2 &= 0, & \tilde{\nabla}_{\varsigma_1} \varsigma_3 &= -\frac{3}{2}\varsigma_1, \\
 \tilde{\nabla}_{\varsigma_2} \varsigma_1 &= 0, & \tilde{\nabla}_{\varsigma_2} \varsigma_2 &= \varsigma_3, & \tilde{\nabla}_{\varsigma_2} \varsigma_3 &= -\frac{3}{2}\varsigma_2, \\
 \tilde{\nabla}_{\varsigma_3} \varsigma_1 &= \frac{1}{2}\varsigma_1, & \tilde{\nabla}_{\varsigma_3} \varsigma_2 &= \frac{1}{2}\varsigma_2, & \tilde{\nabla}_{\varsigma_3} \varsigma_3 &= 0.
 \end{aligned}
 \tag{8.9}$$

From (3.2) and (3.3), we yields

$$\tilde{\mathcal{T}}(\varsigma_1, \varsigma_3) = \tilde{\eta}(\varsigma_3)\varsigma_1 - \tilde{\eta}(\varsigma_1)\varsigma_3 = -\varsigma_1 \neq 0$$

and

$$\begin{aligned}
 (\tilde{\nabla}_{\varsigma_1} \mathfrak{g}_1)(\varsigma_1, \varsigma_3) &= \frac{1}{2} [2\tilde{\eta}(\varsigma_1)\mathfrak{g}_1(\varsigma_1, \varsigma_3) - \tilde{\eta}(\varsigma_1)\mathfrak{g}_1(\varsigma_1, \varsigma_3) - \tilde{\eta}(\varsigma_3)\mathfrak{g}_1(\varsigma_1, \varsigma_1)] \\
 &= \frac{1}{2} \neq 0.
 \end{aligned}$$

Consequently, a new type of semi-symmetric non-metric connection defined in (3.1). Also,

$$\begin{aligned}
 \tilde{\nabla}_{\mathfrak{J}_1} \xi^b &= \tilde{\nabla}_{\mathfrak{J}_1^1 \varsigma_1 + \mathfrak{J}_1^2 \varsigma_2 + \mathfrak{J}_1^3 \varsigma_3} \\
 &= \mathfrak{J}_1^1 \tilde{\nabla}_{\varsigma_1} \varsigma_3 + \mathfrak{J}_1^2 \tilde{\nabla}_{\varsigma_2} \varsigma_3 + \mathfrak{J}_1^3 \tilde{\nabla}_{\varsigma_3} \varsigma_3 \\
 &= -\frac{3}{2}\mathfrak{J}_1^1 \varsigma_1 - \frac{3}{2}\mathfrak{J}_1^2 \varsigma_2,
 \end{aligned}
 \tag{8.10}$$

Equation (3.7) can be verified by using (8.7) and (8.10).

The components of \mathcal{R} with connection ∇ are given as

$$\begin{aligned}
 \mathcal{R}(\varsigma_1, \varsigma_2) \varsigma_1 &= -\varsigma_2, & \mathcal{R}(\varsigma_1, \varsigma_3) \varsigma_1 &= -\varsigma_3, & \mathcal{R}(\varsigma_2, \varsigma_3) \varsigma_1 &= 0, \\
 \mathcal{R}(\varsigma_1, \varsigma_2) \varsigma_2 &= -\varsigma_1, & \mathcal{R}(\varsigma_1, \varsigma_3) \varsigma_2 &= 0, & \mathcal{R}(\varsigma_2, \varsigma_3) \varsigma_2 &= \varsigma_3, \\
 \mathcal{R}(\varsigma_1, \varsigma_2) \varsigma_3 &= 0, & \mathcal{R}(\varsigma_1, \varsigma_3) \varsigma_3 &= -\varsigma_1, & \mathcal{R}(\varsigma_2, \varsigma_3) \varsigma_3 &= -\varsigma_2,
 \end{aligned}
 \tag{8.11}$$

also $\mathcal{R}(\varsigma_i, \varsigma_i) \varsigma_i = 0; i = 1, 2, 3$ from simple calculations. We can verify (2.7), (2.8), (2.9), (2.10) and (2.11).

Similarly, the component of $\tilde{\mathcal{R}}$ endowed with connection $\tilde{\nabla}$ are as under:

$$\begin{aligned} \tilde{\mathcal{R}}(\varsigma_1, \varsigma_2)\varsigma_1 &= -\frac{3}{2}\varsigma_2, & \tilde{\mathcal{R}}(\varsigma_1, \varsigma_3)\varsigma_1 &= -\frac{3}{2}\varsigma_3, & \tilde{\mathcal{R}}(\varsigma_2, \varsigma_3)\varsigma_1 &= 0, \\ (8.12) \quad \tilde{\mathcal{R}}(\varsigma_1, \varsigma_2)\varsigma_2 &= -\frac{3}{2}\varsigma_1, & \tilde{\mathcal{R}}(\varsigma_1, \varsigma_3)\varsigma_2 &= 0, & \tilde{\mathcal{R}}(\varsigma_2, \varsigma_3)\varsigma_2 &= \frac{3}{2}\varsigma_3, \\ \tilde{\mathcal{R}}(\varsigma_1, \varsigma_2)\varsigma_3 &= 0, & \tilde{\mathcal{R}}(\varsigma_1, \varsigma_3)\varsigma_3 &= -\frac{3}{4}\varsigma_1, & \tilde{\mathcal{R}}(\varsigma_2, \varsigma_3)\varsigma_3 &= -\frac{3}{4}\varsigma_2, \end{aligned}$$

along with $\tilde{\mathcal{R}}(\varsigma_i, \varsigma_i)\varsigma_i = 0; i = 1, 2, 3$. Thus, we can verify (4.4), (4.8), (4.9), (4.10) and (4.11).

The Ricci tensor $\mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_2)$ of connection ∇ can be derived by using (8.11) in $\mathcal{S}^b(\mathfrak{J}_1, \mathfrak{J}_2) = \sum_{i=1}^3 \mathfrak{g}_1(\mathcal{R}(e_i, \mathfrak{J}_1)\mathfrak{J}_2, e_i)$. As follows:

$$(8.13) \quad \mathcal{S}^b(\varsigma_1, \varsigma_1) = 2, \quad \mathcal{S}^b(\varsigma_2, \varsigma_2) = -2, \quad \mathcal{S}^b(\varsigma_3, \varsigma_3) = -2.$$

The Ricci tensor $\tilde{\mathcal{S}}^b(\mathfrak{J}_1, \mathfrak{J}_2)$ endowed with $\tilde{\nabla}$ can be derived by using (8.12) in $\tilde{\mathcal{S}}^b(\mathfrak{J}_1, \mathfrak{J}_2) = \sum_{i=1}^3 \mathfrak{g}_1(\tilde{\mathcal{R}}(e_i, \mathfrak{J}_1)\mathfrak{J}_2, e_i)$. It is as follows:

$$(8.14) \quad \tilde{\mathcal{S}}^b(\varsigma_1, \varsigma_1) = 3, \quad \tilde{\mathcal{S}}^b(\varsigma_2, \varsigma_2) = -3, \quad \tilde{\mathcal{S}}^b(\varsigma_3, \varsigma_3) = -\frac{3}{2}.$$

In view of (8.13) and (8.14), the scalar curvature can be calculated as under:

$$\begin{aligned} \tau &= \sum_{i=1}^3 \mathcal{S}^b(e_i, e_i) = \mathcal{S}^b(\varsigma_1, \varsigma_1) - \mathcal{S}^b(\varsigma_2, \varsigma_2) - \mathcal{S}^b(\varsigma_3, \varsigma_3) = 6, \\ \tilde{\tau} &= \sum_{i=1}^3 \tilde{\mathcal{S}}^b(e_i, e_i) = \tilde{\mathcal{S}}^b(\varsigma_1, \varsigma_1) - \tilde{\mathcal{S}}^b(\varsigma_2, \varsigma_2) - \tilde{\mathcal{S}}^b(\varsigma_3, \varsigma_3) = \frac{15}{2}. \end{aligned}$$

Therefore, we can say that the example I provided completely correspond to our investigations.

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