# SEMI GENERALIZED $\varphi$ -RECURRENT TRANS-SASAKIAN MANIFOLDS

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**Abstract.** In this paper we studied semi generalized  $\varphi$ -recurrent and concircular  $\varphi$ -recurrent Trans-Sasakian manifolds.

keywords: Trans-Sasakian manifold, semi generalized  $\varphi$ -recurrent,  $\eta$ -Einstein,  $\eta$ -parallel, constant curvature.

#### 1. Introduction

In 1985, Oubina [3] introduced a class of almost contact metric manifolds known as trans-Sasakian manifolds. This class contains  $\alpha$ -Sasakian,  $\beta$ -Kenmotsu and cosymplectic manifolds. An almost contact metric structure on a manifold M is called a trans-Sasakian structure if the product manifold  $M \times R$  belongs to the class  $W_4$ , a class of Hermitian manifolds which are closely related to a locally conformal Kähler manifolds. Trans-Sasakian manifolds were studied extensively by Marrero [10], Tripathi [12], De et al.([5], [7], [8]) and others. Tripathi [12] proved that trans-Sasakian manifolds are always generalized quasi-Sasakian. De et al. and Bagewadi et al.([4], [1]) have obtained results on the conservativeness of Projective, Pseudo projective, Conformal concircular, Quasi conformal curvature tensors on k-contact,Kenmotsu and trans-Sasakian manifolds. De et al. [5] generalized the notion of locally  $\varphi$ -symmetric and introduced the notion of  $\varphi$ -recurrent Sasakian manifolds. The author Nagaraja [11] introduced the notion of  $\varphi$ -recurrent trans-Sasakian manifolds. In the present paper we study generalized  $\varphi$ -recurrent and concircular  $\varphi$ -recurrent Trans-Sasakian manifolds.

#### 2. Preliminaries

Let M be a n dimensional almost contact metric manifold [6] with an almost contact metric structure  $(\varphi, \xi, \eta, g)$  where  $\varphi, \xi, \eta$  are tensor fields on M of types (1,1),(1,0),

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(0,1) respectively and g is the Riemannian metric on M such that

(2.1) 
$$\varphi^2 = -I + \eta \otimes \xi, \quad \eta(\xi) = 1, \quad \varphi(\xi) = 0, \quad \eta \circ \varphi = 0.$$

The Riemannian metric g on M satisfies the condition

(2.2) 
$$g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y),$$

(2.3) 
$$g(X, \varphi Y) = -g(\varphi X, Y), \quad g(X, \xi) = \eta(X),$$

for all  $X, Y \in TM$ . An almost contact metric structure  $(\varphi, \xi, \eta, g)$  in M is called a trans-Sasakian structure [2] if the product manifold  $(M \times R, J, G)$  belongs to the class  $W_4$  where J is the complex structure on  $(M \times R)$  defined by

(2.4) 
$$J(X, \lambda \frac{d}{dt}) = (\varphi X - \lambda \xi, \eta(X) \frac{d}{dt}),$$

for all vector fields X on M and smooth functions  $\lambda$  on  $(M \times R)$  and G is the product metric on  $(M \times R)$ . This may be expressed by the following condition [7]

$$(2.5) \quad (\nabla_X \varphi)(Y) = \alpha(g(X, Y)\xi - \eta(Y)X) + \beta(g(\varphi X, Y)\xi - \eta(Y)\varphi X),$$

where  $\alpha$  and  $\beta$  are smooth functions on M. From (2.5), we have

(2.6) 
$$\nabla_X \xi = -\alpha(\varphi X) + \beta(X, \eta(X)\xi)$$

and

(2.7) 
$$(\nabla_X \eta)(Y) = -\alpha q(\varphi X, Y) + \beta(\varphi X, \varphi Y).$$

In an n-dimensional trans-Sasakian manifold, from (2.5) (2.6) (2.7), we can derive [7]

$$R(X,Y)\xi = (\alpha^2 - \beta^2)(\eta(Y)X - \eta(X)Y)$$

$$+ 2\alpha\beta(\eta(Y)\varphi X - \eta(X)\varphi Y) - (X\alpha)\varphi Y$$

$$+ (Y\alpha)\varphi X - (X\beta)\varphi^2 Y + (Y\beta)\varphi^2 X,$$

(2.9) 
$$S(X,\xi) = \{(n-1)(\alpha^2 - \beta^2) - \xi\beta\} \eta(X) - (n-2)(X\beta) - (\varphi X)\alpha$$

and

(2.10) 
$$Q\xi = \{(n-1)(\alpha^2 - \beta^2) - \xi\beta\}\xi - (n-2)grad\beta + \varphi(grad\alpha),$$

where R is the curvature tensor, S is the Ricci-tensor and r is the scalar curvature. Also

$$(2.11) g(QX,Y) = S(X,Y),$$

where Q being the symmetric endomorphism of the tangent space at each point corresponding to the Ricci-tensor S.

When

(2.12) 
$$\varphi(grad\alpha) = (n-2)grad\beta,$$

then (2.9) and (2.10) reduces to

(2.13) 
$$S(X,\xi) = (n-1)(\alpha^2 - \beta^2)\eta(X),$$

and

(2.14) 
$$Q\xi = (n-1)(\alpha^2 - \beta^2)\xi.$$

A Sasakian manifold is said to be a  $\varphi$ -recurrent manifold if there exists a non zero 1-form A such that

(2.15) 
$$\varphi^2((\nabla_W R)(X, Y)Z) = A(X)R(Y, Z)W$$

for all vector fields X, Y, Z, W orthogonal to  $\xi$ . Further we have

$$(2.16) 2\alpha\beta + \xi\alpha = 0.$$

## 3. Semi-generalized $\varphi$ -recurrent trans Sasakian Manifolds

**Definition 3.1.** A trans-Sasakian manifold  $(M^n, g)$  is called semi-generalized  $\varphi$ -recurrent if its curvature tensor R satisfies the condition

(3.1) 
$$\varphi^2\bigg((\nabla_W R)(X,Y)Z\bigg) = A(W)R(X,Y)Z + B(W)g(Y,Z)X,$$

for all  $X,Y,Z,W\in TM,$  where A and B are two 1-forms, B is non zero and these are defined by

(3.2) 
$$A(W) = q(W, \rho_1), \quad B(W) = q(W, \rho_2),$$

where  $\rho_1$ ,  $\rho_2$  being the vector fields associated to the 1-form A, B respectively.

**Theorem 3.1.** A semi-generalized  $\varphi$ -recurrent trans-Sasakian manifold  $(M^n,g)$  satisfying  $\varphi(grad\alpha) = (n-2)grad\beta$ , is an Einstein manifold and more over the 1-forms A and B are related as

$$(n-1)(\alpha^2 - \beta^2)A(W) + nB(W) = 0.$$

**Proof:** Let us consider a semi-generalized  $\varphi$ -recurrent trans-Sasakian manifold. Then by virtue of (2.1) and (3.1) we have

$$(3.3) \qquad - (\nabla_W R)(X,Y)Z + \eta((\nabla_W R)(X,Y)Z)\xi$$
$$= A(W)R(X,Y)Z + B(W)g(Y,Z)X,$$

from which we get

$$- g((\nabla_W R)(X, Y)Z, U) + \eta((\nabla_W R)(X, Y)Z)\eta(U)$$

$$= A(W)R(X, Y, Z, U) + B(W)g(Y, Z)g(X, U).$$
(3.4)

Let  $\{e_i\}$ ,  $i=1,2,\ldots,n$  be an orthonormal basis of the tangent space at any point of the manifold. Then putting  $X=U=e_i$  in (3.4) and taking summation over  $i, 1 \leq i \leq n$ , we get

$$(3.5) \qquad -(\nabla_W S)(Y,Z) + \sum_{i=1}^n \eta((\nabla_W R)(e_i,Y)Z)\eta(e_i)$$

$$= A(W)S(Y,Z) + nB(W)g(Y,Z).$$

The second term of (3.5) by putting  $Z = \xi$  takes the form  $g((\nabla_W R)(e_i, Y)\xi, e_i)$ . Consider

$$g((\nabla_W R)(e_i, Y)\xi, \xi) = g(\nabla_W R(e_i, Y)\xi, \xi) - g(R(\nabla_W e_i, Y)\xi, \xi)$$

$$- g(R(e_i, \nabla_W Y)\xi, \xi) - g(R(e_i, Y)\nabla_W \xi, \xi)$$
(3.6)

at  $p \in M$ . Since  $\{e_i\}$  is an orthonormal basis, so  $\nabla_X e_i = 0$  at p. Using (2.1), (2.3) and (2.8), we have

$$g(R(e_{i}, \nabla_{W}Y)\xi, \xi) = g\left((\alpha^{2} - \beta^{2})(\eta(\nabla_{W}Y)e_{i} - \eta(e_{i})(\nabla_{W}Y))\right)$$

$$+ 2\alpha\beta(\eta(\nabla_{W}Y)\varphi e_{i} - \eta(e_{i})\varphi(\nabla_{W}Y))$$

$$+ (\nabla_{W}Y\alpha)\varphi e_{i} - (e_{i}\alpha)\varphi(\nabla_{W}Y)$$

$$+ (\nabla_{W}Y\beta)\varphi^{2}e_{i} - (e_{i}\beta)\varphi^{2}(\nabla_{W}Y), \xi\right)$$

$$= 0.$$

$$(3.7)$$

Using (3.7) in (3.6), we obtain

$$(3.8) \quad q((\nabla_W R)(e_i, Y)\xi, \xi) = q(\nabla_W R(e_i, Y)\xi, \xi) - q(R(e_i, Y)\nabla_W \xi, \xi).$$

Since  $(\nabla_W g) = 0$ , we have

$$g(\nabla_W R(e_i, Y)\xi, \xi) + g(R(e_i, Y)\xi, \nabla_W \xi) = 0,$$

which implies

$$(3.9) \quad g(\nabla_W R(e_i, Y)\xi, \xi) = -g(R(e_i, Y)\xi, \nabla_W \xi) - g(R(e_i, Y)\nabla_W \xi, \xi).$$

Using (2.6) in (3.9), we get

$$g((\nabla_{W}R)(e_{i},Y)\xi,\xi) = -g\left(R(e_{i},Y)\xi, -\alpha\varphi W + \beta(W-\eta(W)\xi)\right)$$

$$- g\left(R(e_{i},Y)(-\alpha\varphi W + \beta(W-\eta(W)\xi)),\xi\right)$$

$$= \alpha g(R(e_{i},Y)\xi,\varphi W) - \beta g(R(e_{i},Y)\xi,W)$$

$$+ \beta \eta(W)g(R(e_{i},Y)\xi,\xi) + \alpha g(R(e_{i},Y)\varphi W,\xi)$$

$$- \beta g(R(e_{i},Y)W,\xi) + \beta \eta(W)g(R(e_{i},Y)\xi,\xi)$$

$$= 0.$$
(3.10)

Replacing Z by  $\xi$  in (3.5) and using (2.3),(2.13) and (3.10) we have

$$(3.11) \qquad (\nabla_W S)(Y, \xi) = -\left[ (n-1)(\alpha^2 - \beta^2)A(W) + nB(W) \right] \eta(Y).$$

Now, we have

$$(\nabla_W S)(Y,\xi) = \nabla_W S(Y,\xi) - S(\nabla_W Y,\xi) - S(Y,\nabla_W \xi).$$

Using (2.6) and (2.13) in the above relation, it follows that

$$(\nabla_W S)(Y,\xi) = (n-1)(\alpha^2 - \beta^2)[-\alpha g(\varphi W, Y) + \beta g(\varphi Y, \varphi W)]$$

$$+\alpha S(Y,\varphi W) - S(Y,\beta W) + (n-1)\beta(\alpha^2 - \beta^2)\eta(Y)\eta(W).$$

By virtue of (2.2), we obtain from (3.12) that

$$(\nabla_W S)(Y,\xi) = (n-1)(\alpha^2 - \beta^2)[-\alpha g(Y,\varphi W) + \beta g(Y,W)]$$

$$+ \alpha S(Y,\varphi W) - \beta S(Y,W).$$

From (3.11) and (3.13), we have

$$(n-1)(\alpha^2 - \beta^2)[-\alpha g(Y, \varphi W) + \beta g(Y, W)] + \alpha S(Y, \varphi W)$$

$$- \beta S(Y, W) = -\left[(n-1)(\alpha^2 - \beta^2)A(W) + nB(W)\right]\eta(Y).$$

Replacing  $Y = \xi$  in (3.14) then using (2.1), (2.3), (2.12) and (2.13) we get

$$(3.15) (n-1)(\alpha^2 - \beta^2)A(W) + nB(W) = 0.$$

Again replacing Y and W by  $\varphi Y$  and  $\varphi W$  respectively in (3.14) and then using (2.1), (2.3), (2.11), (2.12) and (2.14), we obtain

(3.16) 
$$S(Y,W) = (n-1)(\alpha^2 - \beta^2)g(Y,W)$$

and

$$S(\varphi Y, W) = (n-1)(\alpha^2 - \beta^2)q(\varphi Y, W).$$

Which proves the theorem.

#### 4. Semi-generalized concircular $\varphi$ -recurrent trans-Sasakian Manifolds

**Definition 4.1.** A trans-Sasakian manifold is said to be concircular  $\varphi$ -recurrent manifold if there exists a non zero 1-form A such that

(4.1) 
$$\varphi^2((\nabla_W C)(X,Y)Z) = A(W)C(X,Y)Z,$$

for arbitrary vector fields X,Y,Z,W where C is a concircular curvature tensor given by

(4.2) 
$$C(X,Y)Z = R(X,Y)Z - \frac{r}{n(n-1)}[g(Y,Z)X - g(X,Z)Y],$$

where R is the curvature tensor and r is the scalar curvature.

**Definition 4.2.** A trans-Sasakian manifold is called a semi-generalized concircular  $\varphi$ -recurrent if its concircular curvature tensor C defined in (4.2) satisfies the condition

(4.3) 
$$\varphi^{2}(\nabla_{W}C)(X,Y,Z) = A(W)C(X,Y,Z) + B(W)g(Y,Z)X,$$

where A and B are defined as (3.2).

**Theorem 4.1.** Let  $(M^n, g)$  be a semi-generalized concircular  $\varphi$ -recurrent trans-Sasakian manifold then

$$[(n-1)(\alpha^{2} - \beta^{2}) - \frac{r}{n}]A(W) + nB(W) = 0.$$

### Proof:

Let  $(M^n, g)$  be a semi-generalized concircular  $\varphi$ -recurrent trans-Sasakian manifold. Then by virtue of (2.1) and (4.3), we have

(4.4) 
$$(\nabla_W C)(X, Y, Z) + \eta(\nabla_W C)(X, Y, Z))\xi$$
$$= A(W)C(X, Y, Z) + B(W)g(Y, Z)X,$$

from which it follows that

$$- g((\nabla_W C)(X, Y, Z), U) + \eta((\nabla_W C)(X, Y, Z))\eta(U)$$

$$= A(W)g(C(X, Y, Z), U) + B(W)g(Y, Z)g(X, U).$$

Let  $\{e_i\}, i = 1, 2, ..., n$  be orthonormal basis of the tangent space at any point of the manifold. Then putting  $Y = Z = e_i$  in (4.5) and taking summation over i,  $1 \le i \le n$ , we get

$$-(\nabla_W S)(X,U) + \frac{W(r)}{n}g(X,U) + (\nabla_W S)(X,\xi)\eta(U)$$
$$-\frac{W(r)}{n}\eta(X)\eta(U) = A(W)\left[S(X,U) - \frac{r}{n}g(X,U)\right]$$
$$+nB(W)g(X,U).$$

Replacing U by  $\xi$  in (4.6) and using (2.1) and (2.13), we get

(4.7) 
$$A(W) \left[ (n-1)(\alpha^2 - \beta^2) - \frac{r}{n} \right] \eta(X) + nB(W)\eta(X) = 0.$$

Putting  $X = \xi$  in (4.7), we have

(4.8) 
$$\left[ (n-1)(\alpha^2 - \beta^2) - \frac{r}{n} \right] A(W) + nB(W) = 0.$$

This completes the proof.

**Theorem 4.2.** A semi-generalized concircular  $\varphi$ -recurrent trans-Sasakian manifold is an Einstein manifold, provided  $\alpha$  and  $\beta$  are constants.

**Proof**: Putting  $X = U = e_i$  in (4.5) and taking summation over  $i, 1 \le i \le n$ , we get

$$(\nabla_{W}S)(Y,Z) = -\sum_{i=1}^{n} g((\nabla_{W}R)(e_{i},Y,Z),\xi)g(e_{i},\xi)$$

$$-\frac{W(r)}{n}g(Y,Z) + \frac{W(r)}{n(n-1)} \left[g(Y,Z) - \eta(Y)\eta(Z)\right]$$

$$+ A(W)\left[S(Y,Z) - \frac{r}{n}g(Y,Z)\right] + nB(W)g(Y,Z).$$
(4.9)

Replacing Z by  $\xi$  in (4.9) and using (4.7), we have

(4.10) 
$$(\nabla_W S)(Y,\xi) = \frac{W(r)}{n} \eta(Y).$$

Now, we have

$$(4.11) \qquad (\nabla_W S)(Y,\xi) = \nabla_W S(Y,\xi) - S(\nabla_W Y,\xi) - S(Y,\nabla_W \xi).$$

Using (2.6) and (2.9) in the above relation, it follows that

$$(\nabla_W S)(Y,\xi) = (n-1)(\alpha^2 - \beta^2)[-\alpha g(\varphi W, Y) + \beta g(W, Y)]$$

$$+ \alpha S(Y, \varphi W) - \beta S(Y, W).$$

In view of (4.10) and (4.12)

$$(n-1)(\alpha^2 - \beta^2)[-\alpha g(\varphi W, Y) + \beta g(W, Y)]$$

$$+ \alpha S(Y, \varphi W) - \beta S(Y, W) = \frac{W(r)}{n} \eta(Y).$$

Replacing Y by  $\varphi Y$  in (4.13) and using (2.2), we get

$$(4.14) - \alpha S(\varphi Y, \varphi W) + \beta S(\varphi Y, W)$$

$$= (n-1)(\alpha^2 - \beta^2)[\beta g(W, \varphi Y) - \alpha g(\varphi W, \varphi Y)].$$

Interchanging Y by W in (4.14) and by using the skew symmetry of  $\varphi$ , we obtain

(4.15) 
$$\alpha S(\varphi W, \varphi Y) = (n-1)\alpha(\alpha^2 - \beta^2)g(\varphi W, \varphi Y).$$

By skew symmetry of  $\varphi$  and using (2.9), we obtain

$$S(\varphi W, \varphi Y) = S(\varphi^2 W, Y)$$
  
=  $S(W, Y) - (n-1)(\alpha^2 - \beta^2)\eta(W)\eta(Y).$ 

Substituting this in (4.15), we get

(4.16) 
$$S(W,Y) = (n-1)(\alpha^2 - \beta^2)g(W,Y).$$

i.e M is an Einstein manifold. Hence the theorem is verified.

#### 5. Conclusion

This paper is all about the study of geometrical properties of a semi-generalized  $\phi$ -recurrent trans-Sasakian manifold. We prove that a semi-generalized  $\phi$ -recurrent trans-Sasakian manifold is an Einstein manifold. It is proved that a semi-generalized concircular  $\phi$ -recurrent trans-Sasakian manifold is also an Einstein manifold.

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