

AW(k)-TYPE CURVES ACCORDING TO PARALLEL TRANSPORT
FRAME IN EUCLIDEAN SPACE \mathbb{E}^4

İlim Kişi, Sezgin Büyükkütük, Deepmala¹ and Günay Öztürk

Abstract. In this paper, we study AW(k)-type ($k = 1, 2, \dots, 7$) curves according to the parallel transport frame in Euclidean space \mathbb{E}^4 . We give the classification of these types curves with the parallel transport curvatures (Bishop curvatures). Finally, we consider the curvatures k_1, k_2, k_3 as constants respectively and give the relations between the parallel transport curvatures of AW(k)-type ($k = 1, 2, \dots, 7$) curves.

Keywords: AW(k)-type curves, Parallel transport frame

1. Introduction

The Frenet frame can be constructed for a 3–time continuously differentiable curve. But, for some points the second derivative may vanish. Namely, the curvature may be zero. In this case, we must use a new frame in \mathbb{E}^3 . Because of that, in [6], Bishop established a new frame named ‘Bishop frame’. This frame is well defined even though the curve’s second derivative vanishes. In [6, 8], the authors gave the positive features of the Bishop frame and the comparison of Frenet frame with the Bishop frame in Euclidean 3–space. In Euclidean 4–space \mathbb{E}^4 , we have the same problem for a curve like being in Euclidean 3–space. That is, one of the $i - th$ ($1 < i < 4$) derivative of the curve may vanish. In this case, we must use a new frame.

In [7], using the similar idea authors considered such curves and constructed an alternative frame. They gave parallel transport frame of a curve, and they introduced the relationship between the Frenet frame and the parallel transport frame of the curve in \mathbb{E}^4 . They generalized the relation to Euclidean space \mathbb{E}^4 .

In [2], Arslan and West defined submanifolds of AW(k)-type. Especially, several authors have done many works related the curves of AW(k)-type. For instance, in [3], the authors obtained curvature conditions and characterized these curves in \mathbb{E}^n . In [9], AW(k) ($k = 1, 2$ or 3)-type curves and surfaces were discussed. Further,

Received April 04., 2016.; Accepted June 27., 2016.

2010 *Mathematics Subject Classification.* Primary 53A04; Secondary 53C40

¹Corresponding author.

associated examples about curves and surfaces which satisfy $AW(k)$ -type conditions were given.

In [10], the authors considered $AW(k)$ -type curves in accordance with Bishop Frame in \mathbb{E}^3 . Also, they mentioned the relationship between Bishop curvatures (k_1, k_2) for these type curves in \mathbb{E}^3 .

Furthermore, in [1], the authors considered a generalization of $AW(k)$ -type ($k = 1, 2, \dots, 7$) curves in Euclidean n -space \mathbb{E}^n . They obtained the curvature conditions for these curves. In [4], the authors characterized curves in Galilean 3-space. In [5], the authors gave a short and understandable exposition on differential operators over modules and rings as a path to the generalized differential geometry. Also in [11], the authors studied projectively flatness of a new class of (α, β) -metrics.

In this paper, we study $AW(k)$ -type ($k = 1, 2, \dots, 7$) curves according to the parallel transport frame in Euclidean space \mathbb{E}^4 . We give the classification of these types curves with the parallel transport curvatures (Bishop curvatures). Finally, we consider the curvatures k_1, k_2, k_3 as constants respectively and give the relations between the parallel transport curvatures of $AW(k)$ -type ($k = 1, 2, \dots, 7$) curves.

2. Basic Concepts

Let $\gamma = \gamma(s) : I \rightarrow \mathbb{E}^4$ be a curve in the Euclidean 4-space \mathbb{E}^4 , where I is interval in \mathbb{R} . γ is called unit speed if $\|\gamma'(s)\| = 1$ (parametrized by arclength functions). Then the Frenet formulae of γ are:

$$\begin{bmatrix} T' \\ N' \\ B_1' \\ B_2' \end{bmatrix} = \begin{bmatrix} 0 & \kappa & 0 & 0 \\ -\kappa & 0 & \tau & 0 \\ 0 & -\tau & 0 & \sigma \\ 0 & 0 & -\sigma & 0 \end{bmatrix} \begin{bmatrix} T \\ N \\ B_1 \\ B_2 \end{bmatrix},$$

where $\{T, N, B_1, B_2\}$ is the Frenet frame of γ and κ, τ , and σ are the curvature functions.

In [7], authors used $T(s)$ which is tangent to γ and the parallel transport vector fields $M_1(s), M_2(s)$, and $M_3(s)$ to construct an alternative frame.

Theorem 2.1. [7] *Let $\{T, N, B_1, B_2\}$ be a Frenet frame along a unit speed curve $\gamma = \gamma(s) : I \rightarrow \mathbb{E}^4$ and $\{T, M_1, M_2, M_3\}$ denotes the parallel transport frame of the curve γ . The relationship may be given with*

$$\begin{aligned} T &= T(s) \\ N &= \cos \theta(s) \cos \psi(s) M_1 + (-\cos \phi(s) \sin \psi(s) + \sin \phi(s) \sin \theta(s) \cos \psi(s)) M_2 \\ &\quad + (\sin \phi(s) \sin \psi(s) + \cos \phi(s) \sin \theta(s) \cos \psi(s)) M_3 \\ B_1 &= \cos \theta(s) \sin \psi(s) M_1 + (\cos \phi(s) \cos \psi(s) + \sin \phi(s) \sin \theta(s) \sin \psi(s)) M_2 \\ &\quad + (-\sin \phi(s) \cos \psi(s) + \cos \phi(s) \sin \theta(s) \sin \psi(s)) M_3 \\ B_2 &= -\sin \theta(s) M_1 + \sin \phi(s) \cos \theta(s) M_2 + \cos \phi(s) \cos \theta(s) M_3 \end{aligned}$$

where θ, ψ and ϕ are the Euler angles. Then the alternative parallel frame equations are

$$(2.1) \quad \begin{bmatrix} T' \\ M'_1 \\ M'_2 \\ M'_3 \end{bmatrix} = \begin{bmatrix} 0 & k_1 & k_2 & k_3 \\ -k_1 & 0 & 0 & 0 \\ -k_2 & 0 & 0 & 0 \\ -k_3 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} T \\ M_1 \\ M_2 \\ M_3 \end{bmatrix},$$

where k_1, k_2 and k_3 are principal curvature functions according to parallel transport frame of the curve γ and their expressions are as follows:

$$\begin{aligned} k_1 &= \kappa \cos \theta \cos \psi, \\ k_2 &= \kappa(-\cos \phi \sin \psi + \sin \phi \sin \theta \cos \psi), \\ k_3 &= \kappa(\sin \phi \sin \psi + \cos \phi \sin \theta \cos \psi), \end{aligned}$$

where $\theta' = \frac{\sigma}{\sqrt{\kappa^2 + \tau^2}}$, $\psi' = -\tau - \sigma \frac{\sqrt{\sigma^2 - \theta'^2}}{\sqrt{\kappa^2 + \tau^2}}$, $\phi' = -\frac{\sqrt{\sigma^2 - \theta'^2}}{\cos \theta}$ and the following equalities

$$\begin{aligned} \kappa &= \sqrt{k_1^2 + k_2^2 + k_3^2}, \\ \tau &= -\psi' + \phi' \sin \theta, \\ \sigma &= \frac{\theta'}{\sin \psi}, \\ \phi' \cos \theta + \theta' \cot \psi &= 0 \end{aligned}$$

hold.

In [1], the authors obtained the higher order derivatives of γ in \mathbb{E}^4 as follows:

$$\begin{aligned} \gamma''(s) &= \kappa N, \\ \gamma'''(s) &= -\kappa^2 T + \kappa' N + \kappa \tau B_1, \\ \gamma^{(iv)}(s) &= -3\kappa \kappa' T + (\kappa'' - \kappa^3 - \kappa \tau^2) N + (2\kappa' \tau + \kappa \tau') B_1 + \kappa \tau \sigma B_2, \\ \gamma^{(v)}(s) &= (-3\kappa'^2 - 4\kappa \kappa'' + \kappa^4 + \kappa^2 \tau^2) T + (\kappa''' - 6\kappa^2 \kappa' - 3\kappa' \tau^2 - 3\kappa \tau \tau') N \\ &\quad + (3\kappa'' \tau + 3\kappa' \tau' - \kappa^3 \tau - \kappa \tau^3 + \kappa \tau'' - \kappa \tau \sigma^2) B_1 \\ &\quad + (3\kappa' \tau \sigma + 2\kappa \tau' \sigma + \kappa \tau \sigma') B_2. \end{aligned}$$

And also they gave the following notation and definition:

Notation:

$$\begin{aligned} N_1 &= \kappa N, \\ N_2 &= \kappa' N + \kappa \tau B_1, \\ N_3 &= \lambda N + \lambda_1 B_1 + \lambda_2 B_2, \\ N_4 &= \mu N + \mu_1 B_1 + \mu_2 B_2, \end{aligned}$$

where

$$\begin{aligned}\lambda &= \kappa'' - \kappa^3 - \kappa\tau^2, \\ \lambda_1 &= 2\kappa'\tau + \kappa\tau', \\ \lambda_2 &= \kappa\tau\sigma,\end{aligned}$$

and

$$\begin{aligned}\mu &= \kappa''' - 6\kappa^2\kappa' - 3\kappa'\tau^2 - 3\kappa\tau\tau', \\ \mu_1 &= 3\kappa''\tau + 3\kappa'\tau' - \kappa^3\tau - \kappa\tau^3 + \kappa\tau'' - \kappa\tau\sigma^2, \\ \mu_2 &= 3\kappa'\tau\sigma + 2\kappa\tau'\sigma + \kappa\tau\sigma'\end{aligned}$$

are differentiable functions.

Definition 2.1. [1] Frenet curves are

i) of *GAW* (1) type if they satisfy

$$N_4 = 0,$$

ii) of *GAW* (2) type if they satisfy

$$\|N_2\|^2 N_4 = \langle N_2, N_4 \rangle N_2,$$

iii) of *GAW* (3) type if they satisfy

$$\|N_1\|^2 N_4 = \langle N_1, N_4 \rangle N_1,$$

iv) of *GAW* (4) type if they satisfy

$$\|N_3\|^2 N_4 = \langle N_3, N_4 \rangle N_3,$$

v) of *GAW* (5) type if they satisfy

$$N_4 = a_1 N_1 + b_1 N_2,$$

vi) of *GAW* (6) type if they satisfy

$$N_4 = a_2 N_1 + b_2 N_3,$$

vii) of *GAW* (7) type if they satisfy

$$N_4 = a_3 N_2 + b_3 N_3,$$

where a_i, b_i ($1 \leq i \leq 3$) are non-zero real valued differentiable functions.

3. AW(k)-Type Curves with Parallel Transport Frame in \mathbb{E}^4

In this section, we consider $GAW(k)$ -type curves according to the parallel transport frame in Euclidean space \mathbb{E}^4 .

Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathbb{E}^4$ be a unit speed curve in \mathbb{E}^4 . By the use of parallel transport frame formulas (2.1), we obtain the higher order derivatives of γ as follows:

$$\begin{aligned} \gamma''(s) &= T'(s) = k_1M_1 + k_2M_2 + k_3M_3, \\ \gamma'''(s) &= \{-k_1^2 - k_2^2 - k_3^2\}T + k'_1M_1 + k'_2M_2 + k'_3M_3, \\ \gamma^{(iv)}(s) &= \{-3k_1k'_1 - 3k_2k'_2 - 3k_3k'_3\}T \\ &\quad + \{k''_1 - k_1^3 - k_1k_2^2 - k_1k_3^2\}M_1 \\ &\quad + \{k''_2 - k_2^3 - k_1^2k_2 - k_3^2k_2\}M_2 \\ &\quad + \{k''_3 - k_3^3 - k_1^2k_3 - k_2^2k_3\}M_3, \\ \gamma^{(v)}(s) &= \left\{ \begin{aligned} &-3k_1'^2 - 3k_2'^2 - 3k_3'^2 - 4k_1k_1'' - 4k_2k_2'' - 4k_3k_3'' \\ &+ k_1^4 + k_2^4 + k_3^4 + 2k_1^2k_2^2 + 2k_1^2k_3^2 + 2k_2^2k_3^2 \end{aligned} \right\}T \\ &\quad + \{-6k_1^2k'_1 - 5k_1k_2k'_2 - 5k_1k_3k'_3 + k_1''' - k'_1k_2^2 - k'_1k_3^2\}M_1 \\ &\quad + \{-6k_2^2k'_2 - 5k_1k_2k'_1 - 5k_3k_2k'_3 + k_2''' - k_1^2k'_2 - k_3^2k'_2\}M_2 \\ &\quad + \{-6k_3^2k'_3 - 5k_1k_3k'_1 - 5k_2k_3k'_2 + k_3''' - k_1^2k'_3 - k_2^2k'_3\}M_3. \end{aligned}$$

Then we give the following notation:

Notation:

$$\begin{aligned} \overline{N}_1 &= k_1M_1 + k_2M_2 + k_3M_3, \\ \overline{N}_2 &= k'_1M_1 + k'_2M_2 + k'_3M_3, \\ \overline{N}_3 &= \phi_1M_1 + \phi_2M_2 + \phi_3M_3, \\ \overline{N}_4 &= \psi_1M_1 + \psi_2M_2 + \psi_3M_3, \end{aligned} \tag{3.1}$$

where

$$\begin{aligned} \phi_1 &= k''_1 - k_1^3 - k_1k_2^2 - k_1k_3^2, \\ \phi_2 &= k''_2 - k_2^3 - k_1^2k_2 - k_3^2k_2, \\ \phi_3 &= k''_3 - k_3^3 - k_1^2k_3 - k_2^2k_3, \end{aligned} \tag{3.2}$$

and

$$\begin{aligned} \psi_1 &= -6k_1^2k'_1 - 5k_1k_2k'_2 - 5k_1k_3k'_3 + k_1''' - k'_1k_2^2 - k'_1k_3^2, \\ \psi_2 &= -6k_2^2k'_2 - 5k_1k_2k'_1 - 5k_2k_3k'_3 + k_2''' - k_1^2k'_2 - k_3^2k'_2, \\ \psi_3 &= -6k_3^2k'_3 - 5k_1k_3k'_1 - 5k_2k_3k'_2 + k_3''' - k_1^2k'_3 - k_2^2k'_3 \end{aligned} \tag{3.3}$$

are differentiable functions.

Definition 3.1. Let γ be a unit speed curve in \mathbb{E}^4 . According to its *parallel transport frame*, γ is

i) of PAW (1) type if it satisfies

$$(3.4) \quad \overline{N}_4 = 0,$$

ii) of PAW (2) type if it satisfies

$$(3.5) \quad \|\overline{N}_2\|^2 \overline{N}_4 = \langle \overline{N}_2, \overline{N}_4 \rangle \overline{N}_2,$$

iii) of PAW (3) type if it satisfies

$$(3.6) \quad \|\overline{N}_1\|^2 \overline{N}_4 = \langle \overline{N}_1, \overline{N}_4 \rangle \overline{N}_1,$$

iv) of PAW (4) type if it satisfies

$$(3.7) \quad \|\overline{N}_3\|^2 \overline{N}_4 = \langle \overline{N}_3, \overline{N}_4 \rangle \overline{N}_3,$$

v) of PAW (5) type if it satisfies

$$(3.8) \quad \overline{N}_4 = a_1 \overline{N}_1 + b_1 \overline{N}_2,$$

vi) of PAW (6) type if it satisfies

$$(3.9) \quad \overline{N}_4 = a_2 \overline{N}_1 + b_2 \overline{N}_3,$$

vii) of PAW (7) type if it satisfies

$$(3.10) \quad \overline{N}_4 = a_3 \overline{N}_2 + b_3 \overline{N}_3,$$

where a_i, b_i ($1 \leq i \leq 3$) are non-zero real valued differentiable functions.

Theorem 3.1. Let γ be a unit speed curve in \mathbb{E}^4 . According to its *parallel transport frame*, γ is

i) of PAW(1) type if and only if

$$(3.11) \quad \begin{aligned} -6k_1^2 k_1' - 5k_1 k_2 k_2' - 5k_1 k_3 k_3' + k_1''' - k_1' k_2^2 - k_1' k_3^2 &= 0, \\ -6k_2^2 k_2' - 5k_1 k_2 k_1' - 5k_3 k_2 k_3' + k_2''' - k_1^2 k_2' - k_3^2 k_2' &= 0, \\ -6k_3^2 k_3' - 5k_1 k_3 k_1' - 5k_2 k_3 k_2' + k_3''' - k_1^2 k_3' - k_2^2 k_3' &= 0. \end{aligned}$$

ii) of PAW(2) type if and only if

$$(3.12) \quad \begin{aligned} (k_2'^2 + k_3'^2) \psi_1 &= k_1' (k_2' \psi_2 + k_3' \psi_3), \\ (k_1'^2 + k_3'^2) \psi_2 &= k_2' (k_1' \psi_1 + k_3' \psi_3), \\ (k_1'^2 + k_2'^2) \psi_3 &= k_3' (k_1' \psi_1 + k_2' \psi_2). \end{aligned}$$

iii) of PAW(3) type if and only if

$$(3.13) \quad \begin{aligned} (k_2^2 + k_3^2)\psi_1 &= k_1(k_2\psi_2 + k_3\psi_3), \\ (k_1^2 + k_3^2)\psi_2 &= k_2(k_1\psi_1 + k_3\psi_3), \\ (k_1^2 + k_2^2)\psi_3 &= k_3(k_1\psi_1 + k_2\psi_2). \end{aligned}$$

iv) of PAW(4) type if and only if

$$(3.14) \quad \begin{aligned} (\phi_2^2 + \phi_3^2)\psi_1 &= \phi_1(\phi_2\psi_2 + \phi_3\psi_3), \\ (\phi_1^2 + \phi_3^2)\psi_2 &= \phi_2(\phi_1\psi_1 + \phi_3\psi_3), \\ (\phi_1^2 + \phi_2^2)\psi_3 &= \phi_3(\phi_1\psi_1 + \phi_2\psi_2). \end{aligned}$$

v) of PAW(5) type if and only if

$$(3.15) \quad \begin{aligned} \psi_1 &= a_1k_1 + b_1k'_1, \\ \psi_2 &= a_1k_2 + b_1k'_2, \\ \psi_3 &= a_1k_3 + b_1k'_3. \end{aligned}$$

vi) of PAW(6) type if and only if

$$(3.16) \quad \begin{aligned} \psi_1 &= a_2k_1 + b_2\phi_1, \\ \psi_2 &= a_2k_2 + b_2\phi_2, \\ \psi_3 &= a_2k_3 + b_2\phi_3. \end{aligned}$$

vii) of PAW(7) type if and only if

$$(3.17) \quad \begin{aligned} \psi_1 &= a_3k'_1 + b_3\phi_1, \\ \psi_2 &= a_3k'_2 + b_3\phi_2, \\ \psi_3 &= a_3k'_3 + b_3\phi_3. \end{aligned}$$

Proof. i) Let γ be of PAW(1)-type. Then from the equations (3.1) and (3.4), we have $\overline{N}_4 = \psi_1M_1 + \psi_2M_2 + \psi_3M_3 = 0$. Since M_1, M_2, M_3 are linearly independent, we obtain $\psi_1 = \psi_2 = \psi_3 = 0$, which means

$$(3.18) \quad \begin{aligned} -6k_1^2k'_1 - 5k_1k_2k'_2 - 5k_1k_3k'_3 + k_1''' - k_1'k_2^2 - k_1'k_3^2 &= 0, \\ -6k_2^2k'_2 - 5k_1k_2k'_1 - 5k_3k_2k'_3 + k_2''' - k_1^2k'_2 - k_3^2k'_2 &= 0, \\ -6k_3^2k'_3 - 5k_1k_3k'_1 - 5k_2k_3k'_2 + k_3''' - k_1^2k'_3 - k_2^2k'_3 &= 0. \end{aligned}$$

The sufficiency is trivial.

ii) Let γ be of PAW(2)-type. If we calculate $\|\overline{N}_2\|^2$ and $\langle \overline{N}_2, \overline{N}_4 \rangle$, by the use of equations (3.1) and (3.5), we get

$$(3.19) \quad (k_1'^2 + k_2'^2 + k_3'^2)(\psi_1M_1 + \psi_2M_2 + \psi_3M_3) = (k_1'\psi_1 + k_2'\psi_2 + k_3'\psi_3)(k_1'M_1 + k_2'M_2 + k_3'M_3),$$

which means

$$(3.20) \quad \begin{aligned} (k_2'^2 + k_3'^2)\psi_1 &= k_1'(k_2'\psi_2 + k_3'\psi_3), \\ (k_1'^2 + k_3'^2)\psi_2 &= k_2'(k_1'\psi_1 + k_3'\psi_3), \\ (k_1'^2 + k_2'^2)\psi_2 &= k_3'(k_1'\psi_1 + k_2'\psi_2). \end{aligned}$$

Conversely, if the equations (3.20) are satisfied, by the equation (3.5), γ is of *PAW*(2)-type.

iii) Let γ be of *PAW*(3)-type. If we calculate $\|\overline{N_1}\|^2$, $\langle \overline{N_1}, \overline{N_4} \rangle$ and substitute them in the equation (3.6), we get

$$(3.21) \quad \begin{aligned} (k_1^2 + k_2^2 + k_3^2)(\psi_1 M_1 + \psi_2 M_2 + \psi_3 M_3) = \\ (k_1\psi_1 + k_2\psi_2 + k_3\psi_3)(k_1 M_1 + k_2 M_2 + k_3 M_3), \end{aligned}$$

which means

$$(3.22) \quad \begin{aligned} (k_2^2 + k_3^2)\psi_1 &= k_1(k_2\psi_2 + k_3\psi_3), \\ (k_1^2 + k_3^2)\psi_2 &= k_2(k_1\psi_1 + k_3\psi_3), \\ (k_1^2 + k_2^2)\psi_3 &= k_3(k_1\psi_1 + k_2\psi_2). \end{aligned}$$

Conversely, if the equations (3.22) are satisfied, by the equation (3.6), γ is of *PAW*(3)-type.

iv) Let γ be of *PAW*(4)-type. If we calculate $\|\overline{N_3}\|^2$, $\langle \overline{N_3}, \overline{N_4} \rangle$ and substitute them in (3.7), we get

$$(3.23) \quad \begin{aligned} (\phi_1^2 + \phi_2^2 + \phi_3^2)(\psi_1 M_1 + \psi_2 M_2 + \psi_3 M_3) = \\ (\phi_1\psi_1 + \phi_2\psi_2 + \phi_3\psi_3)(\phi_1 M_1 + \phi_2 M_2 + \phi_3 M_3), \end{aligned}$$

which means

$$(3.24) \quad \begin{aligned} (\phi_2^2 + \phi_3^2)\psi_1 &= \phi_1(\phi_2\psi_2 + \phi_3\psi_3), \\ (\phi_1^2 + \phi_3^2)\psi_2 &= \phi_2(\phi_1\psi_1 + \phi_3\psi_3), \\ (\phi_1^2 + \phi_2^2)\psi_3 &= \phi_3(\phi_1\psi_1 + \phi_2\psi_2). \end{aligned}$$

Conversely, if the equations (3.24) are satisfied, by the equation (3.7), γ is of *PAW*(4)-type.

v) Let γ be of *PAW*(5)-type. In view of the equations (3.1) and (3.8), we can write

$$(3.25) \quad \psi_1 M_1 + \psi_2 M_2 + \psi_3 M_3 = a_1(k_1 M_1 + k_2 M_2 + k_3 M_3) + b_1(k_1' M_1 + k_2' M_2 + k_3' M_3),$$

which gives us

$$(3.26) \quad \begin{aligned} \psi_1 &= a_1 k_1 + b_1 k_1', \\ \psi_2 &= a_1 k_2 + b_1 k_2', \\ \psi_3 &= a_1 k_3 + b_1 k_3'. \end{aligned}$$

Conversely, if the equations (3.26) are satisfied, by the equation (3.8), γ is of PAW(5)-type.

vi) Let γ be of PAW(6)-type. In view of the equations (3.1) and (3.9), we can write

$$(3.27) \quad \psi_1 M_1 + \psi_2 M_2 + \psi_3 M_3 = a_2(k_1 M_1 + k_2 M_2 + k_3 M_3) + b_2(\phi_1 M_1 + \phi_2 M_2 + \phi_3 M_3),$$

that means

$$(3.28) \quad \begin{aligned} \psi_1 &= a_2 k_1 + b_2 \phi_1, \\ \psi_2 &= a_2 k_2 + b_2 \phi_2, \\ \psi_3 &= a_2 k_3 + b_2 \phi_3. \end{aligned}$$

Conversely, if the equations (3.28) are satisfied, by the equation (3.9), γ is of PAW(6)-type.

vii) Let γ be of PAW(7)-type. In view of equations (3.1) and (3.10), we can write

$$(3.29) \quad \psi_1 M_1 + \psi_2 M_2 + \psi_3 M_3 = a_3(k'_1 M_1 + k'_2 M_2 + k'_3 M_3) + b_3(\phi_1 M_1 + \phi_2 M_2 + \phi_3 M_3),$$

which means

$$(3.30) \quad \begin{aligned} \psi_1 &= a_3 k'_1 + b_3 \phi_1, \\ \psi_2 &= a_3 k'_2 + b_3 \phi_2, \\ \psi_3 &= a_3 k'_3 + b_3 \phi_3. \end{aligned}$$

Conversely, if the equations (3.30) are satisfied, by the equation (3.10), γ is of PAW(7)-type. \square

From now on, we consider space curves whose curvatures k_1 is non-zero constant, k_2 and k_3 are not constants. We give curvature conditions of such a curve to be of PAW(k)-type. In this case, we obtain;

$$(3.31) \quad \begin{aligned} \overline{N}_1 &= k_1 M_1 + k_2 M_2 + k_3 M_3, \\ \overline{N}_2 &= k'_2 M_2 + k'_3 M_3, \\ \overline{N}_3 &= \phi_{11} M_1 + \phi_{21} M_2 + \phi_{31} M_3, \\ \overline{N}_4 &= \psi_{11} M_1 + \psi_{21} M_2 + \psi_{31} M_3, \end{aligned}$$

where

$$(3.32) \quad \begin{aligned} \phi_{11} &= -k_1^3 - k_1 k_2^2 - k_1 k_3^2, \\ \phi_{21} &= k'_2 - k_2^3 - k_1^2 k_2 - k_3^2 k_2, \\ \phi_{31} &= k'_3 - k_3^3 - k_1^2 k_3 - k_2^2 k_3, \end{aligned}$$

and

$$(3.33) \quad \begin{aligned} \psi_{11} &= -5k_1k_2k'_2 - 5k_1k_3k'_3, \\ \psi_{21} &= -6k_2^2k'_2 - 5k_2k_3k'_3 + k_2''' - k_1^2k'_2 - k_3^2k'_2, \\ \psi_{31} &= -6k_3^2k'_3 - 5k_2k_3k'_2 + k_3''' - k_1^2k'_3 - k_2^2k'_3. \end{aligned}$$

Proposition 3.1. *Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathbb{E}^4$ be a unit speed curve with non-zero constant k_1 . Then γ is*

i) of PAW(1)-type if and only if

$$(3.34) \quad -k_2^2 = k_3^2 + c,$$

and

$$(3.35) \quad \begin{aligned} -6k_2^2k'_2 - 5k_3k_2k'_3 + k_2''' - k_1^2k'_2 - k_3^2k'_2 &= 0, \\ -6k_3^2k'_3 - 5k_2k_3k'_2 + k_3''' - k_1^2k'_3 - k_2^2k'_3 &= 0. \end{aligned}$$

ii) of PAW(2)-type if and only if

$$(3.36) \quad -k_2^2 = k_3^2 + c,$$

and

$$(3.37) \quad k_3'\psi_{21} = k_2'\psi_{31}.$$

iii) of PAW(3)-type if and only if

$$(3.38) \quad \begin{aligned} (k_2^2 + k_3^2)\psi_{11} &= k_1(k_2\psi_{21} + k_3\psi_{31}), \\ (k_1^2 + k_3^2)\psi_{21} &= k_2(k_1\psi_{11} + k_3\psi_{31}), \\ (k_1^2 + k_2^2)\psi_{31} &= k_3(k_1\psi_{11} + k_2\psi_{21}). \end{aligned}$$

iv) of PAW(4)-type if and only if

$$(3.39) \quad \begin{aligned} (\phi_{21}^2 + \phi_{31}^2)\psi_{11} &= \phi_{11}(\phi_{21}\psi_{21} + \phi_{31}\psi_{31}), \\ (\phi_{11}^2 + \phi_{31}^2)\psi_{21} &= \phi_{21}(\phi_{11}\psi_{11} + \phi_{31}\psi_{31}), \\ (\phi_{11}^2 + \phi_{21}^2)\psi_{31} &= \phi_{31}(\phi_{11}\psi_{11} + \phi_{21}\psi_{21}). \end{aligned}$$

v) of PAW(5)-type if and only if

$$(3.40) \quad \begin{aligned} \psi_{11} &= a_1k_1, \\ \psi_{21} &= a_1k_2 + b_1k'_2, \\ \psi_{31} &= a_1k_3 + b_1k'_3, \end{aligned}$$

and

$$(3.41) \quad a_1 = -\frac{5}{2}(\kappa^2)'.$$

vi) of PAW(6)-type if and only if

$$(3.42) \quad \begin{aligned} \psi_{11} &= a_2 k_1 + b_2 \phi_{11}, \\ \psi_{21} &= a_2 k_2 + b_2 \phi_{21}, \\ \psi_{31} &= a_2 k_3 + b_2 \phi_{31}, \end{aligned}$$

and

$$(3.43) \quad a_2 - b_2 \kappa^2 = -\frac{5}{2}(\kappa^2)'.$$

vii) of PAW(7)-type if and only if

$$(3.44) \quad \begin{aligned} \psi_{11} &= b_3 \phi_{11}, \\ \psi_{21} &= a_3 k_2' + b_3 \phi_{21}, \\ \psi_{31} &= a_3 k_3' + b_3 \phi_{31}, \end{aligned}$$

and

$$(3.45) \quad \frac{5}{2}(\kappa^2)' = b_3 \kappa^2.$$

Proof. i) Let γ be of PAW(1)-type. Using the equations (3.4), (3.31) and (3.33), we obtain

$$(3.46) \quad \psi_{11} = \psi_{21} = \psi_{31} = 0,$$

that means

$$(3.47) \quad \begin{aligned} -5k_1 k_2 k_2' - 5k_1 k_3 k_3' &= 0, \\ -6k_2^2 k_2' - 5k_3 k_2 k_3' + k_2''' - k_1^2 k_2' - k_3^2 k_2' &= 0, \\ -6k_3^2 k_3' - 5k_2 k_3 k_2' + k_3''' - k_1^2 k_3' - k_2^2 k_3' &= 0. \end{aligned}$$

If we solve the equation (3.47), we get

$$(3.48) \quad -k_2^2 = k_3^2 + c,$$

where c is an arbitrary constant. Converse proposition is trivial.

ii) Let γ be of PAW(2)-type. Using the equations (3.5), (3.31) and (3.33), we obtain

$$(3.49) \quad \begin{aligned} (k_2^2 + k_3^2)\psi_{11} &= 0, \\ k_3'^2 \psi_{21} &= k_2' k_3' \psi_{31}, \\ k_2'^2 \psi_{31} &= k_2' k_3' \psi_{21}. \end{aligned}$$

Since k_2 and k_3 are not constants the solution of the first equation of the system (3.49) is

$$\psi_{11} = 0,$$

which corresponds to

$$-k_2^2 = k_3^2 + c.$$

If we simplify the second and the third equations of the system (3.49), we obtain

$$k_3' \psi_{21} = k_2' \psi_{31}.$$

Converse proposition is trivial.

iii) Let γ be of *PAW*(3)-type. Substituting the equations (3.31) and (3.33) in (3.6), we get the solution. Converse proposition is trivial.

iv) Let γ be of *PAW*(4)-type. Substituting the equations (3.31), (3.32) and (3.33) in (3.7), we get the solution. Converse proposition is trivial.

v) Let γ be of *PAW*(5)-type. Using the equation (3.8), (3.31) and (3.33), we get

$$(3.50) \quad \begin{aligned} \psi_{11} &= a_1 k_1, \\ \psi_{21} &= a_1 k_2 + b_1 k_2', \\ \psi_{31} &= a_1 k_3 + b_1 k_3'. \end{aligned}$$

From the first equation of the system (3.50), we obtain

$$-5k_1 k_2 k_2' - 5k_1 k_3 k_3' = a_1 k_1,$$

which corresponds to

$$a_1 = -5k_2 k_2' - 5k_3 k_3'.$$

Using $k_1^2 + k_2^2 + k_3^2 = \kappa^2$ and solving the last equation, we obtain

$$a_1 = -\frac{5}{2}(\kappa^2)'.$$

Converse proposition is trivial.

vi) Let γ be of *PAW*(6)-type. Substituting the equations (3.31), (3.32) and (3.33) in (3.9), we obtain the equations (3.42). Substituting the equations (3.32) and (3.33) in (3.42), we get

$$k_1(a_2) + k_1(-b_2 k_1^2 - b_2 k_2^2 - b_2 k_3^2) = k_1(-5k_2 k_2' - 5k_3 k_3'),$$

which means

$$a_2 - b_2 \kappa^2 = -\frac{5}{2}(\kappa^2)'.$$

Converse proposition is trivial.

vii) Let γ be of *PAW*(7)-type. Substituting the equations (3.31), (3.32) and (3.33) in (3.10), we obtain the equations (3.44). Substituting the equations (3.32) and (3.33) in (3.44), we get

$$(-5k_1 k_2 k_2' - 5k_1 k_3 k_3') = b_3(-k_1^3 - k_1 k_2^2 - k_1 k_3^2).$$

If we divide both side with $-k_1$, we obtain

$$5(k_2k'_2 + k_3k'_3 + k_1k'_1) = b_3(k_1^2 + k_2^2 + k_3^2),$$

which means

$$\frac{5}{2}(\kappa^2)' = b_3\kappa^2.$$

Converse proposition is trivial. \square

Corollary 3.1. *Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathbb{E}^4$ be a unit speed curve with non-zero constant k_1 . If γ is of PAW(1)-type, then γ is of PAW(2)-type.*

Now, let's assume that k_2 is non-zero constant, k_1 and k_3 are not constants. In this case, we obtain;

$$\begin{aligned} \overline{N_1} &= k_1M_1 + k_2M_2 + k_3M_3, \\ \overline{N_2} &= k'_1M_1 + k'_3M_3, \\ \overline{N_3} &= \phi_{12}M_1 + \phi_{22}M_2 + \phi_{32}M_3, \\ \overline{N_4} &= \psi_{12}M_1 + \psi_{22}M_2 + \psi_{32}M_3, \end{aligned} \tag{3.51}$$

where

$$\begin{aligned} \phi_{12} &= k''_1 - k_1^3 - k_1k_2^2 - k_1k_3^2, \\ \phi_{22} &= -k_2^3 - k_1^2k_2 - k_3^2k_2, \\ \phi_{32} &= k''_3 - k_3^3 - k_1^2k_3 - k_2^2k_3, \end{aligned} \tag{3.52}$$

and

$$\begin{aligned} \psi_{12} &= -6k_1^2k'_1 - 5k_1k_3k'_3 + k_1''' - k'_1k_2^2 - k'_1k_3^2, \\ \psi_{22} &= -5k_1k_2k'_1 - 5k_3k_2k'_3, \\ \psi_{32} &= -6k_3^2k'_3 - 5k_1k_3k'_1 + k_3''' - k_1^2k'_3 - k_2^2k'_3. \end{aligned} \tag{3.53}$$

Proposition 3.2. *Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathbb{E}^4$ be a unit speed curve with non-zero constant k_2 . Then γ is*

i) of PAW(1)-type if and only if

$$-k_1^2 = k_3^2 + c,$$

and

$$\begin{aligned} -6k_1^2k'_1 - 5k_1k_3k'_3 + k_1''' - k'_1k_2^2 - k'_1k_3^2 &= 0, \\ -6k_3^2k'_3 - 5k_1k_3k'_1 + k_3''' - k_1^2k'_3 - k_2^2k'_3 &= 0. \end{aligned}$$

ii) of PAW(2)-type if and only if

$$\begin{aligned} -k_1^2 &= k_3^2 + c, \\ k'_1\psi_{32} &= k'_3\psi_{12}. \end{aligned}$$

iii) of PAW(3)-type if and only if

$$\begin{aligned}(k_2^2 + k_3^2)\psi_{12} &= k_1(k_2\psi_{22} + k_3\psi_{32}), \\ (k_1^2 + k_3^2)\psi_{22} &= k_2(k_1\psi_{12} + k_3\psi_{32}), \\ (k_1^2 + k_2^2)\psi_{32} &= k_3(k_1\psi_{12} + k_2\psi_{22}).\end{aligned}$$

iv) of PAW(4)-type if and only if

$$\begin{aligned}(\phi_{22}^2 + \phi_{32}^2)\psi_{12} &= \phi_{12}(\phi_{22}\psi_{22} + \phi_{32}\psi_{32}), \\ (\phi_{12}^2 + \phi_{32}^2)\psi_{22} &= \phi_{22}(\phi_{12}\psi_{12} + \phi_{32}\psi_{32}), \\ (\phi_{12}^2 + \phi_{22}^2)\psi_{32} &= \phi_{32}(\phi_{12}\psi_{12} + \phi_{22}\psi_{22}).\end{aligned}$$

v) of PAW(5)-type if and only if

$$\begin{aligned}\psi_{12} &= a_1k_1 + b_1k'_1, \\ \psi_{22} &= a_1k_2, \\ \psi_{32} &= a_1k_3 + b_1k'_3,\end{aligned}$$

and

$$a_1 = -\frac{5}{2}(\kappa^2)'.$$

vi) of PAW(6)-type if and only if

$$(3.54) \quad \begin{aligned}\psi_{12} &= a_2k_1 + b_2\phi_{12}, \\ \psi_{22} &= a_2k_2 + b_2\phi_{22}, \\ \psi_{32} &= a_2k_3 + b_2\phi_{32},\end{aligned}$$

and

$$a_2 - b_2\kappa^2 = -\frac{5}{2}(\kappa^2)'.$$

vii) of PAW(7)-type if and only if

$$(3.55) \quad \psi_{12} = a_3k'_1 + b_3\phi_{12},$$

$$\psi_{22} = b_3\phi_{22},$$

$$(3.56) \quad \psi_{32} = a_3k'_3 + b_3\phi_{32},$$

and

$$\frac{5}{2}(\kappa^2)' = b_3\kappa^2.$$

Proof. i) Let γ be of PAW(1)-type. Using the equations (3.4), (3.51) and (3.53), we obtain

$$\psi_{11} = \psi_{22} = \psi_{32} = 0,$$

that means

$$\begin{aligned}
 (3.57) \quad & -6k_1^2k_1' - 5k_1k_3k_3' + k_1''' - k_1'k_2^2 - k_1'k_3^2 = 0, \\
 & -5k_1k_2k_1' - 5k_2k_3k_3' = 0, \\
 & -6k_3^2k_3' - 5k_1k_3k_1' + k_3''' - k_1^2k_3' - k_2^2k_3' = 0.
 \end{aligned}$$

If we solve the equation (3.57), we get

$$-k_1^2 = k_3^2 + c,$$

where c is an arbitrary constant. Converse proposition is trivial.

ii) Let γ be of PAW(2)-type. Using the equations (3.5), (3.51) and (3.53), we obtain

$$\begin{aligned}
 (3.58) \quad & k_3^2 \psi_{12} = k_1'k_3'\psi_{32}, \\
 & (k_1^2 + k_3^2)\psi_{22} = 0, \\
 & k_1^2 \psi_{32} = k_1'k_3'\psi_{12}.
 \end{aligned}$$

Since k_1 and k_3 are not constant, the solution of the second equation of the system (3.58) is

$$\psi_{22} = 0,$$

which corresponds to

$$-k_1^2 = k_3^2 + c.$$

If we simplify the first and the third equations of the system (3.58), we obtain

$$k_1' \psi_{32} = k_3' \psi_{12}.$$

Converse proposition is trivial.

iii) Let γ be of PAW(3)-type. Substituting the equations (3.51) and (3.53) in (3.6), we get the solution. Converse proposition is trivial.

iv) Let γ be of PAW(4)-type. Substituting the equations (3.51), (3.52) and (3.53) in (3.7), we get the solution. Converse proposition is trivial.

v) Let γ be of PAW(5)-type. Using (3.8), equations (3.51) and (3.53), we get

$$\begin{aligned}
 (3.59) \quad & \psi_{12} = a_1k_1 + b_1k_1', \\
 & \psi_{22} = a_1k_2, \\
 & \psi_{32} = a_1k_3 + b_1k_3'.
 \end{aligned}$$

From the second equation of the system (3.59), we obtain

$$-5k_1k_2k_1' - 5k_3k_2k_3' = a_1k_2,$$

which corresponds to

$$a_1 = -5k_1k_1' - 5k_3k_3'.$$

Using $k_1^2 + k_2^2 + k_3^2 = \kappa^2$ and solving the last equation, we obtain

$$a_1 = -\frac{5}{2}(\kappa^2)'.$$

Converse proposition is trivial.

vi) Let γ be of $PAW(6)$ -type. Substituting the equations (3.51), (3.52) and (3.53) in (3.9), we obtain the equations (3.54). Substituting the equations (3.52) and (3.53) in (3.54), we get

$$k_2(a_2) + k_2(-b_2k_2^2 - b_2k_1^2 - b_2k_3^2) = k_2(-5k_1k_1' - 5k_3k_3'),$$

which means

$$a_2 - b_2\kappa^2 = -\frac{5}{2}(\kappa^2)'.$$

Converse proposition is trivial.

vii) Let γ be of $PAW(7)$ -type. Substituting the equations (3.51), (3.52) and (3.53) in (3.10), we obtain the equations

$$(3.60) \quad \psi_{22} = b_3\phi_{22},$$

(3.55) and (3.56). Substituting the equations (3.52) and (3.53) in the last equation, we get

$$-5k_1k_2k_1' - 5k_3k_2k_3' = -b_3k_2(k_2^2 + k_1^2 + k_3^2).$$

If we divide both side with k_2 , we obtain

$$5(k_1k_1' + k_3k_3' + k_2k_2') = b_3\kappa^2$$

which means

$$\frac{5}{2}(\kappa^2)' = b_3\kappa^2.$$

Converse proposition is trivial. \square

Corollary 3.2. *Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathbb{E}^4$ be a unit speed curve with non-zero constant k_2 . If γ is of $PAW(1)$ -type, then γ is of $PAW(2)$ -type.*

Now, let's assume that k_3 is non-zero constant, k_1 and k_2 are not constants. In this case, we obtain;

$$(3.61) \quad \begin{aligned} \overline{N_1} &= k_1M_1 + k_2M_2 + k_3M_3, \\ \overline{N_2} &= k_1'M_1 + k_2'M_2, \\ \overline{N_3} &= \phi_{13}M_1 + \phi_{23}M_2 + \phi_{33}M_3, \\ \overline{N_4} &= \psi_{13}M_1 + \psi_{23}M_2 + \psi_{33}M_3, \end{aligned}$$

where

$$(3.62) \quad \begin{aligned} \phi_{13} &= k_1'' - k_1^3 - k_1k_2^2 - k_1k_3^2, \\ \phi_{23} &= k_2'' - k_2^3 - k_1^2k_2 - k_3^2k_2, \\ \phi_{33} &= -k_3^3 - k_1^2k_3 - k_2^2k_3, \end{aligned}$$

and

$$(3.63) \quad \begin{aligned} \psi_{13} &= -6k_1^2k_1' - 5k_1k_2k_2' + k_1''' - k_1'k_2^2 - k_1'k_3^2, \\ \psi_{23} &= -6k_2^2k_2' - 5k_1k_2k_1' + k_2''' - k_1^2k_2' - k_3^2k_2', \\ \psi_{33} &= -5k_1k_3k_1' - 5k_2k_3k_2'. \end{aligned}$$

Proposition 3.3. *Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathbb{E}^4$ be a unit speed curve with non-zero constant k_3 . Then γ is*

i) of PAW(1)-type if and only if

$$-k_1^2 = k_2^2 + c,$$

and

$$\begin{aligned} -6k_1^2k_1' - 5k_1k_2k_2' + k_1''' - k_1'k_2^2 - k_1'k_3^2 &= 0, \\ -6k_2^2k_2' - 5k_1k_2k_1' + k_2''' - k_1^2k_2' - k_3^2k_2' &= 0. \end{aligned}$$

ii) of PAW(2)-type if and only if

$$\begin{aligned} k_2'\psi_{13} &= k_1'\psi_{23}, \\ -k_1^2 &= k_2^2 + c. \end{aligned}$$

iii) of PAW(3)-type if and only if

$$\begin{aligned} (k_2^2 + k_3^2)\psi_{13} &= k_1(k_2\psi_{23} + k_3\psi_{33}), \\ (k_1^2 + k_3^2)\psi_{23} &= k_2(k_1\psi_{13} + k_3\psi_{33}), \\ (k_1^2 + k_2^2)\psi_{33} &= k_3(k_1\psi_{13} + k_2\psi_{23}). \end{aligned}$$

vi) of PAW(4)-type if and only if

$$\begin{aligned} (\phi_{23}^2 + \phi_{33}^2)\psi_{13} &= \phi_{13}(\phi_{23}\psi_{23} + \phi_{33}\psi_{33}), \\ (\phi_{13}^2 + \phi_{33}^2)\psi_{23} &= \phi_{23}(\phi_{13}\psi_{13} + \phi_{33}\psi_{33}), \\ (\phi_{13}^2 + \phi_{23}^2)\psi_{33} &= \phi_{33}(\phi_{13}\psi_{13} + \phi_{23}\psi_{23}). \end{aligned}$$

v) of PAW(5)-type if and only if

$$\begin{aligned} \psi_{13} &= a_1k_1 + b_1k_1', \\ \psi_{23} &= a_1k_2 + b_1k_2', \\ \psi_{33} &= a_1k_3, \end{aligned}$$

and

$$a_1 = -\frac{5}{2}(\kappa^2)'.$$

vi) of PAW(6)-type if and only if

$$(3.64) \quad \begin{aligned} \psi_{13} &= a_2 k_1 + b_2 \phi_{13}, \\ \psi_{23} &= a_2 k_2 + b_2 \phi_{23}, \\ \psi_{33} &= a_2 k_3 + b_2 \phi_{33}, \end{aligned}$$

and

$$a_2 - b_2 \kappa^2 = -\frac{5}{2}(\kappa^2)'$$

vii) of PAW(7)-type if and only if

$$(3.65) \quad \begin{aligned} \psi_{13} &= a_3 k'_1 + b_3 \phi_{13}, \\ \psi_{23} &= a_3 k'_2 + b_3 \phi_{23}, \\ \psi_{33} &= b_3 \phi_{33}, \end{aligned}$$

and

$$\frac{5}{2}(\kappa^2)' = b_3 \kappa^2.$$

Proof. i) Let γ be of PAW(1)-type. Using the equations (3.4), (3.61) and (3.63), we obtain

$$\psi_{13} = \psi_{23} = \psi_{33} = 0,$$

that means

$$(3.66) \quad \begin{aligned} -6k_1^2 k'_1 - 5k_1 k_2 k'_2 + k_1''' - k_1' k_2^2 - k_1' k_3^2 &= 0, \\ -6k_2^2 k'_2 - 5k_1 k_2 k'_1 + k_2''' - k_1^2 k'_2 - k_3^2 k'_2 &= 0, \\ -5k_1 k_3 k'_1 - 5k_2 k_3 k'_2 &= 0. \end{aligned}$$

If we solve the equation (3.66), we get

$$-k_1^2 = k_2^2 + c,$$

where c is an arbitrary constant. Converse proposition is trivial.

ii) Let γ be of PAW(2)-type. Using the equations (3.5), (3.61) and (3.63), we obtain

$$(3.67) \quad \begin{aligned} k_2'^2 \psi_{13} &= k_1' k'_2 \psi_{23}, \\ k_1'^2 \psi_{23} &= k_1' k'_2 \psi_{13}, \\ (k_1'^2 + k_2'^2) \psi_{33} &= 0. \end{aligned}$$

Since k_1 and k_2 are not constant, the solution of the third equation of the system (3.67) is

$$\psi_{33} = 0,$$

which corresponds to

$$-k_1^2 = k_2^2 + c.$$

If we simplify the first and the second equations of the system (3.67), we obtain

$$k_2' \psi_{13} = k_1' \psi_{23}.$$

Converse proposition is trivial.

iii) Let γ be of *PAW*(3)-type. Substituting the equations (3.61) and (3.63) in (3.6), we get the solution. Converse proposition is trivial.

iv) Let γ be of *PAW*(4)-type. Substituting the equations (3.61), (3.62) and (3.63) in (3.7), we get the solution. Converse proposition is trivial.

v) Let γ be of *PAW*(5)-type. Using the equations (3.8), (3.61) and (3.63), we get

$$(3.68) \quad \begin{aligned} \psi_{13} &= a_1 k_1 + b_1 k_1', \\ \psi_{23} &= a_1 k_2 + b_1 k_2', \\ \psi_{33} &= a_1 k_3. \end{aligned}$$

From the third equation of the system (3.68), we obtain

$$-5k_1 k_3 k_1' - 5k_2 k_3 k_2' = a_1 k_3,$$

which corresponds to

$$a_1 = -5k_1 k_1' - 5k_2 k_2'.$$

Using $k_1^2 + k_2^2 + k_3^2 = \kappa^2$ and solving the last equation, we obtain

$$a_1 = -\frac{5}{2}(\kappa^2)'.$$

Converse proposition is trivial.

vi) Let γ be of *PAW*(6)-type. Substituting the equations (3.61), (3.62) and (3.63) in (3.9), we obtain the equations (3.64). Substituting the equations (3.62) and (3.63) in (3.64), we get

$$k_3 (a_2) + k_3 (-b_2 k_2^2 - b_2 k_1^2 - b_2 k_3^2) = k_3 (-5k_1 k_1' - 5k_2 k_2'),$$

which means

$$a_2 - b_2 \kappa^2 = -\frac{5}{2}(\kappa^2)'.$$

Converse proposition is trivial.

vii) Let γ be of *PAW*(7)-type. Since k_3 is non-zero constant, substituting the equations (3.61), (3.62) and (3.63) in (3.10), we obtain the equations

$$\psi_{33} = b_3 \phi_{33},$$

and (3.65). Substituting the equations (3.62) and (3.63) in the last equation, we get

$$-5k_1k_2k'_1 - 5k_2k_3k'_2 = -b_3k_3(k_2^2 + k_1^2 + k_3^2).$$

If we divide both side with k_3 , we obtain

$$5(k_1k'_1 + k_3k'_3 + k_2k'_2) = b_3\kappa^2,$$

which means

$$\frac{5}{2}(\kappa^2)' = b_3\kappa^2.$$

Converse proposition is trivial. \square

Corollary 3.3. *Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathbb{E}^4$ be a unit speed curve with non-zero constant k_3 . If γ is of PAW(1)-type, then γ is of PAW(2)-type.*

Acknowledgements

The authors would like to express their deep gratitude to the anonymous learned referee(s) and the editor for their valuable suggestions and constructive comments, which resulted in the subsequent improvement of this research article. The third author Deepmala is thankful to carried out this research work under the SERB National Post-Doctoral fellowship scheme of Science and Engineering Research Board, Department of Science and Technology, Government of India, File Number: PDF/2015/000799. The authors declare that there is no conflict of interests regarding the publication of this research article.

REFERENCES

1. K. ARSLAN AND Ş. GÜVENÇ : *Curves of Generalized AW(k)-Type in Euclidean Spaces*. International Electronic Journal of Geometry **7(2)** (2014), 25–36.
2. K. ARSLAN AND A. WEST : *Product Submanifolds with Pointwise 3-Planar Normal Sections*. Glasgow Math. J. **37** (1995), 73–81.
3. K. ARSLAN AND C. ÖZGÜR : *Curves and Surfaces of AW(k) Type*. Geometry and Topology of Submanifolds IX, World Scientific, (1997), 21–26.
4. S. BÜYÜKKÜTÜK, İ. KIŞI, V.N. MISHRA, G. ÖZTÜRK : *Some Characterizations of Curves in Galilean 3-Space \mathbb{G}_3* . Facta Universitatis, Series: Mathematics and Informatics, **37(2)** (2016), 503–512.
5. DEEPMALA AND L.N. MISHRA : *Differential operators over modules and rings as a path to the generalized differential geometry*. Facta Universtatis Ser. Math. Inform. **30(5)** (2015), 753–764.
6. L.R. BISHOP : *There is more than one way to frame a curve*. Amer. Math. Monthly **82(3)** (1975), 246–251.
7. F. GÖKÇELİK, Z. BOZKURT, İ. GÖK, F. N. EKMEKCI AND Y. YAYLI Y. : *Parallel Transport Frame in 4-dimensional Euclidean Space \mathbb{E}^4* . Caspian J. of Math. Sci. **3(1)** (2014), 91–103.

8. M. K. KARACAN AND B. BÜKCÜ : *On Natural Curvatures of Bishop Frame*, *Journal of Vectorial Relativity*. International Electronic Journal of Geometry **5** (2010), 34–41.
9. B. KILIÇ AND K. ARSLAN : *On Curves and Surfaces of AW(k)-type*. BAÜ Fen Bil. Enst. Dergisi **6(1)** (2004), 52–61.
10. I. KIŞI AND G. ÖZTÜRK : *AW(k)-Type Curves According to the Bishop Frame*. arXiv:1305.3381v1 [math.DG], 15 May 2013.
11. L. PISCORAN AND V.N. MISHRA : *Projectively flatness of a new class of (α, β) -metrics*. Georgian Math. Journal, (2016), in press.

İlim Kişi
Department of Mathematics
Kocaeli University
41380 Kocaeli, Turkey
ilim.ayvaz@kocaeli.edu.tr

Sezgin Büyükkütük
Department of Mathematics
Kocaeli University
41380 Kocaeli, Turkey
sezgin.buyukkutuk@kocaeli.edu.tr

Deepmala (Corresponding author)
SQC & OR Unit
Indian Statistical Institute
203 B. T. Road, Kolkata-700 108, India
dmrai23@gmail.com, deepmaladm23@gmail.com

Günay Öztürk
Department of Mathematics
Kocaeli University
41380 Kocaeli, Turkey
ogunay@kocaeli.edu.tr