

SOME RESULTS ON GENERALIZED (k, μ) -PARACONTACT METRIC MANIFOLDS

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Abstract. The aim of this paper is to study the Codazzi type of the Ricci tensor in generalized (k, μ) -paracontact metric manifolds. We also study the cyclic parallel Ricci tensor in generalized (k, μ) -paracontact metric manifolds. Further, we characterize generalized (k, μ) -paracontact metric manifolds whose structure tensor ϕ is η -parallel. Finally, we investigate locally ϕ -Ricci symmetric generalized (k, μ) -paracontact metric manifolds.

Keywords: Generalized (k, μ) -paracontact metric manifold, Codazzi type of tensor, cyclic parallel Ricci tensor, η -parallel ϕ -tensor, locally ϕ -Ricci symmetric.

1. Introduction

In 1985, Kaneyuki and Williams [8] introduced the idea of paracontact geometry. A systematic investigation on paracontact metric manifolds was done by Zamkovoy [12]. Recently, Cappelletti-Montano et al [5] introduced a new type of paracontact geometry, the so-called paracontact metric (k, μ) space, where k and μ are constants. This is known [2] about the contact case $k \leq 1$, but in the paracontact case there is no restriction of k . Recently, three-dimensional generalized (k, μ) -paracontact metric manifolds were studied by Kupeli Erken et al [9, 10]. Zamkovoy [12] studied paracontact metric manifolds and some remarkable subclasses named para-Sasakian manifolds. In particular, in recent years, many authors have pointed to the importance of paracontact geometry and, in particular, para-Sasakian geometry. Several papers have established relationships with the theory of para-Kähler manifolds and its role in pseudo-Riemannian geometry and mathematical physics. A normal paracontact metric manifold is a para-Sasakian manifold. An almost paracontact metric manifold is a para-sasakian manifold if and only if [12]

$$(1.1) \quad (\nabla_X \phi)Y = -g(X, Y)\xi + \eta(Y)X.$$

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A. Gray [7] introduced the notion of cyclic parallel Ricci tensor and Codazzi type of Ricci tensor. The Ricci tensor S of type $(0,2)$ is said to be cyclic parallel if it is non-zero and satisfies the condition

$$(1.2) \quad (\nabla_Z S)(X, Y) + (\nabla_X S)(Y, Z) + (\nabla_Y S)(Z, X) = 0.$$

Again, a Riemannian or a pseudo-Riemannian manifold is said to be of Codazzi type if its Ricci tensors of type $(0,2)$ is non-zero and satisfy the following condition

$$(1.3) \quad (\nabla_X S)(Y, Z) = (\nabla_Y S)(X, Z),$$

for all vector fields X, Y, Z . On a contact metric manifold there is an associated CR-structure which is integrable if and only if the structure tensor ϕ is η -parallel, that is,

$$g((\nabla_X \phi)Y, Z) = 0,$$

for all vector fields X, Y, Z in the contact distribution $D(\eta = 0)$. In 2005, Boeckx and Cho [3] considered a milder condition that h is η -parallel, that is,

$$g((\nabla_X h)Y, Z) = 0,$$

for all vector fields X, Y, Z in the contact distribution D .

The paper is organized in the following way:

In Section 2, we discuss some basic results of paracontact metric manifolds. Further, we characterize the Codazzi type of the Ricci tensor in generalized (k, μ) -paracontact metric manifolds. In Section 4, we investigate the cyclic parallel Ricci tensor in generalized (k, μ) -paracontact metric manifolds. In the next section we study η -parallel ϕ -tensor in a generalized (k, μ) -paracontact metric manifold. Finally, we investigate locally ϕ -Ricci symmetric generalized (k, μ) -paracontact metric manifolds.

2. Preliminaries

An odd dimensional smooth manifold $M^n (n > 1)$ is said to be an almost paracontact manifold [8] if it carries a $(1, 1)$ -tensor ϕ , a vector field ξ and a 1-form η satisfying :

- (i) $\phi^2 X = X - \eta(X)\xi$, for all $X \in \chi(M)$,
- (ii) $\eta(\xi) = 1$, $\phi(\xi) = 0$, $\eta \circ \phi = 0$,
- (iii) the tensor field ϕ induces an almost paracomplex structure on each fiber of $D = \ker(\eta)$, that is, the eigen distributions D_ϕ^+ and D_ϕ^- of ϕ corresponding to the eigenvalues 1 and -1 , respectively, have an equal dimension n .

An almost paracontact structure is said to be normal [8] if and only if the $(1, 2)$ type torsion tensor $N_\phi = [\phi, \phi] - 2d\eta \otimes \xi$ vanishes identically, where $[\phi, \phi](X, Y) = \phi^2[X, Y] + [\phi X, \phi Y] - \phi[\phi X, Y] - \phi[X, \phi Y]$. A para-Sasakian manifold is a normal paracontact metric manifold. If an almost paracontact manifold admits a pseudo-Riemannian metric g such that

$$(2.1) \quad g(\phi X, \phi Y) = -g(X, Y) + \eta(X)\eta(Y),$$

for $X, Y \in \chi(M)$, then we say that (M, ϕ, ξ, η, g) is an almost paracontact metric manifold. Any such pseudo-Riemannian metric is of signature $(n+1, n)$. An almost paracontact structure is said to be a paracontact structure if $g(X, \phi Y) = d\eta(X, Y)$ [12]. In a paracontact metric manifold we define $(1, 1)$ -type tensor fields h by $h = \frac{1}{2} \mathcal{L}_\xi \phi$, where $\mathcal{L}_\xi \phi$ is the Lie derivative of ϕ along the vector field ξ . Then we observe that h is symmetric and anti-commutes with ϕ . Also h satisfies the following conditions [12]:

$$(2.2) \quad h\xi = 0, \text{tr}(h) = \text{tr}(\phi h) = 0,$$

$$(2.3) \quad \nabla_X \xi = -\phi X + \phi hX,$$

for all $X \in \chi(M)$, where ∇ denotes the Levi-Civita connection of the pseudo-Riemannian manifold.

Moreover, h vanishes identically if and only if ξ is a Killing vector field. In this case, (M, ϕ, ξ, η, g) is said to be a K -paracontact manifold [11].

Generalized (k, μ) -paracontact metric manifolds were studied by Erken et al. [10] and Erken [9]. A generalized (k, μ) -paracontact metric manifold means a three-dimensional paracontact metric manifold which satisfies the curvature condition

$$(2.4) \quad R(X, Y)\xi = k(\eta(Y)X - \eta(X)Y) + \mu(\eta(Y)hX - \eta(X)hY),$$

where k and μ are smooth functions.

In a generalized $(k \neq -1, \mu)$ -paracontact manifold the following results hold [4, 5, 9, 10]

$$(2.5) \quad h^2 = (1 + k)\phi^2,$$

$$(2.6) \quad \xi(k) = 0,$$

$$(2.7) \quad Q\xi = 2k\xi,$$

$$(2.8) \quad (\nabla_\xi h)(Y) = \mu h(\phi Y),$$

$$(2.9) \quad \begin{aligned} (\nabla_X h)Y - (\nabla_Y h)X &= -(1 + k)[2g(X, \phi Y)\xi + \eta(X)\phi Y - \eta(Y)\phi X] \\ &+ (1 - \mu)(\eta(X)\phi hY - \eta(Y)\phi hX), \end{aligned}$$

$$(2.10) \quad (\nabla_X \phi)Y = -g(X - hX, Y)\xi + \eta(Y)(X - hX), \text{ for } k \neq -1$$

$$(2.11) \quad h \text{ grad}\mu = \text{grad}k,$$

$$(2.12) \quad (\nabla_X \eta)(Y) = -g(\phi X, Y) + g(\phi hX, Y),$$

$$(2.13) \quad QX = \left(\frac{r}{2} - k\right)X + \left(-\frac{r}{2} + 3k\right)\eta(X)\xi + \mu hX, k \neq -1,$$

where X is any vector fields on M , Q is the Ricci operator of M , r denotes the scalar curvature of M .

From (2.13), we have

$$(2.14) \quad S(X, Y) = \left(\frac{r}{2} - k\right)g(X, Y) + \left(-\frac{r}{2} + 3k\right)\eta(X)\eta(Y) + \mu g(hX, Y), k \neq -1.$$

3. The Codazzi type of the Ricci tensor in generalized (k, μ) -paracontact metric manifolds

In this section we characterize generalized (k, μ) -paracontact metric manifolds whose Ricci tensor is of Codazzi type.

Then we have

$$(3.1) \quad (\nabla_X S)(Y, Z) = (\nabla_Y S)(X, Z),$$

which implies $r = \text{constant}$.

Now from (2.14) we have

$$(3.2) \quad \begin{aligned} (\nabla_X S)(Y, Z) &= \left\{ \frac{(Xr)}{2} - (Xk) \right\} g(Y, Z) + \left\{ -\frac{(Xr)}{2} + 3(Xk) \right\} \eta(Y)\eta(Z) \\ &\quad + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_X \eta)(Y)\eta(Z) + \eta(Y)(\nabla_X \eta)(Z) \} + (X\mu)g(hY, Z) \\ &\quad + \mu g((\nabla_X h)(Y), Z) \end{aligned}$$

and

$$(3.3) \quad \begin{aligned} (\nabla_Y S)(X, Z) &= \left\{ \frac{(Yr)}{2} - (Yk) \right\} g(X, Z) + \left\{ -\frac{(Yr)}{2} + 3(Yk) \right\} \eta(X)\eta(Z) \\ &\quad + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_Y \eta)(X)\eta(Z) + \eta(X)(\nabla_Y \eta)(Z) \} + (Y\mu)g(hX, Z) \\ &\quad + \mu g((\nabla_Y h)(X), Z). \end{aligned}$$

Using (3.2) and (3.3) in (3.1) yields

$$(3.4) \quad \begin{aligned} &\left\{ \frac{(Xr)}{2} - (Xk) \right\} g(Y, Z) + \left\{ -\frac{(Xr)}{2} + 3(Xk) \right\} \eta(Y)\eta(Z) \\ &\quad + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_X \eta)(Y)\eta(Z) + \eta(Y)(\nabla_X \eta)(Z) \} + (X\mu)g(hY, Z) \\ &\quad + \mu g((\nabla_X h)(Y), Z) = \left\{ \frac{Yr}{2} - Yk \right\} g(X, Z) \\ &\quad + \left\{ -\frac{(Yr)}{2} + 3(Yk) \right\} \eta(X)\eta(Z) + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_Y \eta)(X)\eta(Z) \\ &\quad + \eta(X)(\nabla_Y \eta)(Z) \} + (Y\mu)g(hX, Z) + \mu g((\nabla_Y h)(X), Z). \end{aligned}$$

Substituting $Z = \xi$ in (3.4) gives

$$\begin{aligned}
 & \left\{ \frac{(Xr)}{2} - (Xk) \right\} \eta(Y) + \left\{ -\frac{(Xr)}{2} + 3(Xk) \right\} \eta(Y) + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_X \eta)(Y) \\
 & + \eta(Y)(\nabla_X \eta)(\xi) \} + \mu \eta((\nabla_X h)(Y)) = \left\{ \frac{Yr}{2} - Yk \right\} \eta(X) \\
 & + \left\{ -\frac{(Yr)}{2} + 3(Yk) \right\} \eta(X) + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_Y \eta)(X) + \eta(X)(\nabla_Y \eta)(\xi) \} \\
 (3.5) \quad & + \mu \eta((\nabla_Y h)(X)).
 \end{aligned}$$

Putting $X = \xi$ in (3.5) and using $r = \text{constant}$, we obtain

$$(3.6) \quad \mu \eta((\nabla_\xi h)(Y)) = 2(Yk) + \mu \eta((\nabla_Y h)(\xi)) = 0.$$

Applying (2.8) in (3.6), we have $(Yk) = 0$, which implies $k = \text{constant}$. Hence from (2.11), we get either $h = 0$ or $\mu = \text{constant}$. Thus, we can state the following

Theorem 3.1. *If in a generalized (k, μ) -paracontact metric manifold with $k \neq -1$ the Ricci tensor is of Codazzi type, then the manifold is either a (k, μ) -paracontact metric manifold or a K -paracontact manifold.*

4. The cyclic parallel Ricci tensor in generalized (k, μ) -paracontact metric manifolds

This section is devoted to the study of the cyclic parallel Ricci tensor in generalized (k, μ) -paracontact metric manifolds

If the Ricci tensors is cyclic parallel, then we have

$$(4.1) \quad (\nabla_Z S)(X, Y) + (\nabla_X S)(Y, Z) + (\nabla_Y S)(Z, X) = 0,$$

which implies $r = \text{constant}$.

Now from the equation (2.14), we obtain

$$\begin{aligned}
 & \left\{ \frac{(Zr)}{2} - (Zk) \right\} g(X, Y) + \left\{ -\frac{(Zr)}{2} + 3(Zk) \right\} \eta(X)\eta(Y) \\
 & + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_Z \eta)(X)\eta(Y) + \eta(X)(\nabla_Z \eta)(Y) \} + (Z\mu)g(hX, Y) \\
 & + \mu g((\nabla_Z h)(X)Y) + \left\{ \frac{Xr}{2} - Xk \right\} g(Y, Z) + \left\{ -\frac{(Xr)}{2} + 3(Xk) \right\} \eta(Y)\eta(Z) \\
 & + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_X \eta)(Y)\eta(Z) + \eta(Y)(\nabla_X \eta)(Z) \} + (X\mu)g(hY, Z) \\
 & + \mu g((\nabla_X h)(Y), Z) + \{ (Yr) - (Yk) \} g(Z, X) + \left\{ -\frac{(Yr)}{2} + 3(Yk) \right\} \eta(Z)\eta(X) \\
 & + \left\{ -\frac{r}{2} + 3k \right\} \{ (\nabla_Y \eta)(Z)\eta(X) + \eta(Z)(\nabla_Y \eta)(X) \} + (Y\mu)g(hZ, X) \\
 (4.2) \quad & + \mu g((\nabla_Y h)(Z), X) = 0.
 \end{aligned}$$

Substituting $X = Y = \xi$ and applying (2.8) in (4.2) yields

$$(4.3) \quad 2(Zk) + \left(-\frac{r}{2} + 3k\right)(\nabla_{\xi}\eta)(Z) + \left(-\frac{r}{2} + 3k\right)(\nabla_{\xi}\eta)(Z) = 0.$$

Now using (2.12) in (4.3), we have

$$(4.4) \quad (Zk) = 0.$$

Therefore, $k = \text{constant}$. Hence from (2.11), we have either $h = 0$ or $\mu = \text{constant}$. This leads to the following:

Theorem 4.1. *If in a generalized (k, μ) -paracontact metric manifold with $k \neq -1$ the Ricci tensor is cyclic parallel, then the manifold is either a (k, μ) -paracontact metric manifold or a K -paracontact manifold.*

5. The η -parallel ϕ -tensor in generalized (k, μ) -paracontact metric manifolds

In this section we study the η -parallel ϕ -tensor in generalized (k, μ) -paracontact metric manifolds

If the $(1, 1)$ tensor ϕ is η -parallel, then we have [1]

$$(5.1) \quad g((\nabla_X \phi)Y, Z) = 0.$$

From (2.10) and (5.1), we get

$$(5.2) \quad -g(X, Y)\eta(Z) + g(hX, Y)\eta(Z) + g(X, Z)\eta(Y) - g(hX, Z)\eta(Y) = 0.$$

Putting $Z = \xi$ in (5.2) yields

$$(5.3) \quad -g(X, Y) + g(hX, Y) + \eta(X)\eta(Y) = 0.$$

Substituting $X = hX$ in (5.3), we have

$$(5.4) \quad -g(hX, Y) - (k+1)g(X, Y) + (k+1)\eta(X)\eta(Y) = 0.$$

Adding (5.3) and (5.4), we obtain

$$(5.5) \quad (k+2)\{g(X, Y) - \eta(X)\eta(Y)\} = 0.$$

Thus we have $k = -2$, that is, $k = \text{constant}$. Using (2.11) we have $h \text{ grad} \mu = 0$. Therefore, either $h = 0$ or $\mu = \text{constant}$.

Thus we can state the following:

Theorem 5.1. *If in a generalized (k, μ) -paracontact metric manifold with $k \neq -1$, the tensor ϕ is η -parallel, then the manifold is either a (k, μ) -paracontact metric manifold or a K -paracontact manifold.*

6. Locally ϕ -Ricci symmetric generalized (k, μ) -paracontact manifolds

A paracontact metric manifold is said to be locally ϕ -Ricci symmetric [6] if it satisfies

$$(6.1) \quad \phi^2(\nabla_X Q)(Y) = 0,$$

for all vector fields X, Y orthogonal to ξ , where Q is the Ricci operator defined by $g(QX, Y) = S(X, Y)$.

Taking the covariant derivative of (2.13) with respect to Y and applying ϕ^2 we get

$$(6.2) \quad -\left\{\frac{(Yr)}{2} - Yk\right\}X - (Y\mu)hX + \mu\phi^2((\nabla_Y h)X) = 0.$$

Interchanging X and Y in (6.2), we have

$$(6.3) \quad -\left\{\frac{(Xr)}{2} - Xk\right\}Y - (X\mu)hY + \mu\phi^2((\nabla_X h)Y) = 0.$$

Subtracting (6.3) from (6.2), we obtain

$$(6.4) \quad \left\{\frac{(Yr)}{2} - Yk\right\}X - \left\{\frac{(Xr)}{2} - Xk\right\}Y + (Y\mu)hX - (X\mu)hY + \mu\phi^2((\nabla_X h)Y - (\nabla_Y h)X) = 0.$$

Applying (2.9) in (6.4), we get

$$(6.5) \quad \left\{\frac{(Yr)}{2} - Yk\right\}X - \left\{\frac{(Xr)}{2} - Xk\right\}Y + (Y\mu)hX - (X\mu)hY = 0.$$

Substituting $X = \xi$ in (6.5) yields

$$(6.6) \quad -\frac{1}{2}(\xi r)Y - (\xi\mu)hY + \left\{\frac{Yr}{2} - Yk\right\}\xi = 0.$$

Taking the inner product with Z from (6.6), we have

$$(6.7) \quad -\frac{1}{2}(\xi r)g(Y, Z) - (\xi\mu)g(hY, Z) = 0.$$

Let $\{e_i\}$, $i = 1, 2, 3$ be a local orthonormal basis in the tangent space T_pM at each point $p \in M$. Substituting $Y = Z = e_i$ in (6.7) and summing over $i = 1$ to 3 , we infer that $\xi r = 0$, since $k \neq -1$.

This leads to the following:

Theorem 6.1. *If a generalized (k, μ) -paracontact metric manifold with $k \neq -1$, is locally ϕ -Ricci symmetric, then the characteristic vector field ξ leaves the scalar curvature invariant.*

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