

LEFT INVARIANT (α, β) -METRICS ON 4-DIMENSIONAL LIE GROUPS

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Abstract. Let G be a 4-dimensional Lie group with an invariant para-hypercomplex structure and let $F = \beta + a\alpha + \beta^2/\alpha$ be a left invariant (α, β) -metric, where α is a Riemannian metric and β is a 1-form on G , and a is a real number. We prove that the flag curvature of F with parallel 1-form β is non-positive, except in Case 2, in which F admits both negative and positive flag curvature. Then, we determine all geodesic vectors of (G, F) .

Keywords: para-hypercomplex structure; (α, β) -metric; Riemannian metric; flag curvature.

1. Introduction

Hypercomplex and para-hypercomplex structures are interesting and practical structures in differential geometry [13]. These structures have been used in theoretical physics and HKT-geometry, intensively [11]. According to V. V. Cortés and C. Mayer studies, the para-hypercomplex structures emerged as target manifold of hypermultiplets in Euclidean theories with rigid $N = 2$ supersymmetry [9]. M. L. Barberis classified the invariant hypercomplex structures on a simply-connected 4-dimensional real Lie group [3, 5]. In [6], N. Blažić and S. Vukmirović classified 4-dimensional Lie algebras admitting a para-hypercomplex structure.

Finsler geometry has many applications in mechanics, physics and biology [1]. Among Finsler metrics, (α, β) -metrics, which were first introduced by M. Matsumoto, are the important ones [16].

In [20] the third author introduced a new class of (α, β) -metrics given by $F = \beta + a\alpha + \beta^2/\alpha$ where $a \in (\frac{1}{4}, \infty)$ and studied the locally dually flatness for this type of metrics [21]. One of the key quantities in Riemannian geometry is the sectional curvature. In Finsler geometry, we have the notion of flag curvature as a natural extension of the notion of the sectional curvature [2].

In the present study, we consider the left invariant 4-dimensional para-hypercomplex Lie groups and construct some Berwaldian left invariant (α, β) -metrics of type $F = \beta + a\alpha + \beta^2/\alpha$ on them. We get a formula for the flag curvature of F and prove that F is non- positive flag curvature except one case, consequently, F is not of constant Ricci curvature.

Let (G, α) be a Lie group G furnished by a left invariant Riemannian metric α . There is a natural kind of geodesics of (G, α) which are closely related to the algebraic ingredient of G . More precisely, we are interested in those geodesics which are in the form $\gamma(t) = \exp(tX)$ for some tangent vector X in the Lie algebra of G , i.e., $\mathfrak{g} := T_e G$. In other words, those geodesics which are orbits of one parameter subgroups of G . In this case, X is called a geodesic vector. This notion was extended to Finsler geometry by Latifi [14]. Here, we also obtain all geodesic vectors of the invariant (α, β) -metric $F = \beta + a\alpha + \beta^2/\alpha$.

2. Preliminaries

Let us recall some known facts about para-hypercomplex structures and Finsler spaces. Let M be a smooth manifold and $\{J_i\}_{i=1,2,3}$ be a family of fiberwise endomorphisms of TM such that

$$(2.1) \quad J_1^2 = -Id_{TM},$$

$$(2.2) \quad J_2^2 = Id_{TM}, \quad J_2 \neq \pm Id_{TM},$$

$$(2.3) \quad J_1 J_2 = -J_2 J_1 = J_3,$$

and

$$(2.4) \quad N_i = 0 \quad i = 1, 2, 3,$$

where N_i is the Nijenhuis tensor corresponding to J_i defined as follows:

$$N_1(X, Y) = [J_1 X, J_1 Y] - J_1([X, J_1 Y] + [J_1 X, Y]) - [X, Y],$$

and

$$N_i(X, Y) = [J_i X, J_i Y] - J_i([X, J_i Y] + [J_i X, Y]) + [X, Y], \quad i = 2, 3,$$

for all vector fields X, Y on M . A para-hypercomplex structure on a smooth manifold M is a triple $\{J_i\}_{i=1,2,3}$ such that J_1 is a complex structure and J_i , $i = 2, 3$, are two non-trivial integrable product structures on M satisfying (2.3).

Definition 2.1. A para-hypercomplex structure $\{J_i\}_{i=1,2,3}$ on a Lie group G is said to be left invariant if for any $a \in G$ the following diagram is commutative:

$$\begin{array}{ccc} TG & \xrightarrow{TL_a} & TG \\ J_i \downarrow & & \downarrow J_i \\ TG & \xrightarrow{TL_a} & TG \end{array}$$

That is

$$J_i = TL_a \circ J_i \circ TL_{a^{-1}}, \quad i = 1, 2, 3$$

where $L_a : G \rightarrow G$ given by $L_a(x) = ax$ is the left translation along a and TL_a is its derivation.

A Finsler metric on M is a function $F : TM \rightarrow [0, \infty)$ which has the following properties: (i) F is C^∞ on $TM_0 := TM \setminus \{0\}$; (ii) F is positively 1-homogeneous on the fibers of the tangent bundle TM , and (iii) for each $y \in T_xM$, the following quadratic form \mathbf{g}_y on T_xM is positive definite,

$$\mathbf{g}_y(u, v) := \frac{1}{2} \frac{\partial^2}{\partial s \partial t} \left[F^2(y + su + tv) \right] \Big|_{s,t=0} = g_{ij}(x, y) u^i v^j,$$

$$u = u^i \frac{\partial}{\partial x^i}, v = v^j \frac{\partial}{\partial x^j} \in T_xM,$$

where $g_{ij} = \frac{1}{2} \frac{\partial^2 F^2}{\partial y^i \partial y^j}$ is called the fundamental tensor of F .

An important class of Finsler metrics is the class of (α, β) -metrics which was first introduced by M. Matsumoto in 1992 [16]. An (α, β) -metric on a manifold M is a Finsler metric with the form $F = \alpha \phi(\frac{\beta}{\alpha})$, where $\alpha(x, y) = \sqrt{g_{ij}(x) y^i y^j}$, $\beta(x, y) = b_i(x) y^i$ is a Riemannian metric and a 1-form on the manifold M , respectively and $\phi : (-b_0, b_0) \rightarrow \mathbb{R}^+$ is a C^∞ function satisfying

$$(2.5) \quad \phi(s) - s\phi'(s) > 0, \quad \phi(s) - s\phi'(s) + (b^2 - s^2)\phi''(s) > 0,$$

for all $|s| \leq b < b_0$ in which $b := \|\beta\|$ denotes the norm of β with respect to α (see [17], [26] and [28]).

Given a Finsler manifold (M, F) , then a global vector field \mathbf{G} given by $\mathbf{G} = y^i \frac{\partial}{\partial x^i} - 2G^i(x, y) \frac{\partial}{\partial y^i}$, where

$$(2.6) \quad G^i := \frac{1}{4} g^{il} \left\{ 2 \frac{\partial g_{jl}}{\partial x^k} - \frac{\partial g_{jk}}{\partial x^l} \right\} y^j y^k$$

is called the associated spray to (M, F) . The projection of an integral curve of \mathbf{G} is called a *geodesic* in M . For Riemannian metrics, $G^i(x, y)$ are quadratic with respect to y . For a general Finsler metric F , we define the Berwald curvature of F by

$$(2.7) \quad B_{jkl}^i := \frac{\partial^3 G^i}{\partial y^j \partial y^k \partial y^l}.$$

A Finsler metric is called Berwald metric if its Berwald curvature vanishes [18].

A Finsler metric F on a Lie group G is called left invariant if for all $a \in G$ and $Y \in T_aG$

$$(2.8) \quad F(a, Y) = F(e, (L_{a^{-1}})_* Y).$$

One of the main quantities in Finsler geometry is the flag curvature which is defined as follows:

$$(2.9) \quad K(P, Y) = \frac{g_Y(R(U, Y)Y, U)}{g_Y(Y, Y) \cdot g_Y(U, U) - g_Y^2(Y, U)},$$

where $P = \text{span}\{U, Y\}$ is a 2-plane in $T_x M$, $R(U, Y)Y = \nabla_U \nabla_Y Y - \nabla_Y \nabla_U Y - \nabla_{[U, Y]} Y$ and ∇ is the Chern connection induced by F (for more details, see [4, 25]).

In [6], N. Blažić and S. Vukmirović classified 4-dimensional Lie algebras admitting left invariant para-hypercomplex structures. H. R. Salimi Moghaddam obtained some curvature properties of left invariant Riemannian metrics on such Lie groups [23]. In each case, let G_i be the connected 4-dimensional Lie group corresponding to the considered Lie algebra \mathfrak{g}_i and \langle, \rangle is an inner product on \mathfrak{g}_i such that $\{X, Y, Z, W\}$ is an orthonormal basis for \mathfrak{g}_i . Additionally, we use g for the left invariant Riemannian metric on G_i induced by \langle, \rangle and use ∇ for its Levi-Civita connection. Let us denote the Riemannian curvature tensor of g by R . Furthermore, suppose that $U = aX + bY + cZ + dW$ and $V = \tilde{a}X + \tilde{b}Y + \tilde{c}Z + \tilde{d}W$ are any two independent vectors in \mathfrak{g}_i .

Now, we list all five classes of 4-dimensional Lie algebras admitting an invariant para-hypercomplex structure and non-zero parallel vector fields. These classes of Lie algebras were first introduced in [6].

Case 1. [6] Let \mathfrak{g}_1 be the Lie algebra spanned by the basis $\{X, Y, Z, W\}$ with the following Lie algebra structure:

$$(2.10) \quad [X, Y] = Y, \quad [X, W] = W.$$

Hence, using Koszula's formula, we have

Table 2.1: Taken from [23]

	X	Y	Z	W
∇_X	0	0	0	0
∇_Y	$-Y$	X	0	0
∇_Z	0	0	0	0
∇_W	$-W$	0	0	X

Therefore, for U and V we have

$$R(V, U)U = (a\tilde{b} - b\tilde{a})(bX - aY) + (a\tilde{d} - d\tilde{a})(dX - aW) + (b\tilde{d} - d\tilde{b})(dY - bW).$$

Case 2. [6] The Lie algebra of Case 2 has the following Lie bracket:

$$(2.11) \quad [X, Y] = Z.$$

Therefore

Table 2.2: Taken from [23]

	X	Y	Z	W
∇_X	0	$\frac{1}{2}Z$	$-\frac{1}{2}Y$	0
∇_Y	$-\frac{1}{2}Z$	0	$\frac{1}{2}X$	0
∇_Z	$-\frac{1}{2}Y$	$\frac{1}{2}X$	0	0
∇_W	0	0	0	0

Hence for U and V we have

$$R(V, U)U = \frac{3}{4}(\tilde{a}b - b\tilde{a})(bX - aY) + \frac{1}{4}(a\tilde{c} - c\tilde{a})(aZ - cX) + \frac{1}{4}(b\tilde{c} - c\tilde{b})(bZ - cY).$$

Case 3. [6] The Lie algebra structure of g_3 is in the following form:

$$(2.12) \quad [X, Y] = X.$$

Hence,

Table 2.3: Taken from [23]

	X	Y	Z	W
∇_X	$-Y$	X	0	0
∇_Y	0	0	0	0
∇_Z	0	0	0	0
∇_W	0	0	0	0

as a result, for U and V we have

$$R(V, U)U = (a\tilde{b} - b\tilde{a})(bX - aY).$$

Case 4. [6] In the Lie algebra structure of Case 4, there are two real parameters λ and η . This Lie algebra has the following structure:

$$[X, Z] = X, \quad [X, W] = Y, \quad [Y, Z] = Y, \quad [Y, W] = \lambda X + \eta Y, \quad \lambda, \eta \in \mathbb{R},$$

thus

Table 2.4: Taken from [23]

	X	Y	Z	W
∇_X	$-Z$	$-\frac{(1+\lambda)}{2}W$	X	$\frac{1+\lambda}{2}Y$
∇_Y	$-\frac{(1+\lambda)}{2}W$	$-(Z + \eta W)$	Y	$\frac{(1+\lambda)}{2}X + \eta Y$
∇_Z	0	0	0	0
∇_W	$\frac{\lambda-1}{2}Y$	$\frac{1-\lambda}{2}X$	0	0

Therefore, we have

$$\begin{aligned}
 R(V, U)U &= -\left\{ (a\tilde{b} - b\tilde{a}) \left(b \frac{(1+\lambda)^2 - 4}{4} X + a \frac{4 - (1+\lambda)^2}{4} Y \right) \right. \\
 &+ (a\tilde{c} - c\tilde{a}) \left(aZ + b \frac{1+\lambda}{2} W - cX - d \frac{1+\lambda}{2} Y \right) + (a\tilde{d} - d\tilde{a}) \\
 &\times \left(a \frac{-\lambda^2 + 2\lambda + 3}{4} W + b \frac{1+\lambda}{2} Z + b\eta W - c \frac{1+\lambda}{2} Y \right. \\
 &+ \left. d \frac{(1+\lambda)(\lambda-3)}{4} X - d\eta Y \right) \\
 &+ (b\tilde{c} - c\tilde{b}) \left(a \frac{1+\lambda}{2} W + bZ + b\eta W - cY - d \frac{1+\lambda}{2} X - d\beta Y \right) \\
 &+ (b\tilde{d} - d\tilde{b}) \left(a \frac{1+\lambda}{2} Z + a\eta W + b\eta Z + b \frac{3\lambda^2 + 4\eta^2 + 2\lambda - 1}{4} W \right. \\
 &\left. - c \frac{1+\lambda}{2} X - c\eta Y - d \frac{3\lambda^2 + 4\eta^2 + 2\lambda - 1}{4} Y - \eta dX \right) \left. \right\}.
 \end{aligned}
 \tag{2.13}$$

Case 5. [6] The last Lie algebra is \mathfrak{g}_5 with the following Lie algebra structure:

$$[X, Y] = W, \quad [X, W] = -Y, \quad [Y, W] = -X.
 \tag{2.14}$$

Thus

Table 2.5: Taken from [23]

	X	Y	Z	W
∇_X	0	$\frac{3}{2}W$	X	$-\frac{3}{2}Y$
∇_Y	$\frac{1}{2}W$	$-W$	0	$-\frac{1}{2}X$
∇_Z	0	0	0	0
∇_W	$-\frac{1}{2}Y$	$\frac{1}{2}X$	0	0

Thus for U and V we have

$$R(V, U)U = -\frac{1}{4}\{(a\tilde{b} - b\tilde{a})(bX - aY) + (a\tilde{d} - d\tilde{a})(dX - aW) + 7(b\tilde{d} - d\tilde{b})(-dY + bW)\}.$$

3. Flag curvature of $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$

Let us give a formula for the fundamental tensor of invariant (α, β) -metrics of type $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$, where $a \in (\frac{1}{4}, \infty)$ and α is a left invariant Riemannian metric on a 4-dimensional Lie group G . We consider a left invariant vector field B on G and we let β be the 1-form associated to B with respect to α , that is, for any $x \in G$ and $y \in T_xG$, $\beta_x(y) = \alpha_x(B(x), y)$. Moreover, in the reminder of this section, we require B to be parallel with respect to α , i.e., $\nabla_B B = 0$, where ∇ is the Levi-Civita connection of α . It is known that in this case, the Chern connection of F coincides to the Levi-Civita connection of α , hence F is a Berwald metric [1].

For any non- zero tangent vector $Y \in T_xM$, denote the fundamental tensors of F and α by g_Y and g , respectively. By definition, we have

$$(3.1) \quad g_Y(U, V) := \frac{1}{2} \frac{\partial^2}{\partial s \partial t} \left[F^2(Y + sU + tV) \right]_{|s,t=0}, \quad U, V \in T_xM.$$

$$(3.2) \quad g(U, V) := \frac{1}{2} \frac{\partial^2}{\partial s \partial t} \left[\alpha^2(Y + sU + tV) \right]_{|s,t=0}, \quad U, V \in T_xM.$$

It is easy to see that

$$\begin{aligned} g_Y(U, V) &= \frac{4g(X, Y)^4 g(U, Y)g(V, Y)}{g(X, Y)^3} + \frac{3g(X, Y)^3 g(U, Y)g(V, Y)}{g(Y, Y)^{\frac{5}{2}}} \\ &- \frac{g(X, Y)^3}{g(Y, Y)^2} \left(g(X, Y)g(U, V) + 4g(X, U)g(V, Y) + 4g(X, V)g(U, Y) \right) \\ &- \frac{g(X, Y)}{g(Y, Y)^{\frac{3}{2}}} \left(ag(U, Y)g(V, Y) + g(X, Y)^2 g(U, V) + 3g(X, Y)g(X, U)g(V, Y) \right. \\ &+ \left. 3g(X, Y)g(X, V)g(U, Y) \right) + \frac{6}{g(Y, Y)} \left(g(X, Y)^2 g(X, U)g(X, V) \right) \\ &+ \frac{1}{\sqrt{g(Y, Y)}} \left(ag(X, Y)g(U, V) + 6g(X, Y)g(X, U)g(X, V) + ag(X, U)g(V, Y) \right. \\ (3.3) &+ \left. ag(X, V)g(U, Y) \right) + a^2 g(U, V) + g(X, U)g(X, V) + 2ag(X, U)g(X, V). \end{aligned}$$

Remark 3.1. We know that $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$ is an (α, β) -metric with $\phi(s) = s^2 + s + a$, i.e., $F = \alpha\phi(\frac{\beta}{\alpha})$. By applying the formula obtained by Z. Shen [7], we can also get the

formula of $g_Y(U, V)$. Indeed, we have

$$\begin{aligned}
 g_Y(U, V) &= \phi^2(s)g(U, V) + \phi(s)\phi'(s) \left(-sg(U, V) + g(X, U) \frac{g(V, Y)}{\sqrt{g(Y, Y)}} \right. \\
 &+ \left. g(X, V) \frac{g(U, Y)}{\sqrt{g(Y, Y)}} - s \frac{g(U, V)g(V, Y)}{g(Y, Y)} \right) \\
 &+ \left(\phi(s)\phi''(s) + (\phi'(s))^2 \right) \left(g(X, U)g(X, V) - sg(X, U) \frac{g(V, Y)}{\sqrt{g(Y, Y)}} \right. \\
 (3.4) \quad &- \left. sg(X, V) \frac{g(U, Y)}{\sqrt{g(Y, Y)}} + s^2 \frac{g(U, V)g(V, Y)}{g(Y, Y)} \right),
 \end{aligned}$$

where $s = \frac{g(X, Y)}{\sqrt{g(Y, Y)}}$. It is easy to see that 3.3 and 3.4 coincide.

Let G be a 4-dimensional Lie group admitting an invariant para-hypercomplex structure. As mentioned above, all such Lie groups are classified in [6] [23]. Now we consider the cases 1-5 discussed in [23] and give the explicit formula for their flag curvature in each case. Let $Y := U$ in (3.4), in all cases.

Case 1. Here, the only left invariant and parallel vector field with respect to α is given by $B = qZ$ with $\frac{1}{4} < |q| < \infty$. Note that here $s = \frac{g(qZ, U)}{\sqrt{g(U, U)}} = cq$, where we have used $g(U, U) = 1$. In this case, it follows from (3.4)

$$\begin{aligned}
 g_U(R(V, U)U, V) &= -((\phi(s))^2 - s\phi(s)\phi'(s)) \left((a\tilde{b} - b\tilde{a})^2 + (a\tilde{d} - d\tilde{a})^2 + (b\tilde{d} - d\tilde{b})^2 \right) \\
 g_U(U, U) &= (\phi(s))^2 \\
 g_U(V, V) &= (\phi(s)\phi''(s) + (\phi'(s))^2)(\tilde{c}q)^2 + (\phi(s))^2 - cq\phi(s)\phi'(s) \\
 g_U(U, V) &= \phi(s)\phi'(s)(\tilde{c}q).
 \end{aligned}$$

Let $P = \text{span}\{U, V\}$. In [5], Latifi gives a formula for the flag curvature of a left invariant (α, β) -metric. Using this formula, we get the following

$$K(P, U) = \frac{-((\phi(s))^2 - s\phi(s)\phi'(s)) \{ (a\tilde{b} - b\tilde{a})^2 + (a\tilde{d} - d\tilde{a})^2 + (b\tilde{d} - d\tilde{b})^2 \}}{(\phi(s))^2 \{ (\phi(s)\phi''(s) + (\phi'(s))^2)(\tilde{c}q)^2 + (\phi(s))^2 - cq\phi(s)\phi'(s) \} - (\phi(s)\phi'(s)(\tilde{c}q))^2}.$$

Hence, $K(P, U) \leq 0$. It means that (G, F) has non-positive flag curvature.

Remark 3.2. In [12], L. Huang proved that a left invariant Finsler metric F on a Lie group G admits a direction in which the flag curvature is non-negative, provided $\dim[\mathfrak{g}, \mathfrak{g}] \leq \dim \mathfrak{g} - 2$. Thus, Case 1 shows that we can not replace non-negative with positive in Huang's theorem.

Case 2. We see that the only left invariant and parallel vector field with respect to α is given by $X = qW$ with $\frac{1}{4} < |q| < \infty$. Thus $s = \frac{g(qW,U)}{\sqrt{g(U,U)}} = qd$. A similar argument as in the Case 1 yields

$$\begin{aligned} g_{(RV,U)U,V} &= ((\phi(s))^2 - \phi(s)\phi'(s))\left\{-\frac{3}{4}(a\tilde{b} - b\tilde{a})^2 + \frac{1}{4}(a\tilde{c} - c\tilde{a})^2 + \frac{1}{4}(b\tilde{c} - c\tilde{b})^2\right\} \\ g_U(U,U) &= (\phi(s))^2 \\ g_U(V,V) &= (\phi(s)\phi''(s) + (\phi'(s))^2)(\tilde{d}q)^2 + (\phi(s))^2 - dq\phi(s)\phi'(s) \\ g_U(U,V) &= \phi(s)\phi'(s)(\tilde{d}q). \end{aligned}$$

We obtain the flag curvature as follows:

$$K(P,U) = \frac{((\phi(s))^2 - \phi(s)\phi'(s))\left\{-\frac{3}{4}(a\tilde{b} - b\tilde{a})^2 + \frac{1}{4}(a\tilde{c} - c\tilde{a})^2 + \frac{1}{4}(b\tilde{c} - c\tilde{b})^2\right\}}{\phi^2(s)\left\{(\phi(s))^2 - dq\phi(s)\phi'(s) + (\phi(s)\phi''(s) + (\phi'(s))^2)(\tilde{d}q)^2\right\} - (\phi(s)\phi'(s)(\tilde{d}q))^2}.$$

Unlike Case 1, in this case (G, F) admits both positive and negative flag curvature.

Case 3. According to [23], (G_3, g) admits a parallel left invariant vector field $X = q_1Z + q_2W$ such that $\frac{1}{4} < |q_1^2 + q_2^2| < \infty$. As in the previous cases, we get $s = cq_1 + dq_2$.

$$\begin{aligned} g_U(RV,U)U,V &= -(\phi(s))^2 - s\phi(s)\phi'(s)(a\tilde{b} - b\tilde{a})^2 \\ g_U(U,U) &= (\phi(s))^2 \\ g_U(V,V) &= (\phi(s)\phi''(s) + (\phi'(s))^2)(\tilde{c}q_1 + \tilde{d}q_2) + (\phi(s))^2 - (cq_1 + dq_2)\phi(s)\phi'(s) \\ g_U(U,V) &= \phi(s)\phi'(s)(\tilde{c}q_1 + \tilde{d}q_2) \end{aligned}$$

Therefore, the flag curvature of F is as follows:

$$(3.5) \quad K(P,U) = \frac{-\{\phi^2(s) - s\phi(s)\phi'(s)\}(a\tilde{b} - b\tilde{a})^2}{\Psi},$$

where

$$\Psi := \phi^2\{(\phi\phi'' + \phi'^2)(\tilde{c}q_1 + \tilde{d}q_2) + \phi^2 - (cq_1 + dq_2)\phi\phi'\} - (\phi\phi'(\tilde{c}q_1 + \tilde{d}q_2))^2 \geq 0.$$

Case 4. In [23], it has been shown that vector fields which are parallel to (G_4, g) , are of the form $X = qW$ such that $\frac{1}{4} < |q| < \infty$. Thus $s = dq$ and we have:

$$\begin{aligned} g_U(RV,U)U,V &= -((\phi(s))^2 - s\phi(s)\phi'(s))((a\tilde{c} - c\tilde{a})^2 + (b\tilde{c} - c\tilde{b})^2) \\ g_U(U,U) &= (\phi(s))^2 \\ g_U(V,V) &= (\phi(s)\phi''(s) + (\phi'(s))^2)(\tilde{d}q)^2 + (\phi(s))^2 - dq\phi(s)\phi'(s) \\ g_U(U,V) &= \phi(s)\phi'(s)(\tilde{d}q). \end{aligned}$$

We have the flag curvature of F as follows:

$$K(P, U) = \frac{(-(\phi(s))^2 - dq\phi(s)\phi'(s))\{(a\tilde{c} - c\tilde{a})^2 + (b\tilde{c} - c\tilde{b})^2\}}{(\phi(s))^2\{(\phi(s)\phi''(s) + \phi'(s)^2)(\tilde{d}q)^2 + \phi^2(s) - dq\phi(s)\phi'(s)\} - (\phi(s)\phi'(s)(\tilde{d}q))^2},$$

which are always non-positive.

Case 5. In [23], it has been shown that the parallel left invariant vector fields are of the form $X = qZ$ such that $\frac{1}{4} < |q| < \infty$. Thus $s = cq$ and we get:

$$\begin{aligned} g_U(RV, U)U, V &= -\frac{1}{4}((\phi(s))^2 - cq\phi(s)\phi'(s))\{(a\tilde{b} - b\tilde{a})^2 + (a\tilde{d} - d\tilde{a})^2 + 7(b\tilde{d} - d\tilde{b})^2\} \\ g_U(U, U) &= (\phi(s))^2 \\ g_U(V, V) &= (\phi(s)\phi''(s) + \phi'(s)^2)(\tilde{c}q)^2 + (\phi(s))^2 - cq\phi(s)\phi'(s) \\ g_U(U, V) &= \phi(s)\phi'(s)(\tilde{c}q), \end{aligned}$$

Moreover, the flag curvature is given by the following:

$$K(P, U) = \frac{-\frac{1}{4}((\phi(s))^2 - cq\phi(s)\phi'(s))\{(a\tilde{b} - b\tilde{a})^2 + (a\tilde{d} - d\tilde{a})^2 + 7(b\tilde{d} - d\tilde{b})^2\}}{(\phi(s))^2\{(\phi(s)\phi''(s) + \phi'(s)^2)(\tilde{c}q)^2 + (\phi(s))^2 - cq\phi(s)\phi'(s)\} - (\phi(s)\phi'(s)(\tilde{c}q))^2}.$$

which are always non-positive.

Sumarizing the above results, we get the following.

Theorem 3.1. *In all above cases, except for the Case 2, the flag curvature of F is non-positive. Moreover, in Case 2, (G, F) admits both positive and negative flag curvature.*

Remark 3.3. In [10], S. Deng proved that if a G -invariant Randers metric $F = \alpha + \beta$ on a homogeneous manifold $\frac{G}{H}$, which is Douglas type, has negative flag curvature, then the sectional curvature of α is negative. Case 5 shows that this fact is no longer true for (α, β) -metric of type $F = \beta + \alpha + \frac{\beta^2}{\alpha}$.

4. Geodesic vectors

In this section, we discuss the geodesic vectors of a left invariant Finsler metric $F = \beta + \frac{\alpha\alpha^2 + \beta^2}{\alpha}$ on a 4-dimensional Lie group G admitting an invariant parahypercomplex structure. We still assume that β is parallel with respect to α . Let us recall the definition of geodesic vectors.

Definition 4.1. Let F be a left invariant Finsler metric on a Lie group G . A non-zero tangent vector $B \in T_e G$ is said to be a geodesic vector of F , if the 1-parameter subgroup $t \rightarrow \exp(tB)$, $t \in \mathbb{R}_+$ is a geodesic of F .

To find all geodesic vectors of a left invariant Finsler metric $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$ on a 4-dimensional Lie group G admitting an invariant para-hypercomplex structure, we need the following propositions.

Proposition 4.1. (see [14]) Let G be a connected Lie group with Lie algebra \mathfrak{g} , and let F be a left-invariant Finsler metric on G . Then a non-zero vector $B \in \mathfrak{g}$ is a geodesic vector of F if and only if for every $Z \in \mathfrak{g}$

$$(4.1) \quad g_B([B, Z], B) = 0,$$

Proposition 4.2. Let G be a connected Lie group with Lie algebra \mathfrak{g} , and let F be a left-invariant (α, β) -Berwald Finsler metric on G . Then a non-zero vector $B \in \mathfrak{g}$ is a geodesic vector of F if and only if it is a geodesic vector of α .

Now, we find all geodesic vectors in each case of all five classes given in [23], while they equipped with Left invariant Finsler metric $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$. Using Proposition 4.1 and 4.2, we obtain all geodesic vectors of $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$ as follows.

Theorem 4.1. The geodesic vectors of left invariant finsler metric $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$ are given by the following

geodesic vectors	
Case 1	$\{aX + cZ \mid a, c \in \mathbb{R}\}$
Case 2	$\{aX + bY + cZ + dW \mid bc = ac = 0\}$
Case 3	$\{bY + cZ + dW \mid b, c, d \in \mathbb{R}\}$
Case 4	$\{aX + cZ + dW \mid ac = ad\lambda = 0\}$
Case 5	$\{aX + bY + cZ + dW \mid ad = ab = 0\}$

Now, we obtain a relation between the geodesic vectors of a general (α, β) -metric F and a Riemannian metric g .

Theorem 4.2. Let G be a Lie group and $F = \alpha\phi(\frac{\beta}{\alpha})$ be an (α, β) -metric arising from a Riemannian metric g and a left invariant vector field B , i.e., $\alpha(x, y) = \sqrt{g_x(y, y)}$ and $\beta(x, y) = \alpha_x(B, y)$ Suppose that $Y \in \mathfrak{g}$ is a unit vector for which $g(B, [Y, Z]) = 0$ for all $Z \in \mathfrak{g}$. Then Y is a geodesic vector of (M, F) if and only if Y is a geodesic vector of (M, g) .

Proof. Using (3.3) and taking into account $g(B, [Y, Z]) = 0$ for all $Z \in \mathfrak{g}$, we have

$$(4.2) \quad g_Y(Y, [Y, Z]) = \left(\phi^2(s) - \phi(s)\phi'(s) \frac{g(B, Y)}{\sqrt{g(Y, Y)}} \right) g(Y, [Y, Z]),$$

Let Y be a geodesic vector of g . Replacing (4.1) into (4.2) and using $g(B, [Y, Z]) = 0$, we have Y is a geodesic vector of (M, F) .
Conversely, let Y be a unit geodesic vector of (M, F) . We have

$$(4.3) \quad \left(\phi^2(s) - \phi(s)\phi'(s)g(X, Y) \right) g(Y, [Y, Z]) = 0,$$

This completes the proof. \square

Theorem 4.3. *Let (G, F) be a connected Lie group and $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$ be a left- invariant Finsler metric of Berwald type on G defined by the Riemannian metric α and the vector field B . Then (G, F) is complete.*

Proof. Since F is of the Berwald type then (G, F) and (G, α) have the same connection also $\nabla B = 0$ where ∇ is Riemannian connection of α . On the other hand (G, α) is a Lie group and hence a complete space. As (G, F) and (G, α) have the same geodesics. We show that these geodesics have constant Finsler speed. Let $\sigma(t)$, $-\infty < t < \infty$ be a geodesic for F , we have

$$F(\sigma(t), \dot{\sigma}(t)) = g_{\sigma(t)}(B, \dot{\sigma}(t)) + a\sqrt{g_{\sigma(t)}(\dot{\sigma}(t), \dot{\sigma}(t))} + \frac{g_{\sigma(t)}^2(B, \dot{\sigma}(t))}{\sqrt{g_{\sigma(t)}(\dot{\sigma}(t), \dot{\sigma}(t))}}$$

Since $g_{\sigma(t)}(\dot{\sigma}(t), \dot{\sigma}(t))$ is constant, it is enough to show that $g_{\sigma(t)}(B, \dot{\sigma}(t))$ is also constant. we have

$$(4.4) \quad \frac{d}{dt}(g_{\sigma(t)}(B, \dot{\sigma}(t))) = g_{\sigma(t)}(\nabla_{\dot{\sigma}(t)} B, \dot{\sigma}(t)) + g_{\sigma(t)}(B, \nabla_{\dot{\sigma}(t)} \dot{\sigma}(t)) = 0$$

Then this yields that these geodesics have constant Finsler speed. \square
The following Proposition can be found in [14].

Proposition 4.3. *Let (M, F) be a forward geodesically complete Finsler manifold. If X is a vector field such that $F(X)$ is bounded, then X is a forward complete vector field.*

Using Proposition 4.3, we get the following.

Theorem 4.4. *Let (G, F) be a connected Lie group and $F = \beta + \frac{a\alpha^2 + \beta^2}{\alpha}$ be a left- invariant Finsler metric of Berwald type. Then the vector field B is complete.*

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