

ON THREE-DIMENSIONAL TRANS-SASAKIAN MANIFOLDS ADMITTING SCHOUTEN-VAN KAMPEN CONNECTION

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Abstract. In the present paper, we study three-dimensional trans-Sasakian manifolds admitting the Schouten-van Kampen connection. Also, we have proved some results on ϕ -projectively flat, ξ -projectively flat and ξ -concurcularly flat three-dimensional trans-Sasakian manifolds with respect to the Schouten-van Kampen connection. Locally ϕ -symmetric trans-Sasakian manifolds of dimension three have been studied with respect to Schouten-van Kampen connection. Finally, we construct an example of a three-dimensional trans-Sasakian manifold admitting Schouten-van Kampen connection which verifies Theorem 4.1. and Theorem 5.2.

Key words: General geometric structures on manifolds, Schouten-van Kampen connection, Special Riemannian manifolds

1. Introduction

The Schouten-van Kampen connection is one of the most natural connections adapted to a pair of complementary distributions on a differentiable manifold endowed with an affine connection. Solov'ev investigated hyperdistributions in Riemannian manifolds using the Schouten-van Kampen connection ([18], [19], [20], [21]). In 2014, Olszak studied the Schouten-van Kampen connection to adapt it to an almost contact metric structure [17]. He characterized some classes of almost contact metric manifolds with the Schouten-van Kampen connection. Recently, G. Ghosh [10], Yildiz [26], Nagaraja [15] and D. L. Kiran Kumar [12] have studied the

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Schouten-van Kampen connection in Sasakian manifolds, f -Kenmotsu manifolds and Kenmotsu manifolds respectively.

A transformation of an n -dimensional differentiable manifold M , which transforms every geodesic circle of M into a geodesic circle, is called a concircular transformation [27], [13]. A concircular transformation is always a conformal transformation [13]. Here geodesic circle means a curve in M whose first curvature is constant and whose second curvature is identically zero. Thus the geometry of concircular transformations, i.e., the concircular geometry, is a generalization of inversive geometry in the sense that the change of metric is more general than that induced by a circle preserving diffeomorphism. An interesting invariant of a concircular transformation is the concircular curvature tensor \mathbb{W} with respect to Levi-Civita connection. It is defined by [27], [28]

$$(1.1) \quad \mathbb{W}(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)}[g(Y, Z)X - g(X, Z)Y],$$

where $X, Y, Z \in \chi(M)$, R and r are the curvature tensor and the scalar curvature with respect to the Levi-Civita connection.

The concircular curvature tensor $\tilde{\mathbb{W}}$ with respect to the Schouten-van Kampen connection is defined by

$$(1.2) \quad \tilde{\mathbb{W}}(X, Y)Z = \tilde{R}(X, Y)Z - \frac{\tilde{r}}{n(n-1)}[g(Y, Z)X - g(X, Z)Y],$$

where \tilde{R} and \tilde{r} are the curvature tensor and the scalar curvature with respect to the Schouten-van Kampen connection. Riemannian manifolds with vanishing concircular curvature tensor are of constant curvature. Thus the concircular curvature tensor is a measure of the failure of a Riemannian manifold to be of constant curvature.

In 1985, a new class of n -dimensional almost contact manifold namely trans-Sasakian manifold was introduced by J. A. Oubina [16] and further study about the local structures of trans-Sasakian manifolds was carried by J. C. Marrero [14]. Trans-Sasakian manifolds of type $(0, 0)$, $(\alpha, 0)$ and $(0, \beta)$ are, called the cosymplectic, α -Sasakian and β -Kenmotsu respectively ([2], [11]). In particular, if $\alpha = 0, \beta = 1; \alpha = 1, \beta = 0$; then a trans-Sasakian manifold becomes Kenmotsu and Sasakian manifolds respectively. Hence, trans-Sasakian structures give a large class of generalized Quasi-Sasakian structures. It has been proven that a trans-Sasakian manifold of dimension $n \geq 5$ is either cosymplectic or α -Sasakian and β -Kenmotsu manifold. Three-dimensional trans-Sasakian manifolds with different restrictions on curvature and smooth functions α, β are studied in ([7], [8], [5], [6]).

In the present paper, we have studied three-dimensional trans-Sasakian manifolds with respect to the Schouten-van Kampen connection.

The present paper is organized as follows: After the introduction in Section 1, we give some required preliminaries in Section 2. Section 3 is devoted to the study of the curvature tensor, the Ricci tensor, scalar curvature of a three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection. Section 4

is devoted to the study of ξ -projectively and ϕ -projectively flat trans-Sasakian manifolds of dimension three with respect to the Schouten-van Kampen connection. In this section, we have proved that a three-dimensional trans-Sasakian manifold admitting the Schouten-van Kampen connection is ξ -projectively flat if and only if the scalar curvature of the manifold vanishes. In Section 5, we study ξ -concurrently flat trans-Sasakian manifold of dimension three admitting Schouten-van Kampen connection. In the next section, we study locally ϕ -symmetric trans-Sasakian manifolds of dimension three with respect to Schouten-van Kampen connection. In Section 7, we study Weyl ξ -conformally flat in three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection. In the last section, we construct an example of a three-dimensional trans-Sasakian manifold admitting the Schouten-van Kampen connection to support the results obtained in Section 4 and Section 5.

2. Preliminaries

Let M be a connected almost contact metric manifold with an almost contact metric structure (ϕ, ξ, η, g) , that is, ϕ is an $(1, 1)$ tensor field, ξ is a vector field, η is an 1-form and g is compatible Riemannian metric such that

$$(2.1) \quad \phi^2 X = -X + \eta(X)\xi, \quad \eta(\xi) = 1, \quad \phi\xi = 0, \quad \eta\phi = 0,$$

$$(2.2) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y),$$

$$(2.3) \quad g(X, \phi Y) = -g(\phi X, Y), \quad g(X, \xi) = \eta(X),$$

for all $X, Y \in T(M)$ [1]. The fundamental 2-form Φ of the manifold is defined by

$$(2.4) \quad \Phi(X, Y) = g(X, \phi Y),$$

for $X, Y \in T(M)$.

An almost contact metric manifold is normal if $[\phi, \phi](X, Y) + 2d\eta(X, Y)\xi = 0$.

An almost contact metric structure (ϕ, ξ, η, g) on a manifold M is called trans-Sasakian structure [16] if $(M \times R, J, G)$ belongs to the class W_4 [9], where J is the almost complex structure on $M \times R$ defined by

$$J(X, fd/dt) = (\phi X - f\xi, \eta(X)d/dt),$$

for all vector fields X on M , a smooth function f on $M \times R$ and the product metric G on $M \times R$. This may be expressed by the condition [3]

$$(2.5) \quad (\nabla_X \phi)Y = \alpha(g(X, Y)\xi - \eta(Y)X) + \beta(g(\phi X, Y)\xi - \eta(Y)\phi X),$$

for smooth functions α and β on M . Here ∇ is Levi-Civita connection on M . We say M as the trans-Sasakian manifold of type (α, β) . From (2.5) it follows that

$$(2.6) \quad \nabla_X \xi = -\alpha\phi X + \beta(X - \eta(X)\xi),$$

$$(2.7) \quad (\nabla_X \eta)Y = -\alpha g(\phi X, Y) + \beta g(\phi X, \phi Y).$$

In a three-dimensional trans-Sasakian manifold following relations hold [7], [8]:

$$(2.8) \quad 2\alpha\beta + \xi\alpha = 0,$$

$$(2.9) \quad \begin{aligned} S(X, Y) &= \left\{ \frac{r}{2} + \xi\beta - (\alpha^2 - \beta^2) \right\} g(X, Y) \\ &- \left\{ \frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2) \right\} \eta(X)\eta(Y) - \{Y\beta + (\phi X)\alpha\}\eta(Y), \end{aligned}$$

$$(2.10) \quad \begin{aligned} R(X, Y)Z &= \left(\frac{r}{2} + 2\xi\beta - 2(\alpha^2 - \beta^2) \right) (g(Y, Z)X - g(X, Z)Y) \\ &- g(Y, Z) \left[\left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2) \right) \eta(X)\xi \right. \\ &- \eta(X)(\phi \operatorname{grad}\alpha - \operatorname{grad}\beta) + (X\beta + (\phi X)\alpha)\xi \left. \right] \\ &+ g(X, Z) \left[\left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2) \right) \eta(Y)\xi \right. \\ &- \eta(Y)(\phi \operatorname{grad}\alpha - \operatorname{grad}\beta) + (Y\beta + (\phi Y)\alpha)\xi \left. \right] \\ &- [(Z\beta + (\phi Z)\alpha)\eta(Y) + (Y\beta + (\phi Y)\alpha)\eta(Z) \\ &+ \left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2) \right) \eta(Y)\eta(Z)]X \\ &+ [(Z\beta + (\phi Z)\alpha)\eta(X) + (X\beta + (\phi X)\alpha)\eta(Z) \\ &+ \left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2) \right) \eta(X)\eta(Z)]Y, \end{aligned}$$

where S is the Ricci tensor of type $(0, 2)$, and r is the scalar curvature of the manifold M with respect to Levi-Civita connection.

From here after we consider α and β are constants, then the above relations become

$$(2.11) \quad \begin{aligned} R(X, Y)Z &= \left\{ \frac{r}{2} - (\alpha^2 - \beta^2) \right\} [g(Y, Z)X - g(X, Z)Y] \\ &+ \left\{ \frac{r}{2} - (\alpha^2 - \beta^2) \right\} [g(X, Z)\eta(Y) - g(Y, Z)\eta(X)]\xi \\ &+ \left\{ \frac{r}{2} - 3(\alpha^2 - \beta^2) \right\} [\eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X], \end{aligned}$$

$$(2.12) \quad \begin{aligned} S(X, Y) &= \left\{ \frac{r}{2} - (\alpha^2 - \beta^2) \right\} g(X, Y) \\ &- \left\{ \frac{r}{2} - 3(\alpha^2 - \beta^2) \right\} \eta(X)\eta(Y), \end{aligned}$$

$$(2.13) \quad S(X, \xi) = 2(\alpha^2 - \beta^2)\eta(X),$$

$$(2.14) \quad QX = \left\{ \frac{r}{2} - (\alpha^2 - \beta^2) \right\} X - \left\{ \frac{r}{2} - 3(\alpha^2 - \beta^2) \right\} \eta(X)\xi,$$

$$(2.15) \quad R(X, Y)\xi = (\alpha^2 - \beta^2)(\eta(Y)X - \eta(X)Y),$$

$$(2.16) \quad R(\xi, X)Y = 2(\alpha^2 - \beta^2)(g(X, Y)\xi - \eta(Y)X).$$

From (2.8) it follows that if α and β are constants, then the manifold is either α -Sasakian or β -Kenmotsu or cosymplectic.

3. Curvature tensor of a three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection

For an almost contact metric manifold M , the Schouten-van Kampen connection $\tilde{\nabla}$ is given by [17]

$$(3.1) \quad \tilde{\nabla}_X Y = \nabla_X Y - \eta(Y)\nabla_X \xi + (\nabla_X \eta)(Y)\xi.$$

Let M be a three-dimensional trans-Sasakian manifold. Then from above equation we have

$$(3.2) \quad \tilde{\nabla}_X Y = \nabla_X Y + \alpha\{\eta(Y)\phi X - g(\phi X, Y)\xi\} + \beta\{g(X, Y)\xi - \eta(Y)X\}.$$

We define the curvature tensor \tilde{R} of a three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ by

$$(3.3) \quad \tilde{R}(X, Y)Z = \tilde{\nabla}_X \tilde{\nabla}_Y Z - \tilde{\nabla}_Y \tilde{\nabla}_X Z - \tilde{\nabla}_{[X, Y]}Z.$$

In view of (3.2) and (3.3) we obtain

$$(3.4) \quad \begin{aligned} \tilde{R}(X, Y)Z &= R(X, Y)Z + \alpha^2\{g(\phi Y, Z)\phi X - g(\phi X, Z)\phi Y \\ &\quad + \eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X \\ &\quad - g(Y, Z)\eta(X)\xi + g(X, Z)\eta(Y)\xi\} \\ &\quad + \beta^2\{g(Y, Z)X - g(X, Z)Y\}. \end{aligned}$$

Taking inner product in both sides of (3.4) with W , we have

$$(3.5) \quad \begin{aligned} \tilde{R}(X, Y, Z, W) &= R(X, Y, Z, W) + \alpha^2\{g(\phi Y, Z)g(\phi X, W) - g(\phi X, Z)g(\phi Y, W) \\ &\quad + g(Y, W)\eta(X)\eta(Z) - g(X, W)\eta(Y)\eta(Z) \\ &\quad - g(Y, Z)\eta(X)\eta(W) + g(X, Z)\eta(Y)\eta(W)\} \\ &\quad + \beta^2\{g(Y, Z)g(X, W) - g(X, Z)g(Y, W)\}, \end{aligned}$$

where $\tilde{R}(X, Y, Z, W) = g(\tilde{R}(X, Y)Z, W)$.

Taking a frame field from (3.5), we get

$$(3.6) \quad \tilde{S}(Y, Z) = S(Y, Z) + 2\beta^2 g(Y, Z) - 2\alpha^2 \eta(Y)\eta(Z).$$

From above equation we have

$$(3.7) \quad \tilde{Q}Y = QY + 2\beta^2 Y - 2\alpha^2 \eta(Y)\xi.$$

Again putting $Y = Z = e_i$ ($i = 1, 2, 3$) and taking summation over i in (3.6), we obtain

$$(3.8) \quad \tilde{r} = r - 2\alpha^2 + 6\beta^2,$$

where \tilde{r} and r are the scalar curvatures of the Schouten-van Kampen connection ($\tilde{\nabla}$) and Levi-Civita connection (∇) respectively.

Hence we have the following :

Proposition 3.1. A three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection following statements are equivalent

- (a) The curvature tensor \tilde{R} is given by (3.4),
 - (b) The Ricci tensor \tilde{S} is given by (3.6),
 - (c) $\tilde{r} = r - 2\alpha^2 + 6\beta^2$,
 - (d) The Ricci tensor \tilde{S} is symmetric,
- provided α and β are constants.

4. ξ -Projectively and ϕ -projectively flat trans-Sasakian manifolds with respect to the Schouten-van Kampen connection

In this section, we study projectively flat three-dimensional trans-Sasakian manifold M with respect to the Schouten-van Kampen connection. In a three-dimensional trans-Sasakian manifold, the projective curvature tensor with respect to the Schouten-van Kampen connection is given by

$$(4.1) \quad \tilde{P}(X, Y)Z = \tilde{R}(X, Y)Z - \frac{1}{2}\{\tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y\}.$$

Definition 4.1. A three-dimensional trans-Sasakian manifold M with respect to the Schouten-van Kampen connection is said to be ξ -projectively flat if

$$\tilde{P}(X, Y)\xi = 0,$$

for all vector fields X, Y on M . This notion was first defined by Tripathi and Dwivedi [22]. If $\tilde{P}(X, Y)\xi = 0$, just holds for X, Y orthogonal to ξ , we call such a manifold a horizontal ξ -projectively flat manifold.

Using (3.4) in (4.1) we have

$$\begin{aligned}
 \tilde{P}(X, Y)Z &= R(X, Y)Z + \alpha^2\{g(\phi Y, Z)\phi X - g(\phi X, Z)\phi Y \\
 &\quad + \eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X \\
 &\quad - g(Y, Z)\eta(X)\xi + g(X, Z)\eta(Y)\xi\} \\
 &\quad + \beta^2\{g(Y, Z)X - g(X, Z)Y\} \\
 (4.2) \quad &\quad - \frac{1}{2}\{\tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y\}.
 \end{aligned}$$

Putting $Z = \xi$ and using (2.1), (2.3), (2.15) and (3.6) in (4.2), we get

$$(4.3) \quad \tilde{P}(X, Y)\xi = 0.$$

Thus we can state the following:

Theorem 4.1. A three-dimensional trans-Sasakian manifold is ξ -projectively flat with respect to the Schouten-van Kampen connection provided α and β are constants.

Again putting (3.6) in (4.2) we get

$$\begin{aligned}
 \tilde{P}(X, Y)Z &= P(X, Y)Z + \alpha^2\{g(\phi Y, Z)\phi X - g(\phi X, Z)\phi Y \\
 (4.4) \quad &\quad - g(Y, Z)\eta(X)\xi + g(X, Z)\eta(Y)\xi\}.
 \end{aligned}$$

Putting $Z = \xi$ in (4.4) and using (2.1) and (2.3), it follows that

$$(4.5) \quad \tilde{P}(X, Y)\xi = P(X, Y)\xi.$$

In view of above discussion we state the following theorem:

Theorem 4.2. A three-dimensional trans-Sasakian manifold is ξ -projectively flat with respect to the Schouten-van Kampen connection if and only if the manifold is ξ -projectively flat with respect to the Levi-Civita connection provided α and β are constants.

Definition 4.2. A trans-Sasakian manifold M with respect to the Schouten-van Kampen connection is said to be ϕ -projectively flat if

$$\phi^2\tilde{P}(\phi X, \phi Y)\phi Z = 0.$$

It can be easily seen that $\phi^2\tilde{P}(\phi X, \phi Y)\phi Z = 0$ holds if and only if

$$(4.6) \quad g(\tilde{P}(\phi X, \phi Y)\phi Z, \phi W) = 0,$$

for $X, Y, Z, W \in T(M)$.

Using (4.1) and (4.6), ϕ -projectively flat means

$$(4.7) \quad g(\tilde{R}(\phi X, \phi Y)\phi Z, \phi W) = \frac{1}{2}\{\tilde{S}(\phi Y, \phi Z)g(\phi X, \phi W) - \tilde{S}(\phi X, \phi Z)g(\phi Y, \phi W)\}.$$

Let $\{e_1, e_2, \xi\}$ be a local orthonormal basis of the vector fields in M and using the fact that $\{\phi e_1, \phi e_2, \xi\}$ is also a local orthonormal basis, putting $X = W = e_i$ in (4.7) and summing up with respect to i , we have

$$(4.8) \quad \sum_{i=1}^2 g(\tilde{R}(\phi e_i, \phi Y)\phi Z, \phi e_i) = \frac{1}{2} \sum_{i=1}^2 \{\tilde{S}(\phi Y, \phi Z)g(\phi e_i, \phi e_i) - \tilde{S}(\phi e_i, \phi Z)g(\phi Y, \phi e_i)\}.$$

Using (2.1), (2.2), (2.3) and (3.5) it can be easily verified that

$$(4.9) \quad \sum_{i=1}^2 g(\tilde{R}(\phi e_i, \phi Y)\phi Z, \phi e_i) = \sum_{i=1}^2 g(R(\phi e_i, \phi Y)\phi Z, \phi e_i) + (\alpha^2 + \beta^2)g(Y, Z) + (\beta^2 - 3\alpha^2)\eta(Y)\eta(Z)$$

$$(4.10) \quad = S(\phi Y, \phi Z) + (\alpha^2 + \beta^2)g(Y, Z) + (\beta^2 - 3\alpha^2)\eta(Y)\eta(Z).$$

$$(4.11) \quad \sum_{i=1}^2 g(\phi e_i, \phi e_i) = 2.$$

$$(4.12) \quad \sum_{i=1}^2 \tilde{S}(\phi e_i, \phi Z)g(\phi Y, \phi e_i) = \tilde{S}(\phi Y, \phi Z).$$

Using (4.9), (4.10) and (4.11), the equation (4.8) becomes

$$(4.13) \quad \tilde{S}(\phi Y, \phi Z) = 2\{S(\phi Y, \phi Z) + (\alpha^2 + \beta^2)g(Y, Z) + (\beta^2 - 3\alpha^2)\eta(Y)\eta(Z)\}.$$

Using (3.6) in (4.12), we get

$$(4.14) \quad S(\phi Y, \phi Z) = -2\alpha^2 g(Y, Z) + 2(3\alpha^2 - \beta^2)\eta(Y)\eta(Z).$$

Putting $Y = \phi Y$ and $Z = \phi Z$ in (4.13) and using (2.1) (2.2) and (2.13), we obtain

$$(4.15) \quad S(Y, Z) = -2\alpha^2 g(Y, Z) + 2(2\alpha^2 - \beta^2)\eta(Y)\eta(Z).$$

Conversely, let S be of the form (4.14), then obviously

$$g(\tilde{P}(\phi X, \phi Y)\phi Z, \phi W) = 0.$$

Thus we can state the following:

Theorem 4.3. A three-dimensional trans-Sasakian manifold admitting the Schouten-van Kampen connection is ϕ -projectively flat if and only if the manifold is an η -Einstein manifold with respect to the Levi-Civita connection provided α, β are constants with $\beta \neq \pm\sqrt{2}\alpha, (\alpha \neq 0)$.

5. ξ -Concircularly flat trans-Sasakian manifolds with respect to the Schouten-van Kampen connection

Definition 5.1. A trans-Sasakian manifold M with respect to the Schouten-van Kampen connection is said to be ξ -concircularly flat if

$$(5.1) \quad \tilde{W}(X, Y)\xi = 0,$$

for all vector fields $X, Y \in \chi(M)$, $\chi(M)$ is the set of all differentiable vector fields on M .

Theorem 5.1. A three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection is horizontally ξ -concircularly flat if and only if the manifold with respect to the Levi-Civita connection is also ξ -concircular flat provided α, β are constants.

Proof. Combining (1.1),(1.2) and using (3.4), (3.6) (3.8), we get

$$(5.2) \quad \begin{aligned} \tilde{W}(X, Y)Z &= W(X, Y)Z + \alpha^2\{g(\phi Y, Z)\phi X - g(\phi X, Z)\phi Y \\ &\quad -g(Y, Z)\eta(X)\xi + g(X, Z)\eta(Y)\xi \\ &\quad -\eta(Y)\eta(Z)X + \eta(X)\eta(Z)Y\}. \end{aligned}$$

Putting $Z = \xi$ in (5.2) we get

$$(5.3) \quad \tilde{W}(X, Y)\xi = W(X, Y)\xi + \frac{2\alpha^2}{3}\{\eta(X)Y - \eta(Y)X\}.$$

From (5.3), implies that

$$(5.4) \quad \tilde{W}(X, Y)\xi = W(X, Y)\xi; \quad \text{for all } X, Y \text{ orthogonal to } \xi.$$

Hence the proof of theorem is complete.

Theorem 5.2. A three-dimensional trans-Sasakian manifold is ξ -concircularly flat with respect to the Schouten-van Kampen connection if and only if the scalar curvature \tilde{r} is zero, provided α and β are constants.

Proof. Putting $Z = \xi$ in (1.2) and using (2.1), (2.3), (2.3), (2.15) and (3.4), we have

$$(5.5) \quad \tilde{W}(X, Y)\xi = -\frac{\tilde{r}}{6}\{\eta(Y)X - \eta(X)Y\}.$$

Thus the theorem is proved.

6. Locally ϕ -symmetric trans-Sasakian manifolds with respect to the Schouten-van Kampen connection

Definition 6.1. A trans-Sasakian manifold M with respect to the Schouten-van Kampen connection is called to be locally ϕ -symmetric if

$$(6.1) \quad \phi^2(\tilde{\nabla}_W \tilde{R})(X, Y)Z = 0,$$

for all vector fields X, Y, Z, W orthogonal to ξ on M . This notion was introduced by Takahashi [24], for Sasakian manifolds.

We know that

$$(6.2) \quad \begin{aligned} (\tilde{\nabla}_W \tilde{R})(X, Y)Z &= \tilde{\nabla}_W(\tilde{R}(X, Y)Z) - \tilde{R}(\tilde{\nabla}_W X, Y)Z \\ &\quad - R(X, \tilde{\nabla}_W Y)Z - \tilde{R}(X, Y)\tilde{\nabla}_W Z. \end{aligned}$$

By virtue of (3.1), above equation is reduced to

$$(6.3) \quad \begin{aligned} (\tilde{\nabla}_W \tilde{R})(X, Y)Z &= (\nabla_W \tilde{R})(X, Y)Z + \eta(X)\tilde{R}(\nabla_W \xi, Y)Z + (\nabla_W \eta)(X)\tilde{R}(\xi, Y)Z \\ &\quad + \eta(Y)\tilde{R}(X, \nabla_W \xi)Z + (\nabla_W \eta)(Y)\tilde{R}(X, \xi)Z \\ &\quad + \eta(Z)\tilde{R}(X, Y)\nabla_W Z + (\nabla_W \eta)(Z)\tilde{R}(X, Y)\xi. \end{aligned}$$

Now differentiating (3.4) with respect to W , using (2.1), (2.2), (2.3), (2.5) and (2.7) we obtain

$$(6.4) \quad \begin{aligned} (\nabla_W \tilde{R})(X, Y)Z &= (\nabla_W R)(X, Y)Z \\ &\quad + \alpha^3 \{g(X, Y)g(\phi Y, Z) - g(W, Y)g(\phi X, Z)\}\xi \\ &\quad + \{g(\phi X, Z)\eta(Y) - g(\phi Y, Z)\eta(X)\}W \\ &\quad + \alpha^2 \beta \{g(\phi W, X)g(\phi Y, Z) - g(\phi W, Y)g(\phi X, Z)\}\xi \\ &\quad + \{g(\phi X, Z)\eta(Y) - g(\phi Y, Z)\eta(X)\}\phi W \\ &\quad + (\alpha^2 - \beta^2) \{g(\phi W, Y)X - g(\phi W, X)Y \\ &\quad - \beta^2(g(\phi W, \phi Y)X + g(\phi W, \phi X)Y)\}\eta(Z) \\ &\quad + (\beta g(\phi W, \phi Z) - \alpha g(\phi W, Z))(\eta(X)Y - \eta(Y)X) \\ &\quad + \alpha^2(g(X, Z)\eta(Y) - g(Y, Z)\eta(X))(-\alpha\phi W + \beta(W - \eta(W)\xi)) \\ &\quad - \alpha^2[-\alpha(g(Y, Z)g(\phi W, X) + g(X, Z)g(\phi W, Y)) \\ &\quad + \beta(g(Y, Z)g(\phi W, \phi X) + g(X, Z)g(\phi W, \phi Y))]\xi \\ &\quad + \beta^2 \{[-\alpha(g(W, \phi Z)\eta(Y) + g(W, \phi Y)\eta(Z)) \\ &\quad - \beta(g(\phi W, \phi Z)\eta(Y) + g(\phi W, \phi Y)\eta(Z))\}X \\ &\quad + \{\alpha(g(W, \phi Z)\eta(X) + g(W, \phi X)\eta(Z)) \\ &\quad - \beta(g(\phi W, \phi Z)\eta(X) + g(\phi W, \phi X)\eta(Z))\}Y]. \end{aligned}$$

Using (6.4) in (6.3) we have

$$\begin{aligned}
 (\tilde{\nabla}_W \tilde{R})(X, Y)Z &= (\nabla_W R)(X, Y)Z \\
 &+ \alpha^3 \{g(X, Y)g(\phi Y, Z) - g(W, Y)g(\phi X, Z)\} \xi \\
 &+ \{g(\phi X, Z)\eta(Y) - g(\phi Y, Z)\eta(X)\} W \\
 &+ \alpha^2 \beta \{g(\phi W, X)g(\phi Y, Z) - g(\phi W, Y)g(\phi X, Z)\} \xi \\
 &+ \{g(\phi X, Z)\eta(Y) - g(\phi Y, Z)\eta(X)\} \phi W \\
 &+ (\alpha^2 - \beta^2) \{ \alpha(g(\phi W, Y)X - g(\phi W, X)Y) \\
 &- \beta^2(g(\phi W, \phi Y)X + g(\phi W, \phi X)Y) \} \eta(Z) \\
 &+ (\beta g(\phi W, \phi Z) - \alpha g(\phi W, Z))(\eta(X)Y - \eta(Y)X) \\
 &+ \alpha^2(g(X, Z)\eta(Y) - g(Y, Z)\eta(X))(-\alpha \phi W + \beta(W - \eta(W)\xi)) \\
 &- \alpha^2[-\alpha(g(Y, Z)g(\phi W, X) + g(X, Z)g(\phi W, Y)) \\
 &+ \beta(g(Y, Z)g(\phi W, \phi X) + g(X, Z)g(\phi W, \phi Y))] \xi \\
 &+ \beta^2 \{ \{-\alpha(g(W, \phi Z)\eta(Y) + g(W, \phi Y)\eta(Z)) \\
 &- \beta(g(\phi W, \phi Z)\eta(Y) + g(\phi W, \phi Y)\eta(Z))\} X \\
 &+ \{ \alpha(g(W, \phi Z)\eta(X) + g(W, \phi X)\eta(Z)) \\
 &- \beta(g(\phi W, \phi Z)\eta(X) + g(\phi W, \phi X)\eta(Z)) \} Y \\
 &+ \eta(X)\tilde{R}(\nabla_W \xi, Y)Z + (\nabla_W \eta)(X)\tilde{R}(\xi, Y)Z \\
 &+ \eta(Y)\tilde{R}(X, \nabla_W \xi)Z + (\nabla_W \eta)(Y)\tilde{R}(X, \xi)Z \\
 &+ \eta(Z)\tilde{R}(X, Y)\nabla_W Z + (\nabla_W \eta)(Z)\tilde{R}(X, Y)\xi.
 \end{aligned}
 \tag{6.5}$$

Now applying ϕ^2 on both sides of (6.5) and taking X, Y, Z, W are orthogonal to ξ and using (2.1), (2.3) we get from above equation

$$\phi^2(\tilde{\nabla}_W \tilde{R})(X, Y)Z = \phi^2(\nabla_W R)(X, Y)Z.
 \tag{6.6}$$

Hence we can state the following:

Theorem 6.1. A three-dimensional trans-Sasakian manifold is locally ϕ -symmetry with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ if and only if the manifold is also locally ϕ -symmetry with respect to the Levi-Civita connection ∇ provided α, β are constants.

U. C. De and Avijit Sarkar [7] have proved that a trans-Sasakian manifold is locally ϕ -symmetry if and only if the scalar curvature is constant provided α, β are constants.

In view of above result we can state the following:

Theorem 6.2. A three-dimensional trans-Sasakian manifold is locally ϕ -symmetric with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ if and only if the scalar curvature is constant, provided α, β are constants.

7. Weyl conformally flat trans-Sasakian manifold with respect to Schouten-van Kampen connection

The Weyl conformal curvature tensor \tilde{C} of type (1,3) of M , an n -dimensional trans-Sasakian manifolds with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ is given by [23]

$$(7.1) \quad \begin{aligned} \tilde{C}(X, Y)Z &= \tilde{R}(X, Y)Z - \frac{1}{n-2}[\tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y + g(Y, Z)\tilde{Q}X \\ &\quad - g(X, Z)\tilde{Q}Y] + \frac{\tilde{r}}{(n-1)(n-2)}[g(Y, Z)X - g(X, Z)Y], \end{aligned}$$

where \tilde{Q} is the Ricci operator with respect to the Schouten-van Kampen connection.

Let us consider that a three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection is Weyl conformally flat, that is $\tilde{C} = 0$. Then from (7.1), we get

$$(7.2) \quad \begin{aligned} \tilde{R}(X, Y)Z &= [\tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y + g(Y, Z)\tilde{Q}X \\ &\quad - g(X, Z)\tilde{Q}Y] - \frac{\tilde{r}}{2}[g(Y, Z)X - g(X, Z)Y]. \end{aligned}$$

Let us take inner product of the equation (7.2) with W . Then we get

$$(7.3) \quad \begin{aligned} g(\tilde{R}(X, Y)Z, W) &= [\tilde{S}(Y, Z)g(X, W) - \tilde{S}(X, Z)g(Y, W) + g(Y, Z)g(\tilde{Q}X, W) \\ &\quad - g(X, Z)g(\tilde{Q}Y, W)] - \frac{\tilde{r}}{2}[g(Y, Z)g(X, W) - g(X, Z)g(Y, W)]. \end{aligned}$$

Using (2.1), (2.3), (3.5)-(3.8), we get

$$(7.4) \quad \begin{aligned} g(\tilde{R}(X, Y)Z, W) &= [S(Y, Z)g(X, W) - S(X, Z)g(Y, W) + g(Y, Z)g(QX, W) \\ &\quad - g(X, Z)g(QY, W)] - \frac{r - 2\alpha^2}{2}[g(Y, Z)g(X, W) \\ &\quad - g(X, Z)g(Y, W)] \\ &\quad - \alpha^2[g(\phi Y, Z)g(\phi X, W) - g(\phi X, Z)g(\phi Y, W) \\ &\quad - g(Y, W)\eta(X)\eta(Z) + g(X, W)\eta(Y)\eta(Z) \\ &\quad + g(Y, Z)\eta(X)\eta(W) - g(X, Z)\eta(Y)\eta(W)]. \end{aligned}$$

Putting $X = W = \xi$ in (7.4) and using (2.1) and (2.3), we get

$$(7.6) \quad \begin{aligned} g(\tilde{R}(\xi, Y)Z, \xi) &= [S(Y, Z) - S(\xi, Z)\eta(Y) + g(Y, Z)S(\xi, \xi) \\ &\quad - \eta(Z)S(Y, \xi)] - \frac{r}{2}[g(Y, Z) - \eta(Z)\eta(Y)], \end{aligned}$$

where $g(QY, Z) = S(Y, Z)$.

Now, using (2.13) and (2.16), we get

$$(7.7) \quad S(Y, Z) = \frac{r}{2}g(Y, Z) + [6(\alpha^2 - \beta^2) - \frac{r}{2}]\eta(Y)\eta(Z).$$

Therefore

$$S(Y, Z) = ag(Y, Z) + b\eta(Y)\eta(Z),$$

where $a = \frac{r}{2}$ and $b = [6(\alpha^2 - \beta^2) - \frac{r}{2}]$.

This shows that the manifold M is an η -Einstein manifold.

Thus we can state the following:

Theorem 7.1. A three-dimensional Weyl conformally flat trans-Sasakian manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ is an η -Einstein manifold provided α, β are constants with $\alpha \neq \beta$.

8. Example of a three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen Connection

In this section, we wanted to construct an example of a three-dimensional trans-Sasakian manifold with respect to Schouten-van Kampen connection.

We have considered the three-dimensional manifold $M = \{(x, y, z) \in R^3, z \neq 0\}$, where (x, y, z) are the standard coordinates in R^3 . The vector fields

$$e_1 = e^{-z}(\frac{\partial}{\partial x} + \frac{\partial}{\partial y}), \quad e_2 = e^{-z}(-\frac{\partial}{\partial x} + \frac{\partial}{\partial y}), \quad e_3 = \frac{\partial}{\partial z},$$

are linearly independent at each point of M . Let g be the Riemannian metric defined by

$$g(e_1, e_3) = g(e_2, e_3) = g(e_1, e_2) = 0, \quad g(e_1, e_1) = g(e_2, e_2) = g(e_3, e_3) = 1.$$

Let η be the 1-form defined by $\eta(Z) = g(Z, e_3)$ for any $Z \in \chi(M)$. Let ϕ be the (1,1) tensor field defined by $\phi(e_1) = e_2, \phi(e_2) = -e_1, \phi(e_3) = 0$. Then using the linearity of ϕ and g we have

$$\eta(e_3) = 1, \quad \phi^2 Z = -Z + \eta(Z)e_3, \quad g(\phi Z, \phi W) = g(Z, W) - \eta(Z)\eta(W),$$

for any $Z, W \in \chi(M)$. Thus for $e_3 = \xi, (\phi, \xi, \eta, g)$ defines an almost contact metric structure on M . Now, by direct computations we obtain

$$[e_1, e_2] = 0, \quad [e_2, e_3] = e_2, \quad [e_1, e_3] = e_1.$$

The Riemannian connection ∇ of the metric tensor g is given by the Koszul's formula which is

$$(8.1) \quad \begin{aligned} 2g(\nabla_X Y, Z) &= Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) \\ &- g(X, [Y, Z]) - g(Y, [X, Z]) + g(Z, [X, Y]). \end{aligned}$$

By Koszul formula

$$\begin{aligned} \nabla_{e_1} e_3 &= e_1, & \nabla_{e_1} e_2 &= 0, & \nabla_{e_1} e_1 &= -e_3, \\ \nabla_{e_2} e_3 &= e_2, & \nabla_{e_2} e_2 &= -e_3, & \nabla_{e_2} e_1 &= 0, \\ \nabla_{e_3} e_3 &= 0, & \nabla_{e_3} e_2 &= 0, & \nabla_{e_3} e_1 &= 0. \end{aligned}$$

From above we see that the manifold satisfies (2.6) for $\alpha = 0$, $\beta = 1$, and $e_3 = \xi$. Hence the manifold is a trans-Sasakian manifold of type $(0, 1)$. With the help of the above results it can be verified that

$$\begin{aligned} R(e_1, e_2)e_3 &= 0, & R(e_2, e_3)e_3 &= -e_2, & R(e_1, e_3)e_3 &= -e_1, \\ R(e_1, e_2)e_2 &= -e_1, & R(e_2, e_3)e_2 &= e_3, & R(e_1, e_3)e_2 &= 0, \\ R(e_1, e_2)e_1 &= e_2, & R(e_2, e_3)e_1 &= 0, & R(e_1, e_3)e_1 &= e_3. \end{aligned}$$

Now we consider the Schouten-Van Kampen connection to this example.

Using (3.2) and above result we have

$$\begin{aligned} \tilde{\nabla}_{e_1} e_3 &= (1 - \beta)e_1 + \alpha e_2, & \tilde{\nabla}_{e_1} e_2 &= -\alpha e_3, & \tilde{\nabla}_{e_1} e_1 &= (\beta - 1)e_3, \\ \tilde{\nabla}_{e_2} e_3 &= -\alpha e_1 + (1 - \beta)e_2, & \tilde{\nabla}_{e_2} e_2 &= (\beta - 1)e_3, & \tilde{\nabla}_{e_2} e_1 &= 0, \\ \tilde{\nabla}_{e_3} e_3 &= 0, & \tilde{\nabla}_{e_3} e_2 &= -\beta e_2, & \tilde{\nabla}_{e_3} e_1 &= -\beta e_1. \end{aligned}$$

Using (3.4) we get

$$\begin{aligned} \tilde{R}(e_1, e_2)e_3 &= 0, & \tilde{R}(e_2, e_3)e_3 &= (\beta^2 - \alpha^2 - 1)e_2, \\ \tilde{R}(e_1, e_3)e_3 &= (\beta^2 - \alpha^2 - 1)e_1, & \tilde{R}(e_1, e_2)e_2 &= \alpha^2 e_2 + (\beta^2 + \alpha^2 - 1)e_1, \\ \tilde{R}(e_2, e_3)e_2 &= (-\beta^2 + \alpha^2 + 1)e_3, & \tilde{R}(e_1, e_3)e_2 &= 0, \\ \tilde{R}(e_1, e_2)e_1 &= (1 - \beta^2 - \alpha^2)e_2, & \tilde{R}(e_2, e_3)e_1 &= 0, \\ \tilde{R}(e_1, e_3)e_1 &= (1 + \alpha^2 - \beta^2)e_3. \end{aligned}$$

From the above expressions of the curvature tensor we obtain

$$S(e_1, e_1) = \sum_{i=1}^3 g(R(e_i, e_1)e_1, e_i) = -2.$$

Similarly, we have

$$S(e_2, e_2) = -2 \quad \text{and} \quad S(e_3, e_3) = -2.$$

$$\begin{aligned}\tilde{S}(e_1, e_2) = \tilde{S}(e_2, e_2) = 2(\beta^2 - 1) \quad \tilde{S}(e_3, e_3) = 2(\beta^2 - \alpha^2 - 1). \\ r = -6 \quad \tilde{r} = 6\beta^2 - 2\alpha^2 - 6.\end{aligned}$$

From above we see that $\tilde{r} = 0$ for $\alpha = 0, \beta = 1$. Therefore, the manifold under consideration satisfies the Theorem 5.2. Using (4.1) and above relations, we get

$$P(e_1, e_2)e_3 = P(e_1, e_3)e_3 = P(e_2, e_3)e_3 = 0,$$

$$\tilde{P}(e_1, e_2)e_3 = \tilde{P}(e_1, e_3)e_3 = \tilde{P}(e_2, e_3)e_3 = 0.$$

Therefore, the manifold will be ξ -projectively flat on a three-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection which verifies the Theorem 4.1.

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